

Extracting GPDs from CFFs with NN

QCD AT THE FEMTOSCALE IN THE ERA OF BIG DATA

MARCO ZACCHEDDU – JEFFERSON LAB



Outline

Theory:

- What is a GPD?
- How do we construct a GPD?
- Where do we get them?
- Evolution equations
- How do we get the observable?

GPDs extraction with NN

- NN as pixel generator for Double Distributions
- Layers
- Results

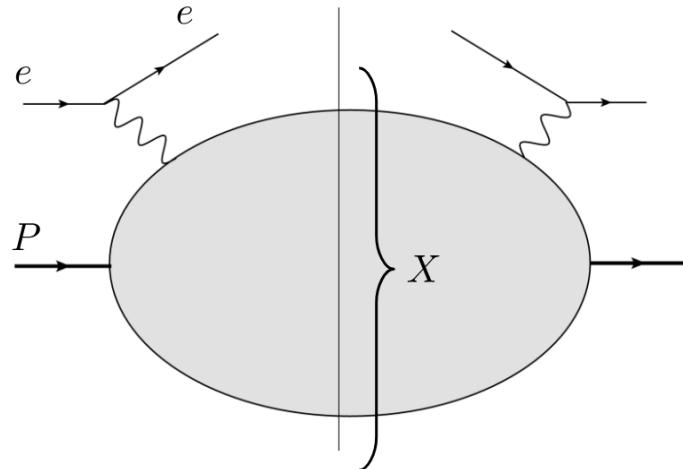
What is a GPD?

GPD : Generalized PDF

PDF : Parton Distribution Function

"Probability" of finding an unpolarized quark with momentum fraction x inside a nucleon

Deep Inelastic Scattering: $eP \rightarrow e X$



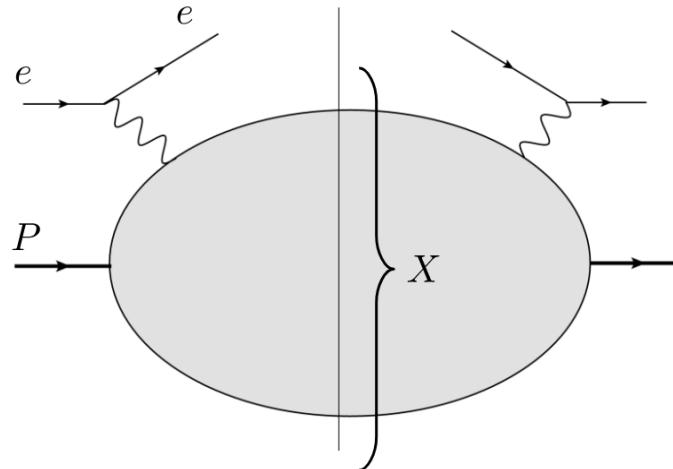
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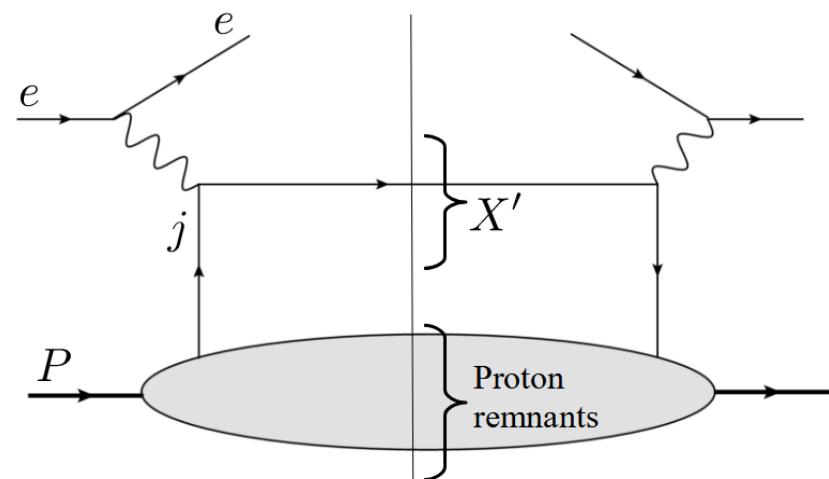
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Factorization



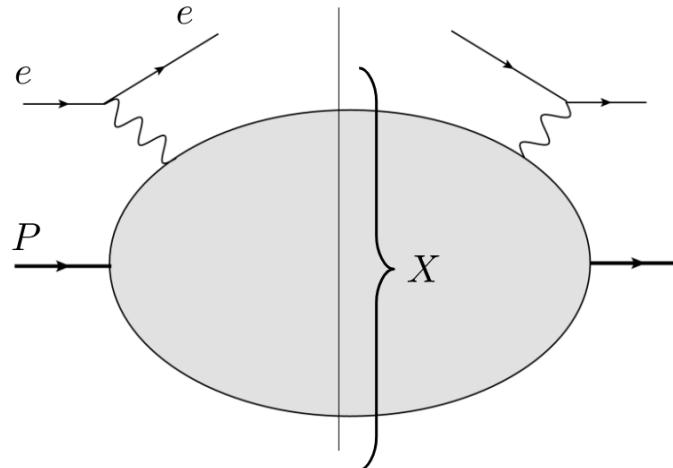
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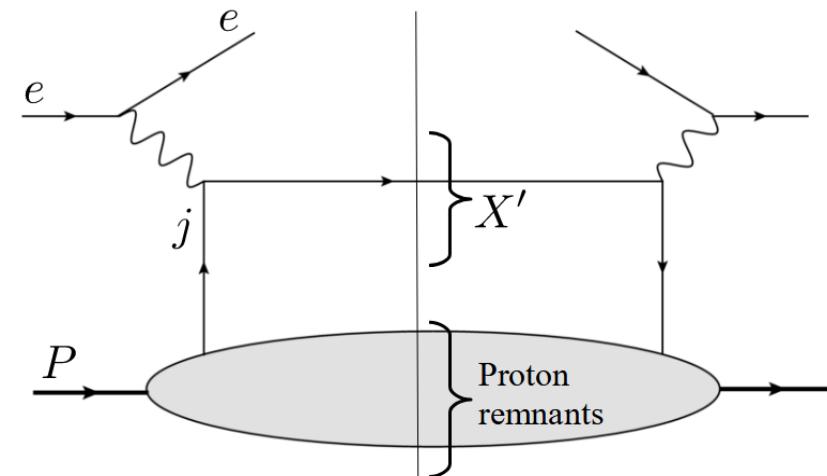
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Factorization



Cross section:

$$\sigma_{eP \rightarrow eX} \simeq \hat{\sigma}_{eq \rightarrow e} \otimes f_{q/P}(x)$$

PDF

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PDF : Parton Distribution Function

Nucleon Polarization

Quark Polarization			
	U	L	T
U	f_1		
L		g_{1L}	
T			h_{1T}

Different PDFs for different parton/nucleon spin configuration

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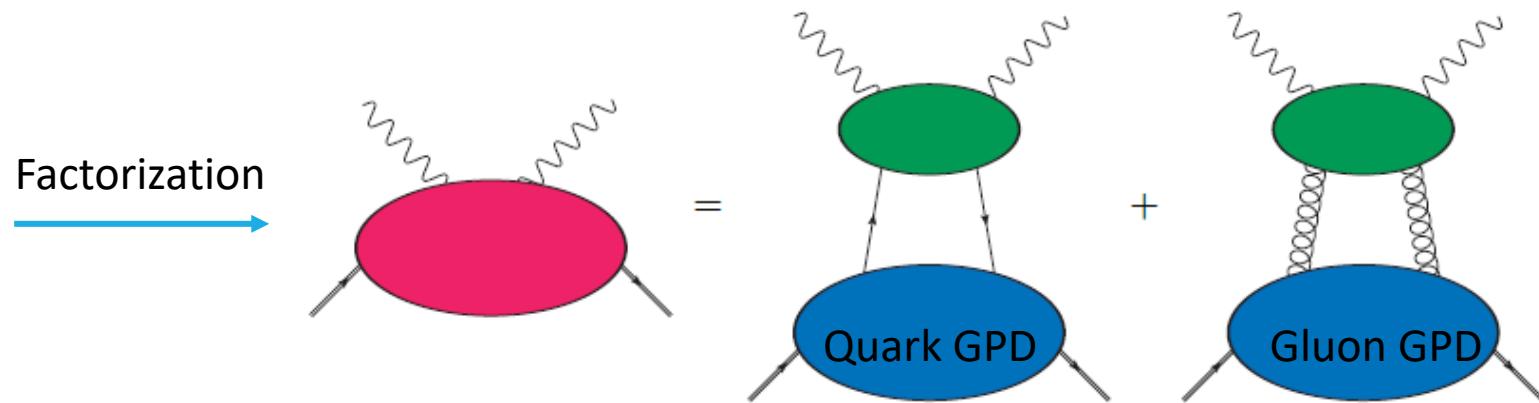
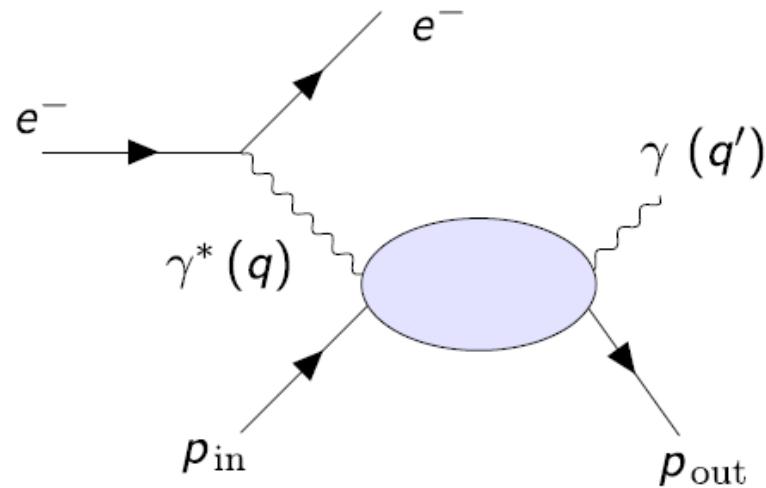
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Different PDFs for different parton/nucleon spin configuration

What is a GPD?

DVCS: Deeply Virtual Compton Scattering

$$e^- P_{in} \rightarrow e^- P_{out} \gamma$$



$$F(x, \xi, t)$$

GPDs depend on 3 variables

Q^2 dependence → Evolution equations

$$\xi = \frac{p^+ - p'^+}{p^+ + p'^+} \text{ Skewness}$$

$$P = \frac{p + p'}{2}, \quad \Delta = p' - p, \quad t = \Delta^2$$

What is a GPD?

$$F^q = \frac{1}{2} \int \frac{dz^-}{2\pi} e^{ixP^+z^-} \langle p' | \bar{q}(-\frac{1}{2}z) \gamma^+ q(\frac{1}{2}z) | p \rangle \Big|_{z^+=0, z=0}$$

$$= \frac{1}{2P^+} \left[H^q(x, \xi, t) \bar{u}(p') \gamma^+ u(p) + E^q(x, \xi, t) \bar{u}(p') \frac{i\sigma^{+\alpha} \Delta_\alpha}{2m} u(p) \right]$$

$$\tilde{F}^q = \frac{1}{2} \int \frac{dz^-}{2\pi} e^{ixP^+z^-} \langle p' | \bar{q}(-\frac{1}{2}z) \gamma^+ \gamma_5 q(\frac{1}{2}z) | p \rangle \Big|_{z^+=0, z=0}$$

$$= \frac{1}{2P^+} \left[\tilde{H}^q(x, \xi, t) \bar{u}(p') \gamma^+ \gamma_5 u(p) + \tilde{E}^q(x, \xi, t) \bar{u}(p') \frac{\gamma_5 \Delta^+}{2m} u(p) \right]$$

Unpolarized GPDs for quarks

Longitudinally polarized GPDs for quarks

Same number of functions for gluons

Polynomiality: the nth-moment are polynomials in ξ of order $n+1$

$$\int_{-1}^1 dx x^n H^q(x, \xi, t) = \sum_{\substack{i=0 \\ \text{even}}}^n (2\xi)^i A_{n+1,i}^q(t) + \text{mod}(n, 2) (2\xi)^{n+1} C_{n+1}^q(t).$$

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How do we construct a GPD?

We can obtain the GPDs integrating Double Distribution

$$H^q(x, \xi, t) = \int d\beta d\alpha \delta(x - \beta - \xi\alpha) f^q(\beta, \alpha, t)$$

$$E^q(x, \xi, t) = \int d\beta d\alpha \delta(x - \beta - \xi\alpha) k^q(\beta, \alpha, t)$$

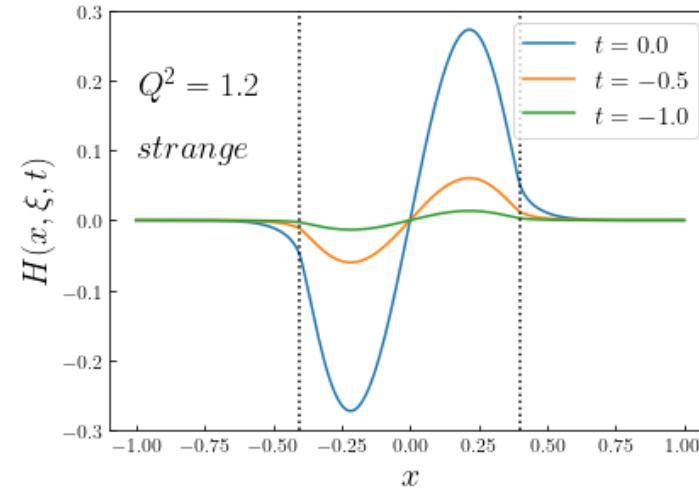
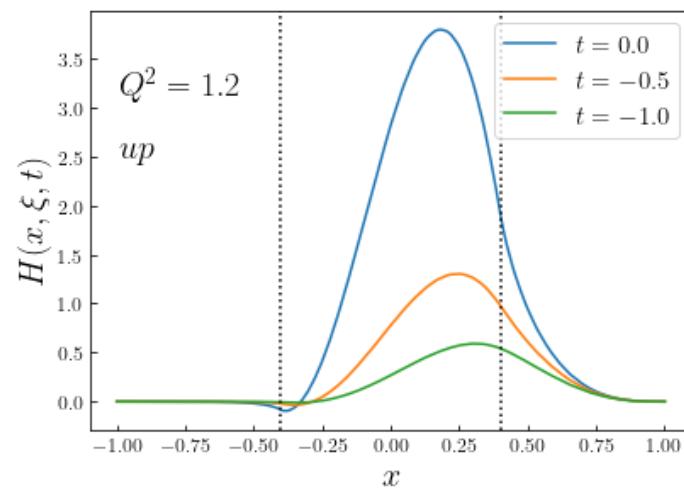
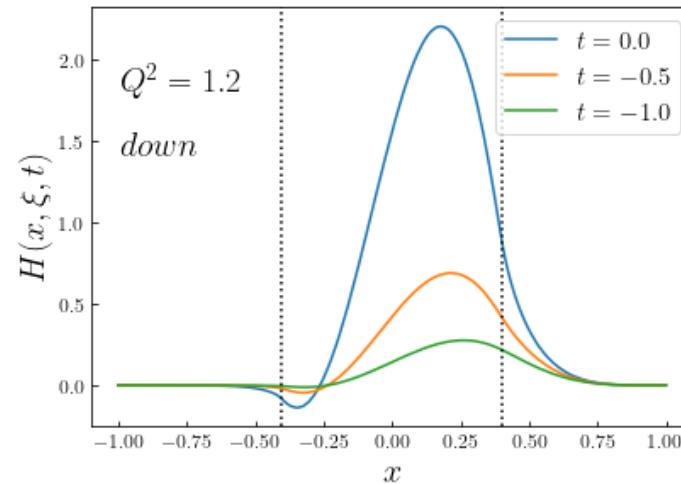
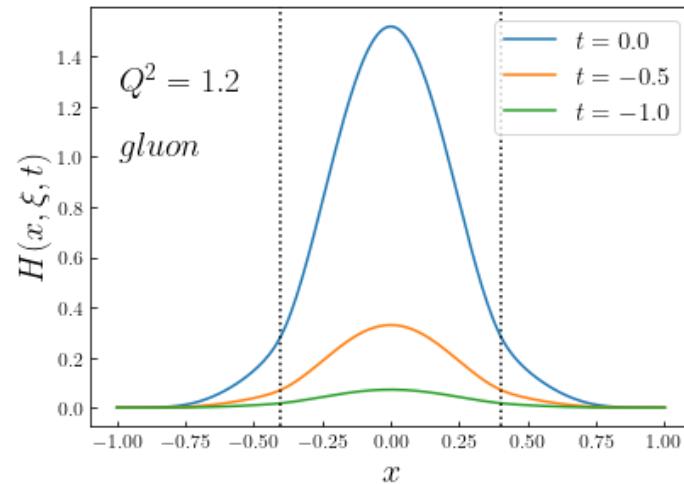
They can be represented by 3D tensors

Properties:

DD generate GPDs which automatically satisfy the polynomiality

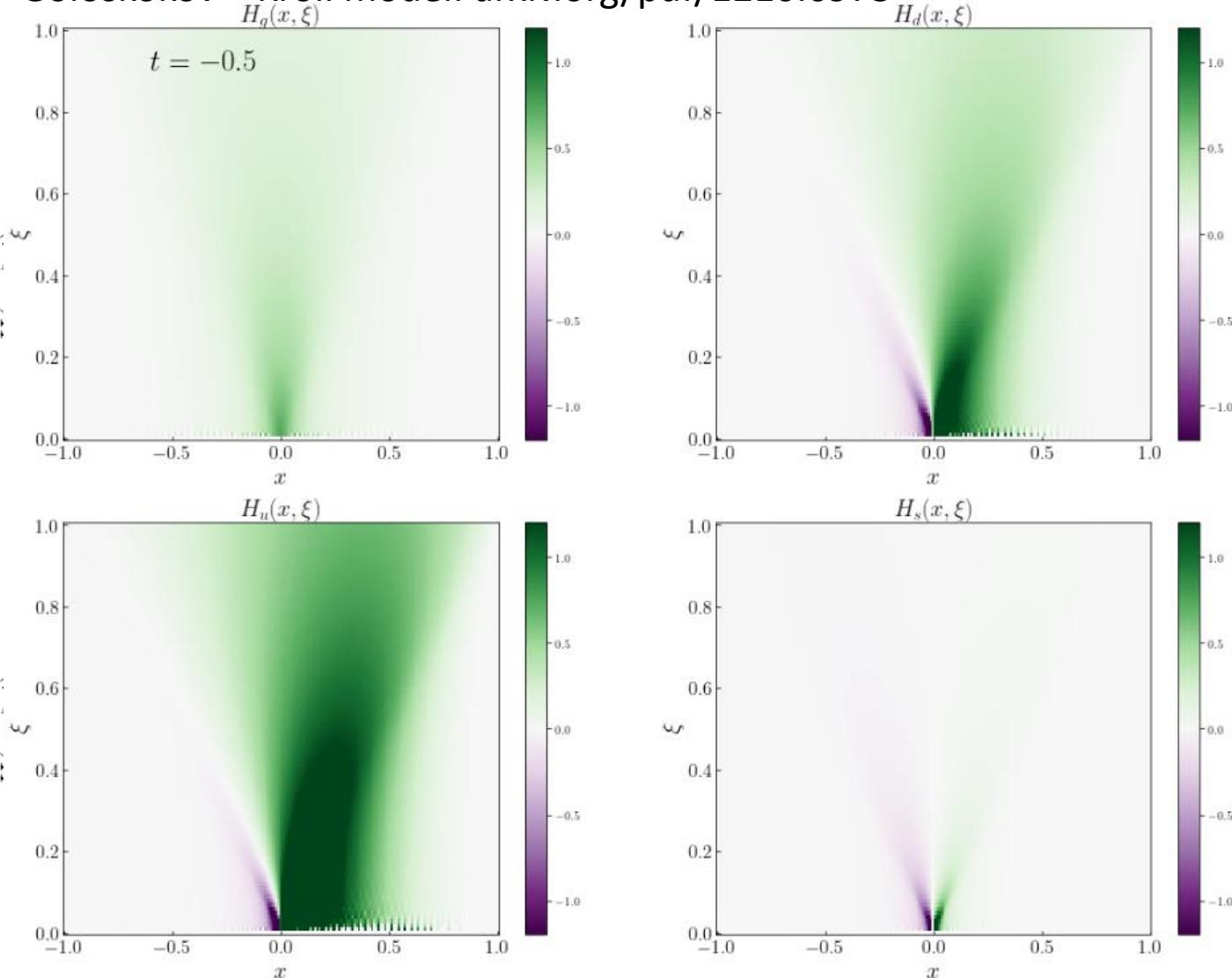
How do we construct a GPD?

Goloskokov – Kroll model: arxiv.org/pdf/1210.6975



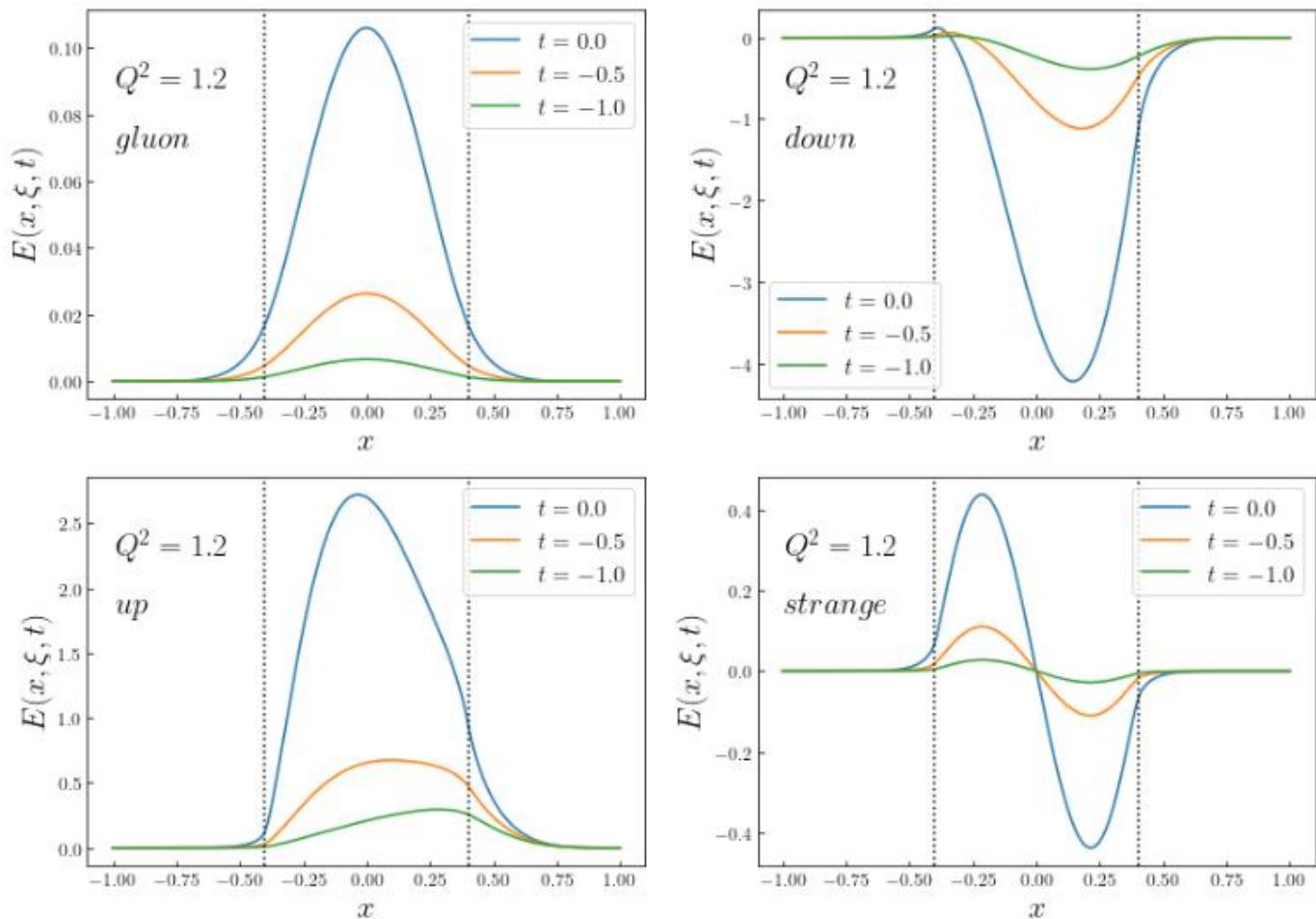
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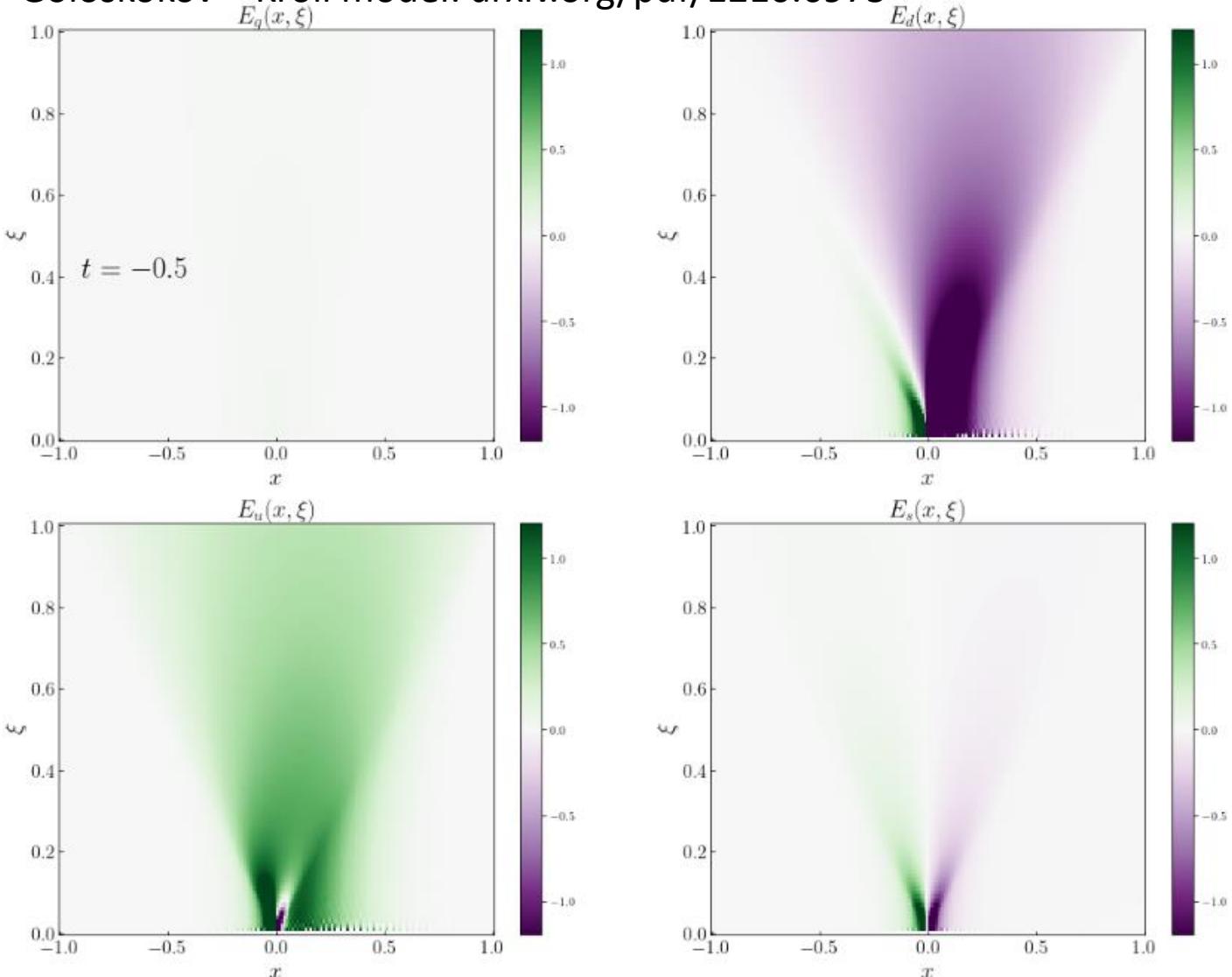
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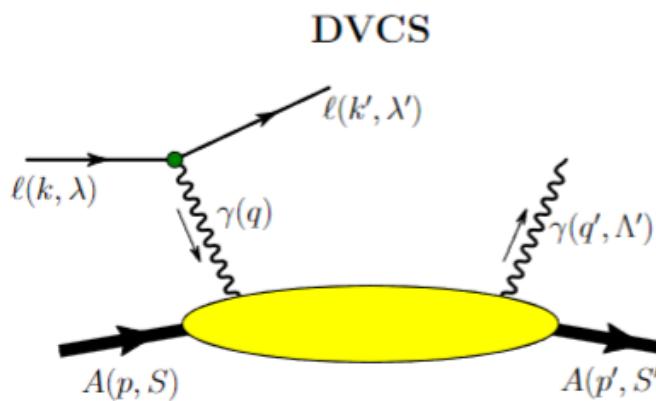
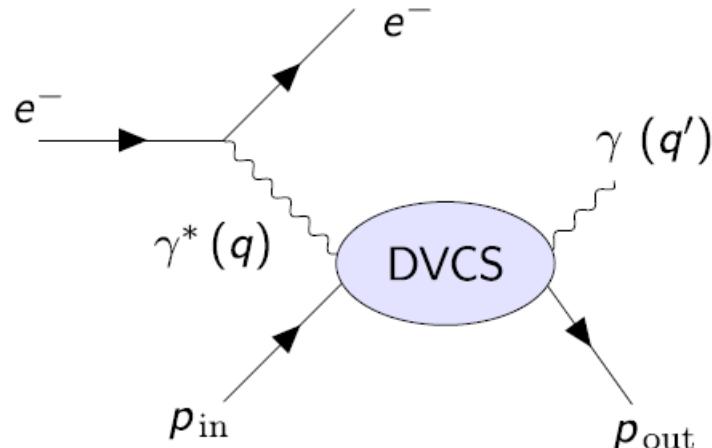
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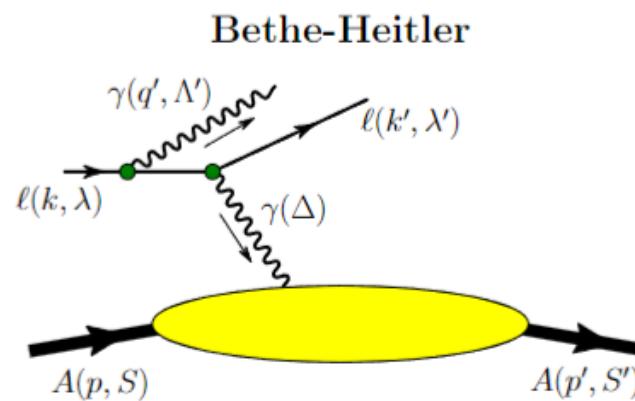
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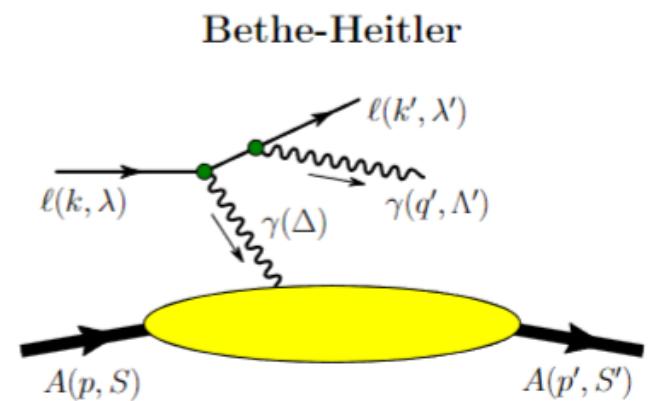
DVCS: Deeply Virtual Compton Scattering



+



+



Interference with

Where do we get them?

The cross section and the asymmetries are written in terms of the following amplitudes

$$|\mathcal{T}_{\text{DVCS}}|^2 = |\mathcal{T}_{\text{DVCS}}|_{\text{UU}}^2 + \lambda |\mathcal{T}_{\text{DVCS}}|_{\text{LU}}^2 + \Lambda \cos \theta \left(|\mathcal{T}_{\text{DVCS}}|_{\text{UL}}^2 + \lambda |\mathcal{T}_{\text{DVCS}}|_{\text{LL}}^2 \right) + \sin \theta \left(|\mathcal{T}_{\text{DVCS}}|_{\text{UT}}^2 + \lambda |\mathcal{T}_{\text{DVCS}}|_{\text{LT}}^2 \right).$$

$$|\mathcal{T}_{\text{BH}}|^2 = |\mathcal{T}_{\text{BH}}|_{\text{UU}}^2 + \lambda |\mathcal{T}_{\text{BH}}|_{\text{LU}}^2 + \Lambda \cos \theta \left(|\mathcal{T}_{\text{BH}}|_{\text{UL}}^2 + \lambda |\mathcal{T}_{\text{BH}}|_{\text{LL}}^2 \right) + \sin \theta \left(|\mathcal{T}_{\text{BH}}|_{\text{UT}}^2 + \lambda |\mathcal{T}_{\text{BH}}|_{\text{LT}}^2 \right)$$

$$\mathcal{I} = \mathcal{I}_{\text{UU}} + \lambda \mathcal{I}_{\text{LU}} + \Lambda \cos \theta (\mathcal{I}_{\text{UL}} + \lambda \mathcal{I}_{\text{LL}}) + \sin \theta (\mathcal{I}_{\text{UT}} + \lambda \mathcal{I}_{\text{LT}})$$

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$$\mathcal{I} = \mathcal{I}_{UU} + \lambda I_{LU} + \Lambda \cos \theta (I_{UL} + \lambda I_{LL}) + \sin \theta (I_{UT} + \lambda I_{LT})$$

Only terms depending on GPDs through CFFs

Where do we get them?

CFFs: Compton Form Factors

$$\{\mathcal{H}, \mathcal{E}\}(\xi, t; Q^2) = \int_{-1}^{+1} dx C^{(-)}(x, \xi) \{H, E\}(x, \xi, t; Q^2)$$

$$\{\tilde{\mathcal{H}}, \tilde{\mathcal{E}}\}(\xi, t; Q^2) = \int_{-1}^{+1} dx C^{(+)}(x, \xi) \{\tilde{H}, \tilde{E}\}(x, \xi, t; Q^2)$$

$$C^{(\pm)}(x, \xi) = e_q^2 \left(\frac{1}{\xi - x - i\epsilon} \pm \frac{1}{\xi + x - i\epsilon} \right)$$

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$$\begin{aligned} \text{Re } \{\mathcal{H}, \mathcal{E}\}(\xi, t; Q^2) &= e_q^2 \left\{ \int_{-1}^{+1} dx \frac{\{H, E\}^+(x, \xi, t; Q^2) - \{H, E\}^+(\xi, \xi, t; Q^2)}{\xi - x} \right. \\ &\quad \left. + \{H, E\}^+(\xi, \xi, t; Q^2) \log \left(\frac{1 - \xi}{1 + \xi} \right) \right\} \end{aligned}$$

$$\text{Im } \{\mathcal{H}, \mathcal{E}\}(\xi, t; Q^2) = e_q^2 \pi \{H, E\}^+(\xi, \xi, t; Q^2)$$

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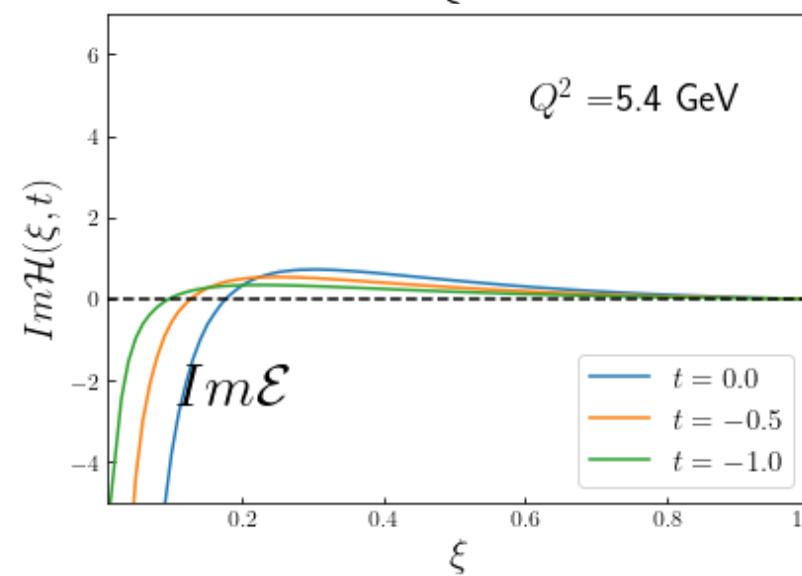
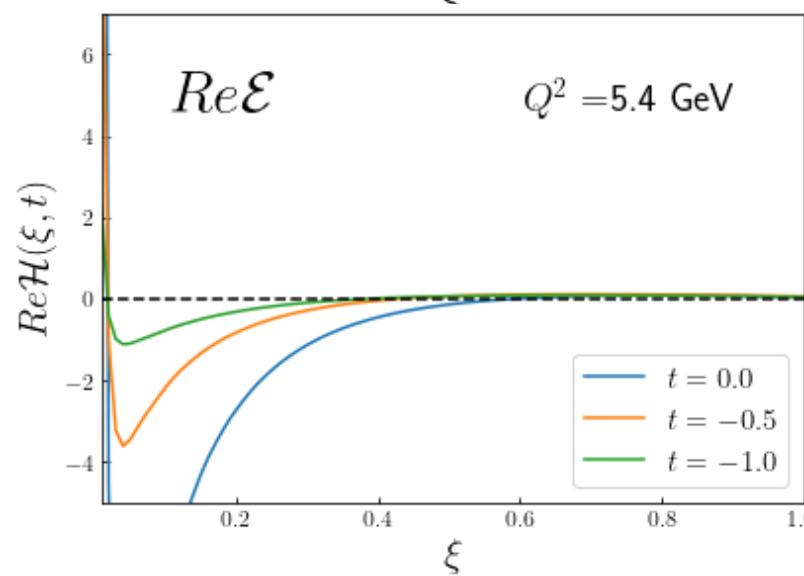
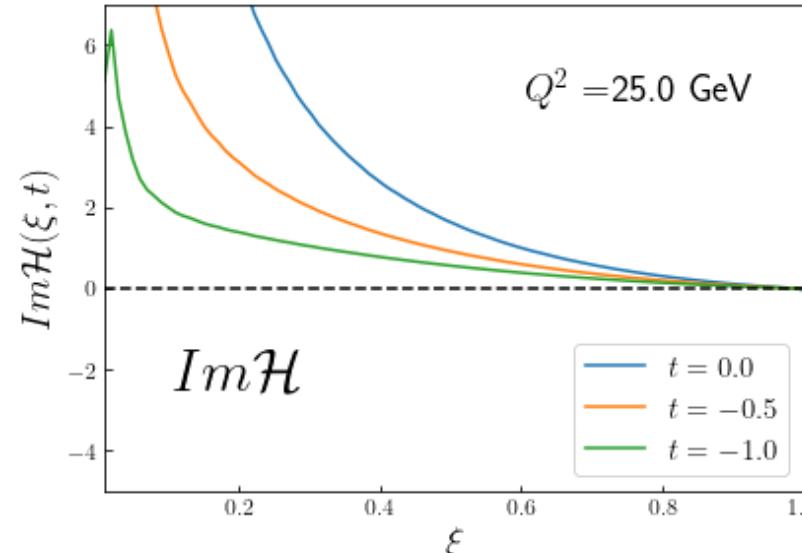
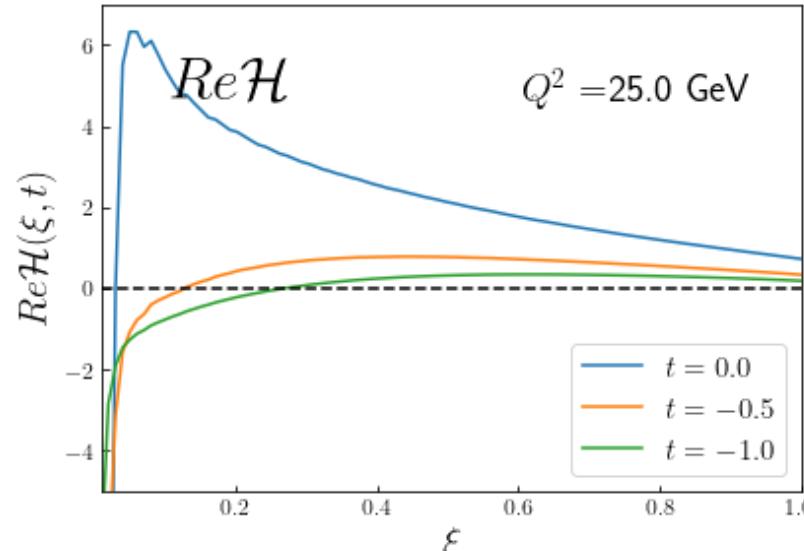
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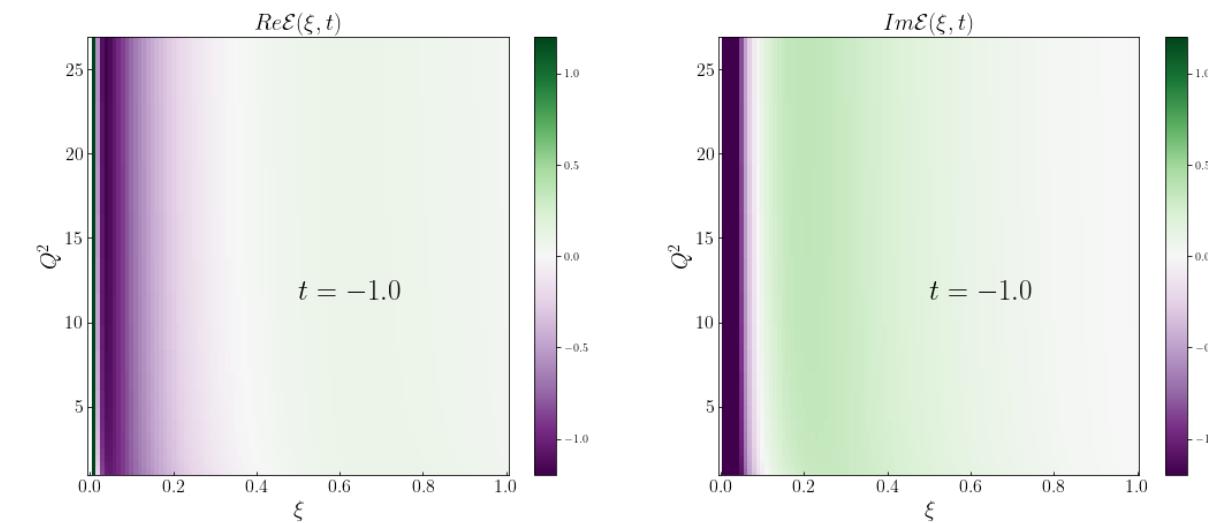
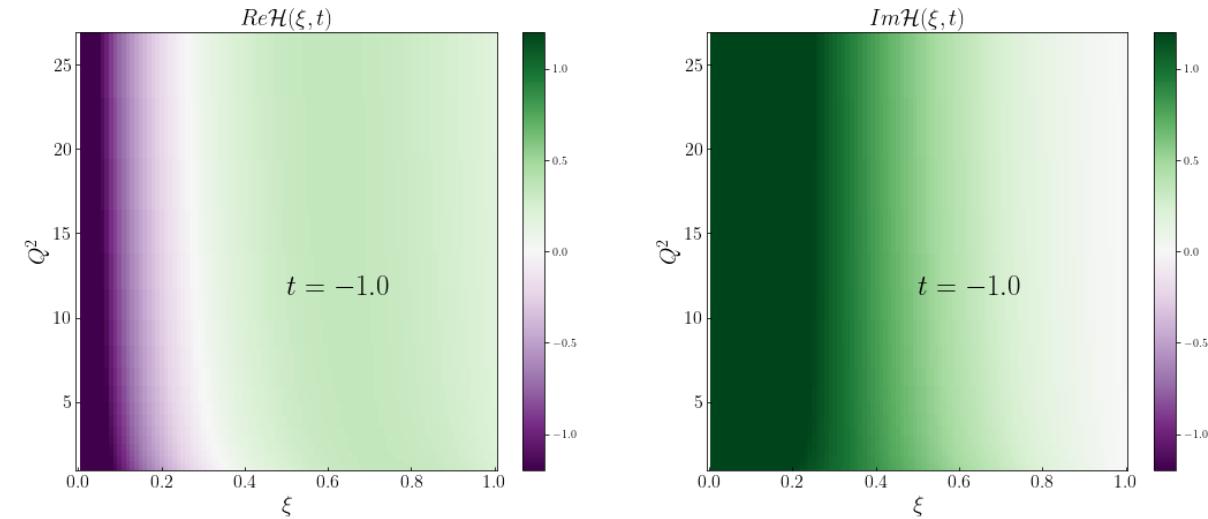
$$Im \{\mathcal{H}, \mathcal{E}\}(\xi, t; Q^2) = e_q^2 \pi \{H, E\}^+(\xi, \xi, t; Q^2)$$

$$\{\tilde{\mathcal{H}}, \tilde{\mathcal{E}}\}(\xi, t; Q^2) = Re \{\tilde{\mathcal{H}}, \tilde{\mathcal{E}}\}(\xi, t; Q^2) + i Im \{\tilde{\mathcal{H}}, \tilde{\mathcal{E}}\}(\xi, t; Q^2)$$

Where do we get them?



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CFFs: Compton Form Factors

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Inversion Problem: CFFs depend only on ξ . We cannot recover the x dependence of the GPDs

Q^2 dependence → Evolution equations

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Evolution equations

Non-Singlet evolution equation:

$$\mu^2 \frac{d}{d\mu^2} H^{q(-)}(x, \xi, t) = \int_{-1}^1 dx' \frac{1}{|\xi|} V_{\text{NS}}\left(\frac{x}{\xi}, \frac{x'}{\xi}\right) H^{q(-)}(x', \xi, t)$$

Solve evolution equation
with Runge-Kutta 4

Singlet evolution equation:

$$H^{q(-)} \rightarrow \begin{pmatrix} (2n_f)^{-1} \sum_q^{n_f} H^{q(+)} \\ H^g \end{pmatrix}$$

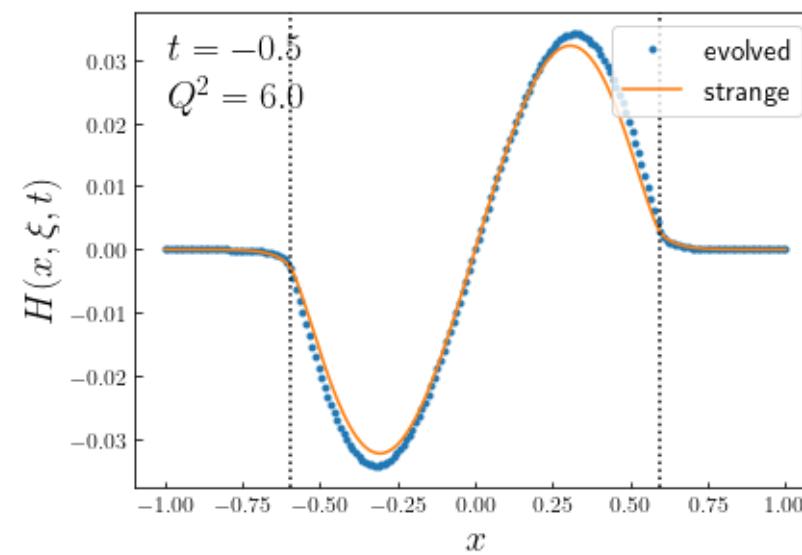
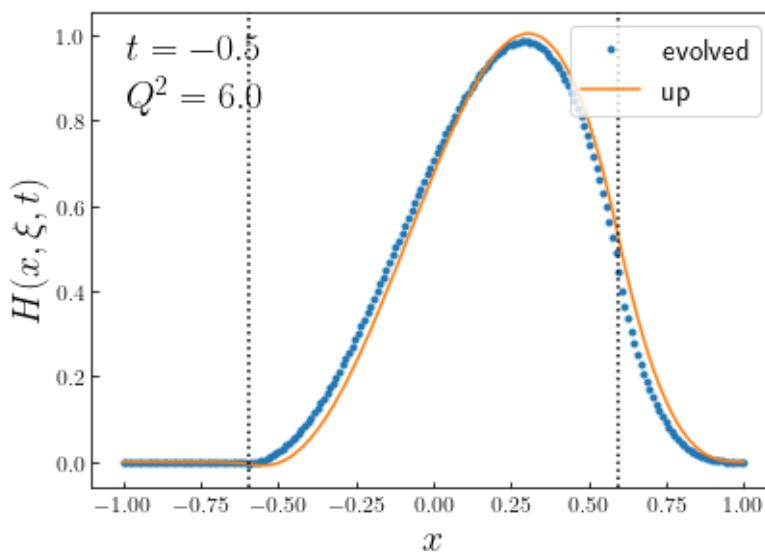
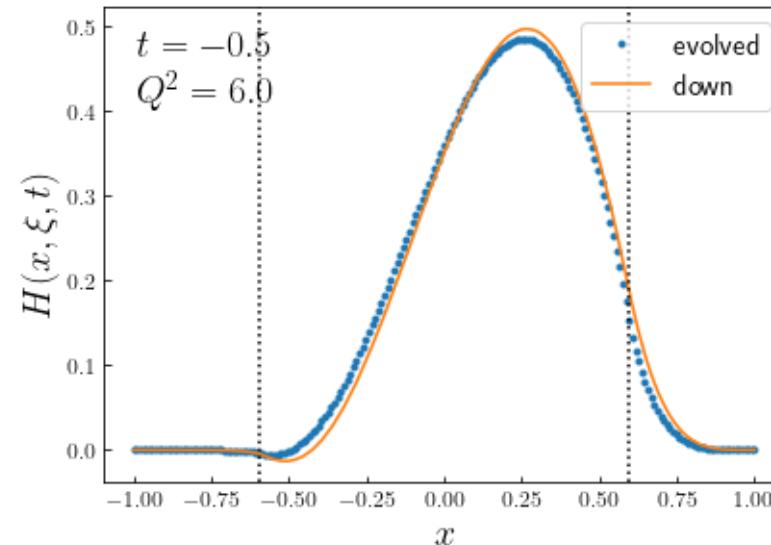
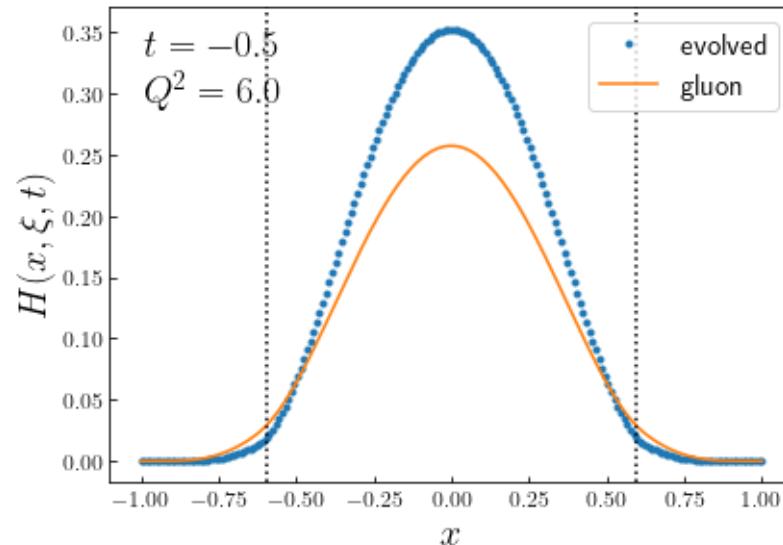
$$V_{\text{NS}}\left(\frac{x}{\xi}, \frac{x'}{\xi}\right) \rightarrow \begin{pmatrix} V^{qq}\left(\frac{x}{\xi}, \frac{x'}{\xi}\right) & \frac{1}{\xi} V^{qg}\left(\frac{x}{\xi}, \frac{x'}{\xi}\right) \\ \xi V^{gq}\left(\frac{x}{\xi}, \frac{x'}{\xi}\right) & V^{gg}\left(\frac{x}{\xi}, \frac{x'}{\xi}\right) \end{pmatrix}$$

Evolution equations

$$\mu^2 \frac{d}{d\mu^2} H^{q(-)}(x, \xi, t) = \int_{-1}^1 dx' \frac{1}{|\xi|} V_{\text{NS}}\left(\frac{x}{\xi}, \frac{x'}{\xi}\right) H^{q(-)}(x', \xi, t)$$

$$\begin{aligned} \frac{d H(x, \xi, t)}{d \ln \mu^2} &= \int_{-1}^1 dy K(x, y, \xi) H(y, \xi, t) \\ &= \sum_g w_g K(x_j, \eta_g, \xi_n) H(\eta_g, \xi_n, t_t) && \xrightarrow{\hspace{1cm}} \text{Gaussian quadrature} \\ &= \sum_g w_g K(x_j, \eta_g, \xi_n) L(\eta_g, x_l) H(x_l, \xi_n, t_l) && \xrightarrow{\hspace{1cm}} \text{Interpolation} \\ &= \sum_g w_g K_{jgn} L_{jgl} H_{lnt} \\ &= M_{jln} H_{lnt} && \xrightarrow{\hspace{1cm}} \text{Matrix multiplication} \end{aligned}$$

Evolution equations



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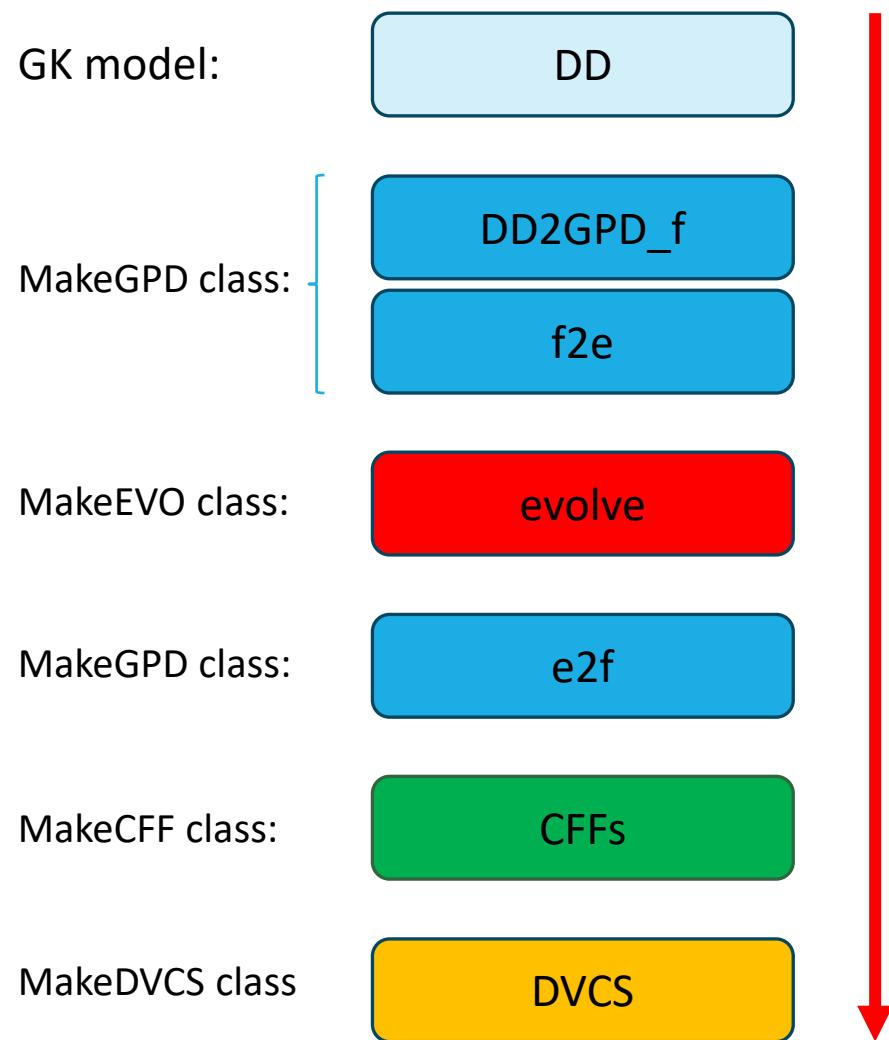
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How do we get the observables?



How do we get the observables?

GK model:

DD

MakeGPD class:

DD2GPD_f

f2e

MakeEVO class:

evolve

MakeGPD class:

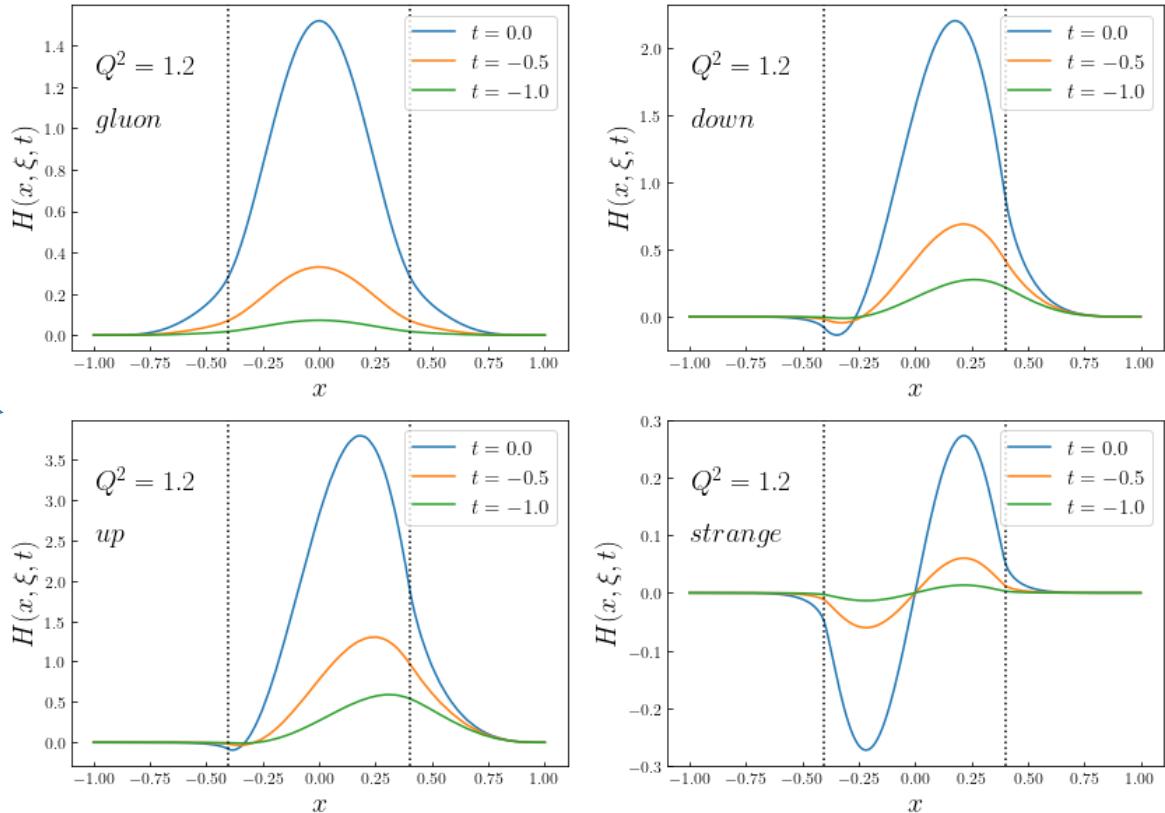
e2f

MakeCFF class:

CFFs

MakeDVCS class

DVCS



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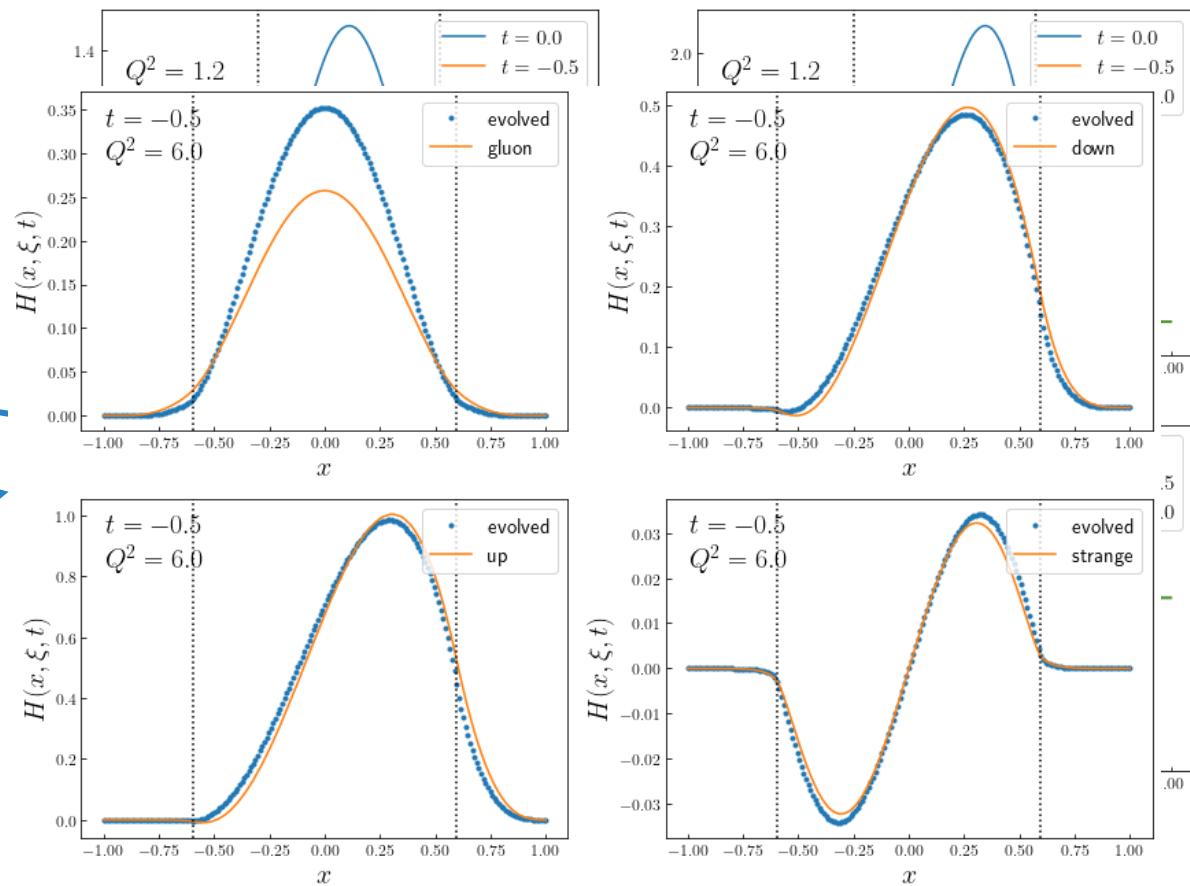
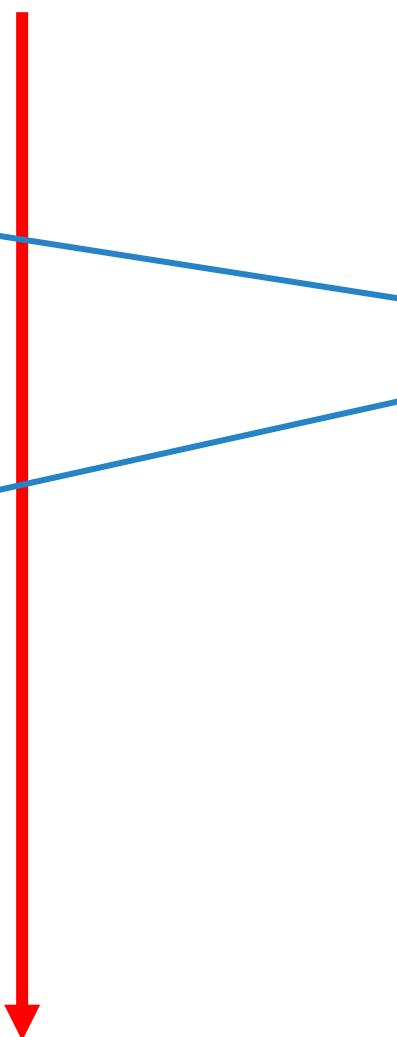
e2f

MakeCFF class:

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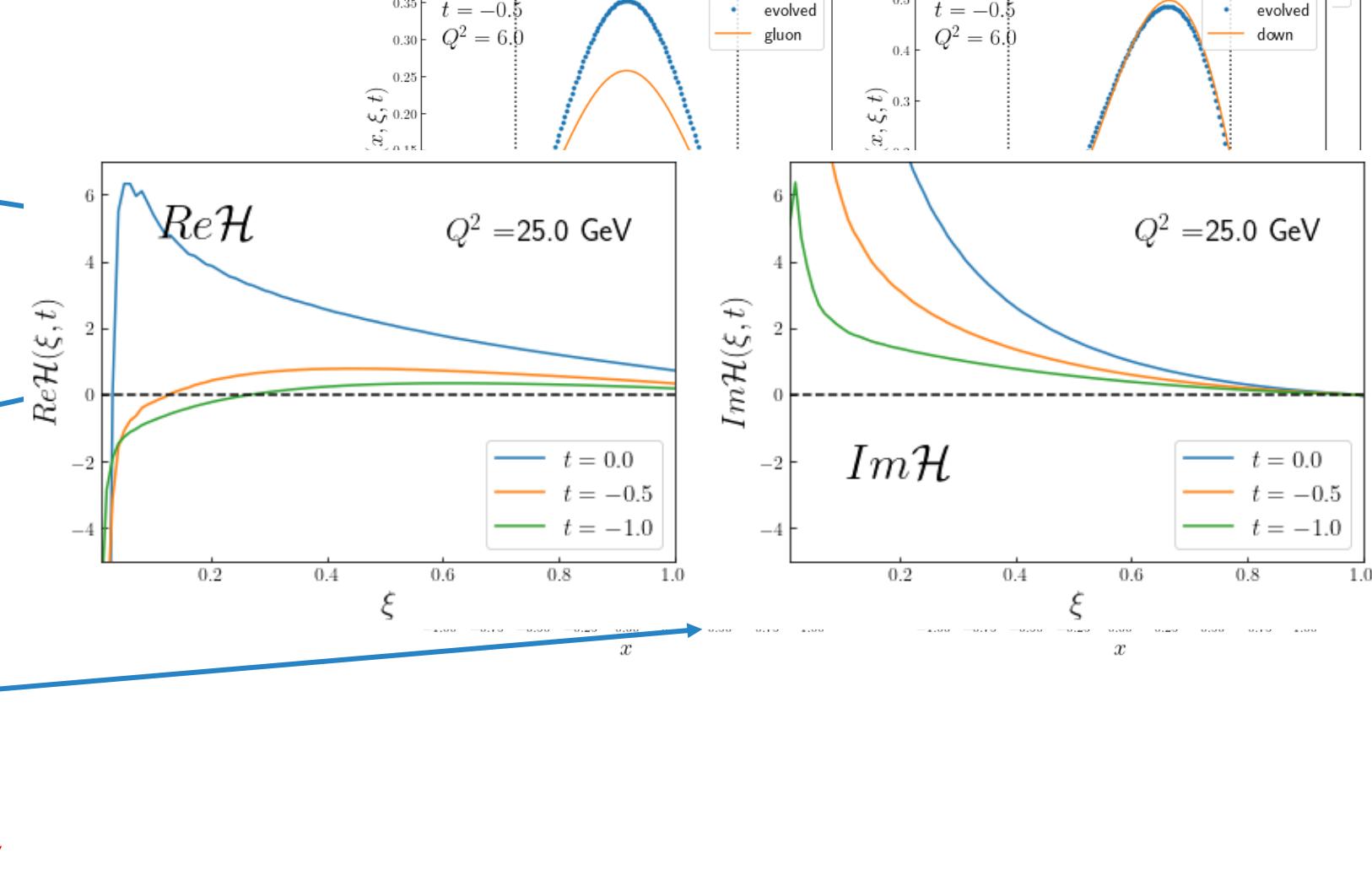
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MakeCFF class:

CFFs

MakeDVCS class

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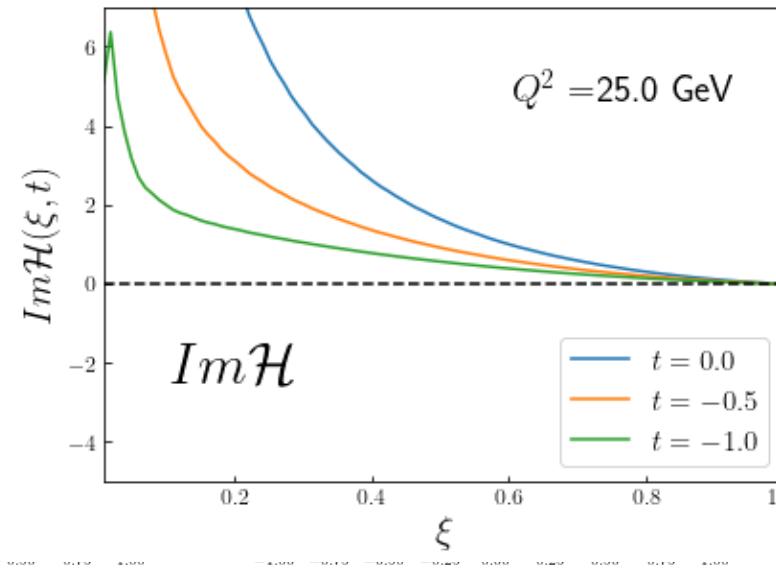
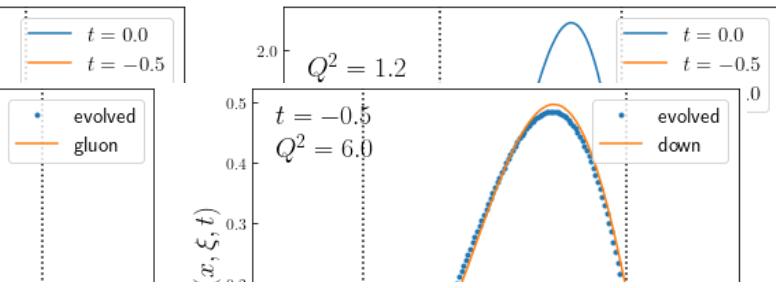
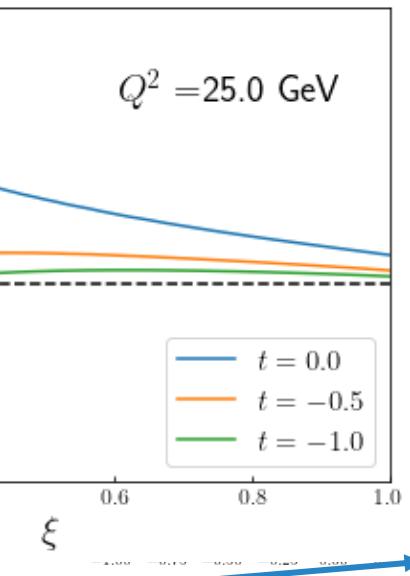
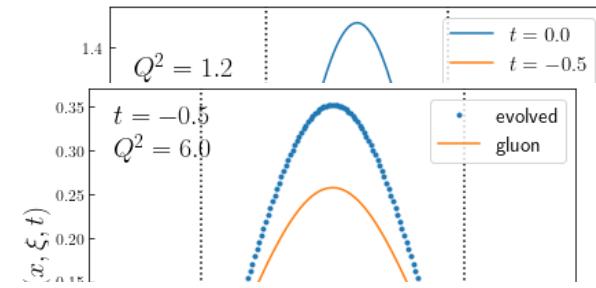
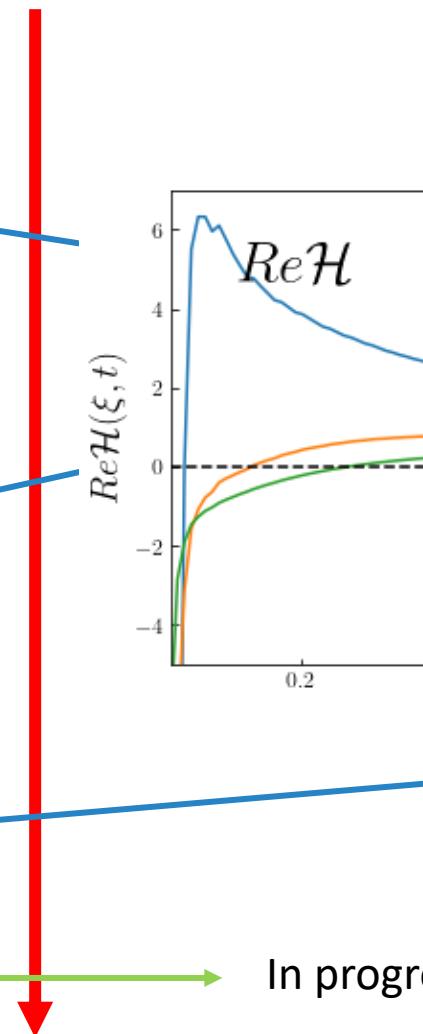
e2f

MakeCFF class:

CFFs

MakeDVCS class

DVCS



How do we get the observables?

GK model:

DD

MakeGPD class:

DD2GPD_f
f2e

MakeEVO class:

evolve

MakeGPD class:

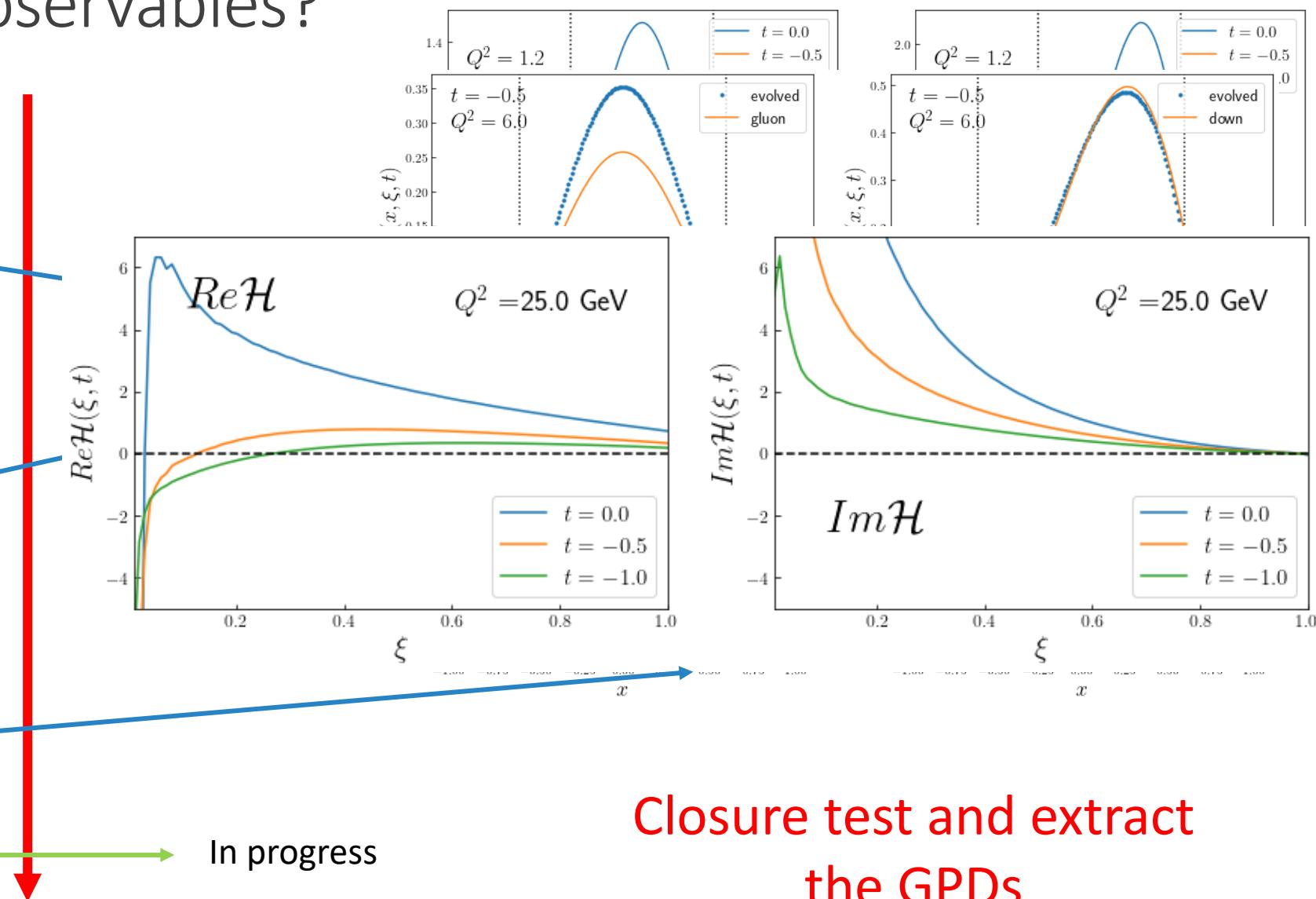
e2f

MakeCFF class:

CFFs

MakeDVCS class

DVCS



Closure test and extract
the GPDs

Outline

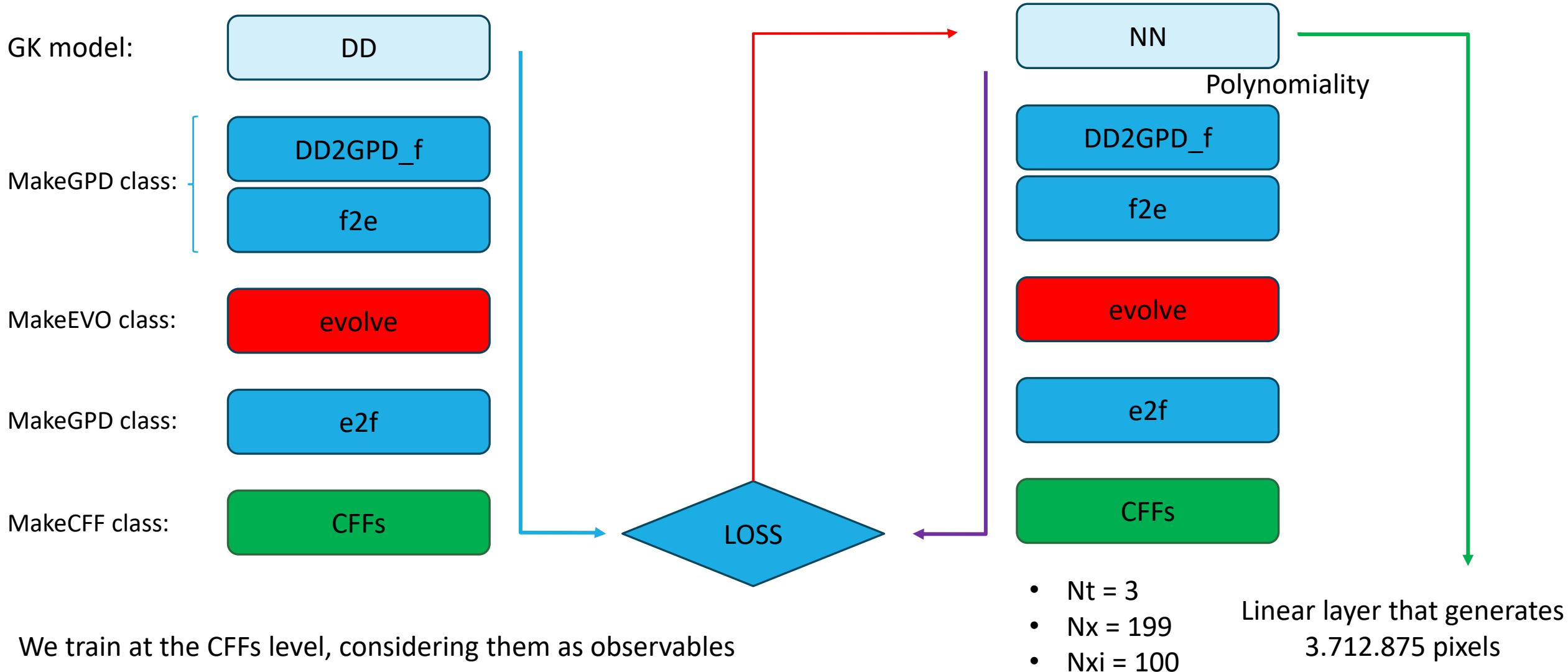
Theory:

- What is a GPD?
- How do we construct a GPD?
- Where do we get them?
- Evolution equations
- How do we get the observable?

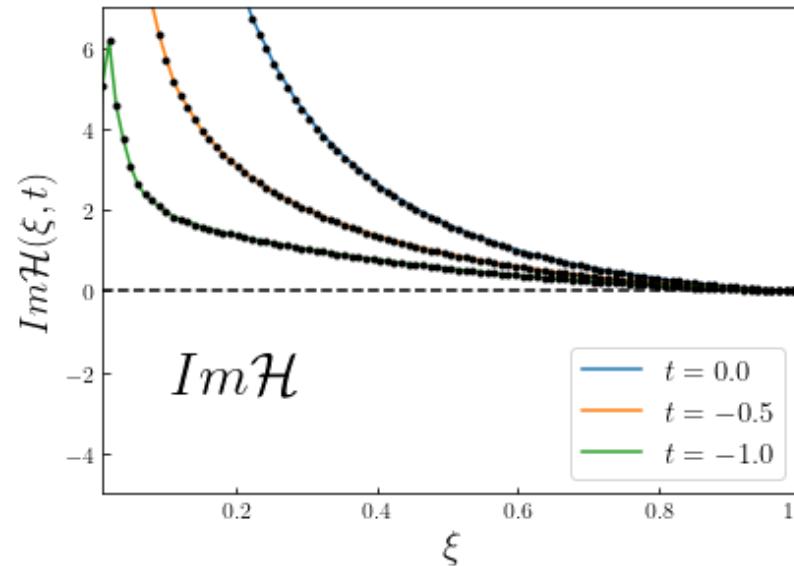
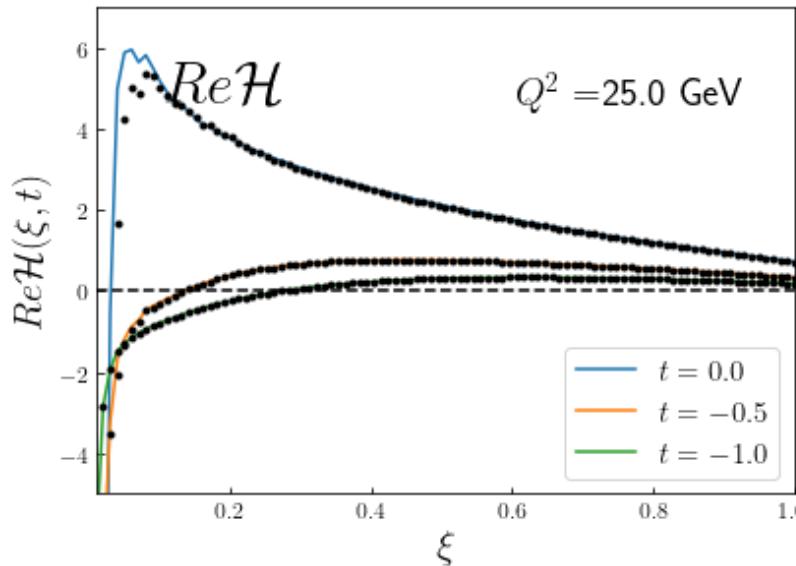
GPDs extraction with NN

- NN as pixel generator for Double Distributions
- Layers
- Results

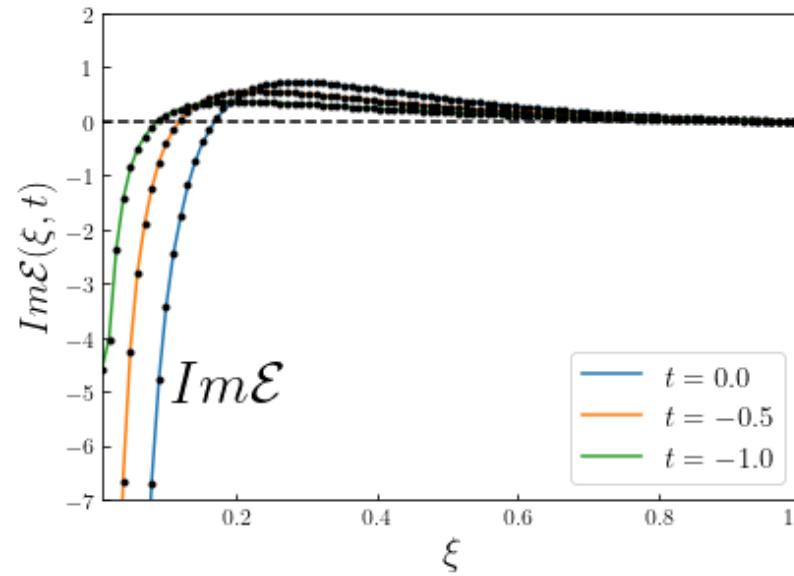
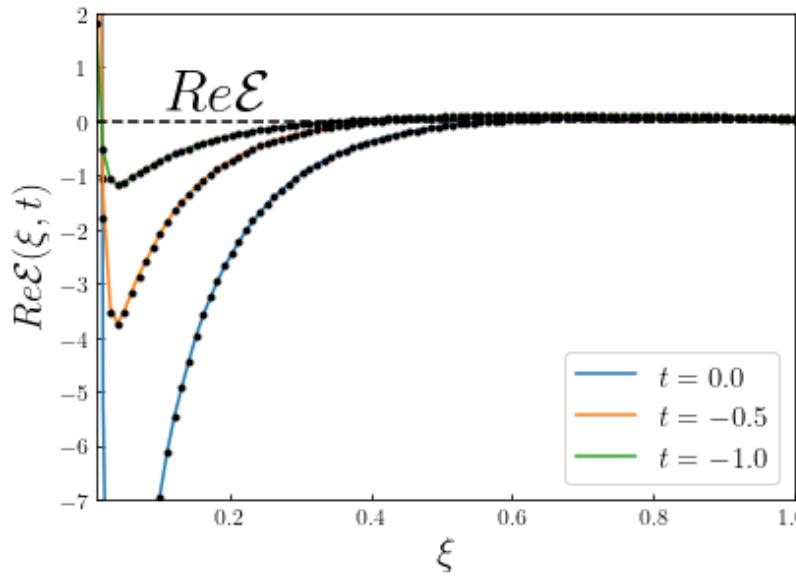
Extracting GPDs with NN



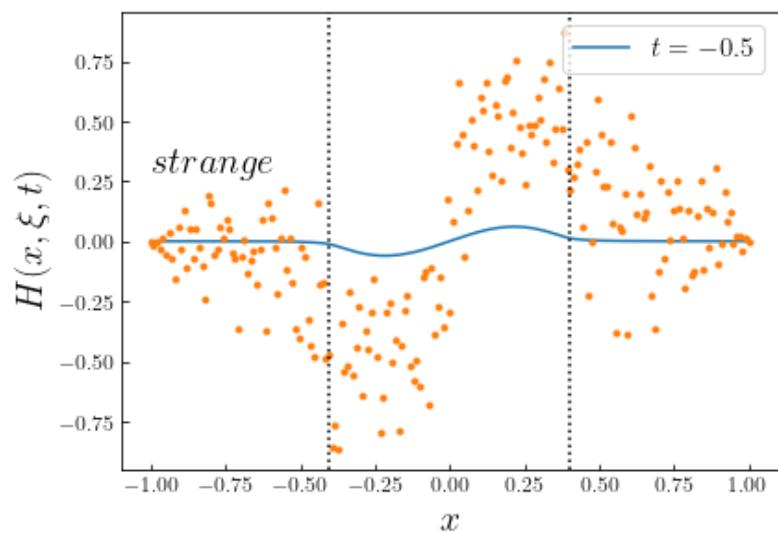
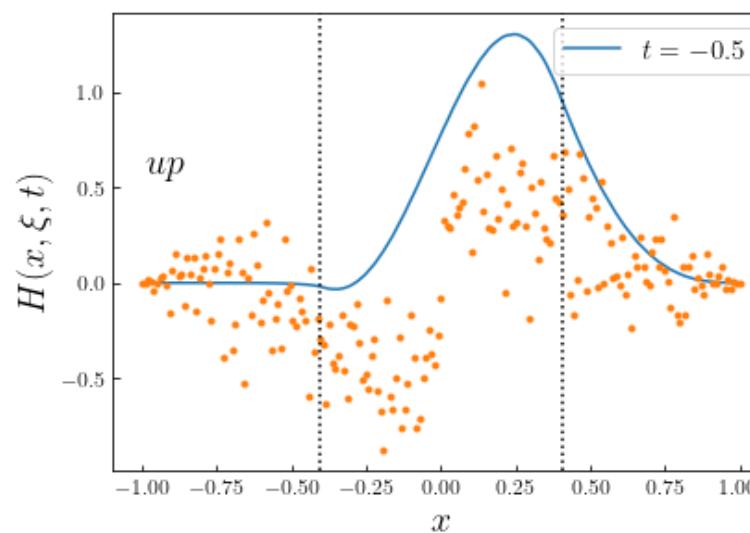
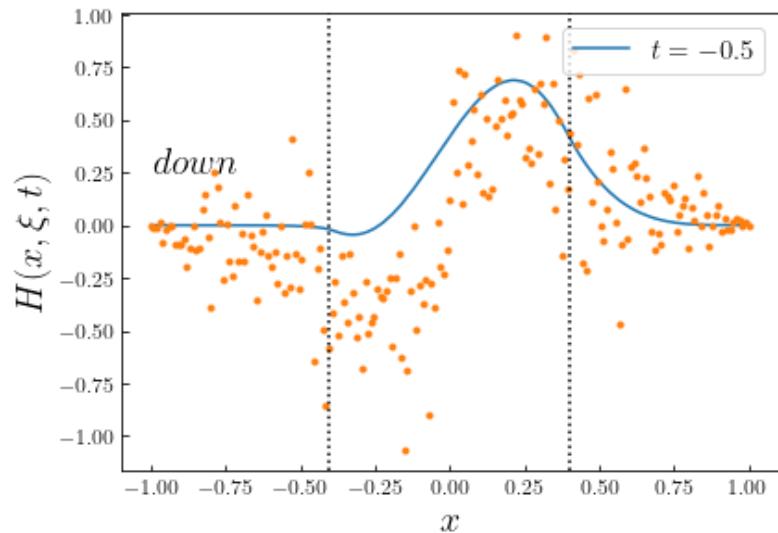
Extracting GPDs with NN



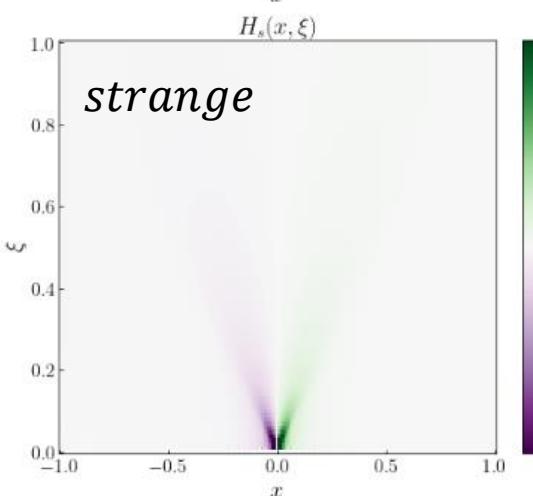
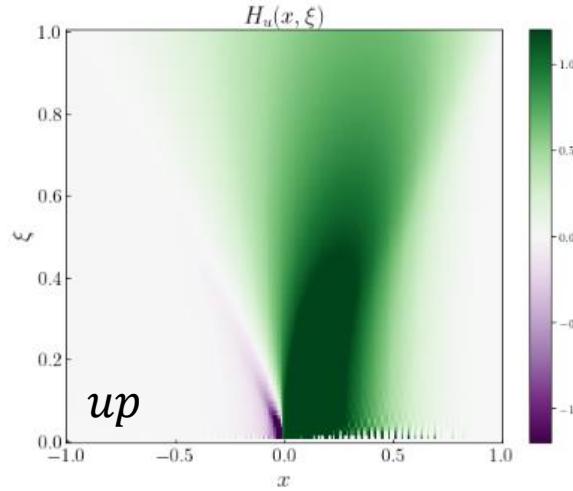
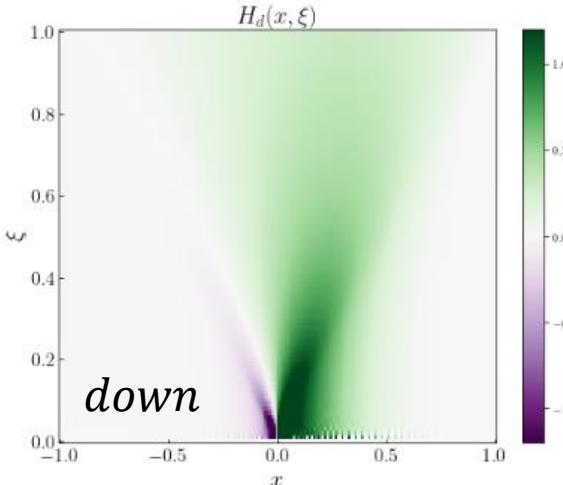
Solid lines: true
Black point: NN



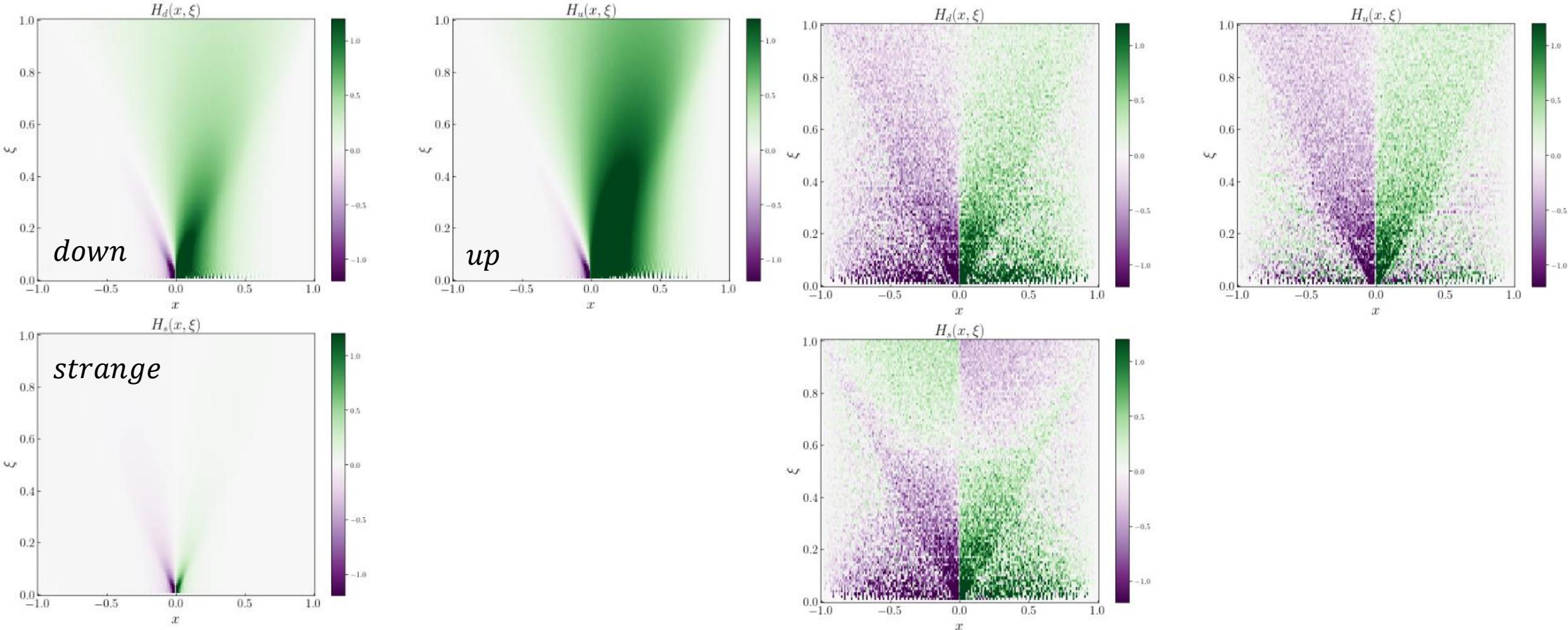
Extracting GPDs with NN



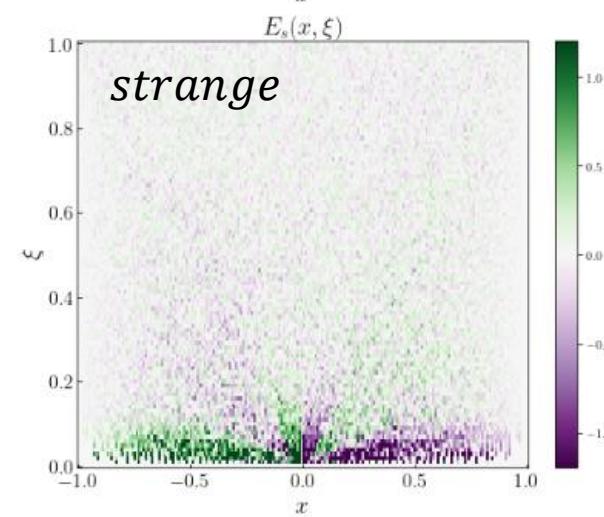
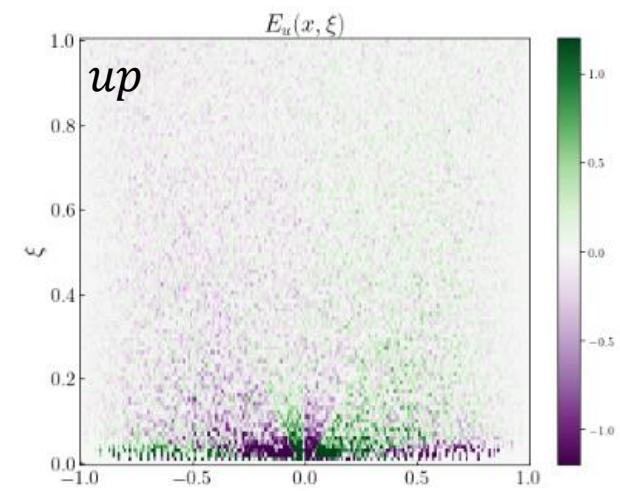
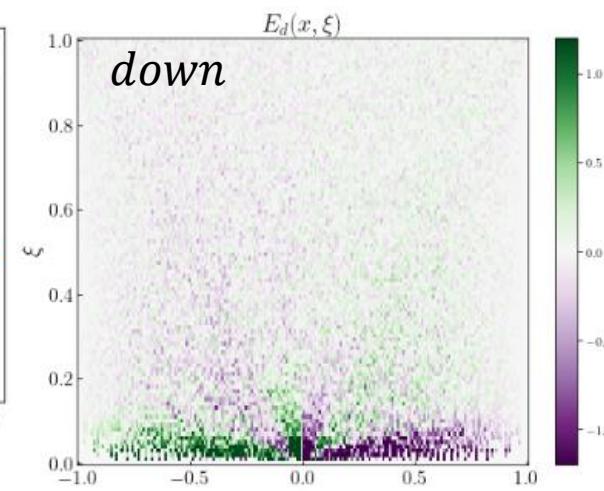
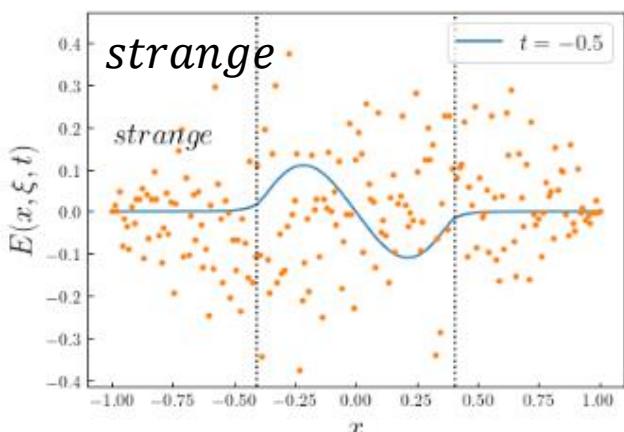
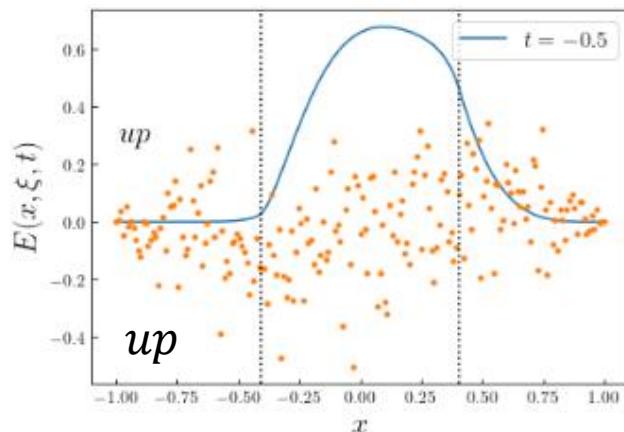
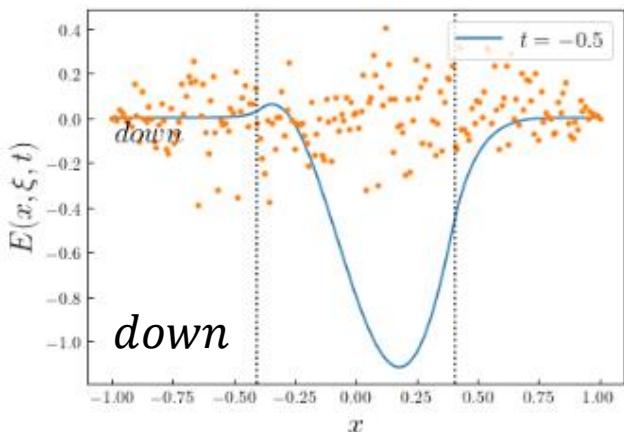
Extracting GPDs with NN



Extracting GPDs with NN



Extracting GPDs with NN



Conclusions

Theory:

- What is a GPD?
- How do we construct a GPD?
- Where do we get them?
- Evolution equations
- How do we get the observable?

To do: Evolution equations for Long. Pol. GPDs and at NLO

To do: DVCS cross section and asymmetries