

Energy Transfer and Scale-Locality in Compressible Shocks: Revisiting the Cascade Picture

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Compressible Turbulence: From Cold Atoms to Neutron Star Mergers Summer 2025











Normal Shock: A Real Compressible System

Incompressible Turbulence Theory

1. Relied in a central way on an empirical observation: The "Zeroth Law" of Turbulence [G. I. Taylor (1935)]

2. The 4/5-th Law

 Inertial Range: Assuming self-similarity (scale-invariance), and scale-locality [Kolmogorov (1941, 1946), Onsager (1945)]

Zeroth Law of Turbulence



Empirical Observation¹:

$$C_{\varepsilon} = \frac{\varepsilon_{dissip}}{U_{rms}^3/L}$$

G.I. Taylor, Proc. Roy. Soc. Lond., (1935)

Dissipation is independent of microphysical viscosity.

Zeroth Law of Turbulence





A. Kolmogorov AM. Obukhov W. Heisenberg CF Weizsacker



"turbulent fluids could be described by singular (weak) solutions of incompressible Euler equations whose kineticenergy balance would be afflicted with an anomaly due to the nonlinear cascade mechanism¹."

L. Onsager

Eyink & Drivas, 2018, Phys. Rev. X.
 A voyage through Turbulence, 2011

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Traditional derivation (e.g. Frisch's 1995 book)

$$\partial_t \boldsymbol{u} + \boldsymbol{u} \cdot \nabla \boldsymbol{u} = -\nabla p + \nu \nabla^2 \boldsymbol{u} + \boldsymbol{f}$$

Point-splitting KE budget (a form of scale decomposition)

$$\partial_t \langle \boldsymbol{u}(x) \cdot \boldsymbol{u}(x+r) \rangle = \frac{1}{4} \nabla_r \cdot \langle |\delta \boldsymbol{u}(r)|^2 \delta \boldsymbol{u}(r) \rangle$$
 –Dissipation + Forcing

Traditional derivation (e.g. Frisch's 1995 book)

$$\partial_t \boldsymbol{u} + \boldsymbol{u} \cdot \nabla \boldsymbol{u} = -\nabla p + \nu \nabla^2 \boldsymbol{u} + \boldsymbol{f}$$

Point-splitting KE budget (a form of scale decomposition) Assuming homogeneity

 $\partial_t \langle \boldsymbol{u}(\boldsymbol{x}) \cdot \boldsymbol{u}(\boldsymbol{x} + \boldsymbol{r}) \rangle = \frac{1}{4} \nabla_{\boldsymbol{r}} \cdot \langle |\delta \boldsymbol{u}(\boldsymbol{r})|^2 \delta \boldsymbol{u}(\boldsymbol{r}) \rangle$ –Dissipation + Forcing

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Point-splitting KE budget (a form of scale decomposition)

$$\partial_t \langle \boldsymbol{u}(\boldsymbol{x}) \cdot \boldsymbol{u}(\boldsymbol{x} + \boldsymbol{r}) \rangle = \frac{1}{4} \nabla_{\boldsymbol{r}} \cdot \langle |\delta \boldsymbol{u}(\boldsymbol{r})|^2 \delta \boldsymbol{u}(\boldsymbol{r}) \rangle$$
 –Dissipation + Forcing

The Cascade Term

Increments: $\delta u(r;x) = u(x+r) - u(x)$ Galilean Invariant
Scaling Conditions
Cale-local

11

Traditional derivation (e.g. Frisch's 1995 book)

$$\partial_t \boldsymbol{u} + \boldsymbol{u} \cdot \nabla \boldsymbol{u} = -\nabla p + \nu \nabla^2 \boldsymbol{u} + \boldsymbol{f}$$

This is just conservation of kinetic energy at each scale, r!

Point-splitting KE budget (a form of scale decomposition)

$$\partial_t \langle \boldsymbol{u}(x) \cdot \boldsymbol{u}(x+\boldsymbol{r}) \rangle = \frac{1}{4} \nabla_{\boldsymbol{r}} \cdot \langle |\delta \boldsymbol{u}(\boldsymbol{r})|^2 \delta \boldsymbol{u}(\boldsymbol{r}) \rangle$$
 –Dissipation + Forcing



For r in the inertial range:



 $\partial_t \langle \boldsymbol{u}(\boldsymbol{x}) \cdot \boldsymbol{u}(\boldsymbol{x} + \boldsymbol{r}) \rangle = \frac{1}{4} \nabla_{\boldsymbol{r}} \cdot \langle |\delta \boldsymbol{u}(\boldsymbol{r})|^2 \delta \boldsymbol{u}(\boldsymbol{r}) \rangle$ –Dissipation + Forcing

For r in the inertial range:

 $\partial_t \langle \boldsymbol{u}(\boldsymbol{x}) \cdot \boldsymbol{u}(\boldsymbol{x} + \boldsymbol{r}) \rangle = \frac{1}{4} \nabla_{\boldsymbol{r}} \cdot \langle |\delta \boldsymbol{u}(\boldsymbol{r})|^2 \delta \boldsymbol{u}(\boldsymbol{r}) \rangle - \text{Dissipation} + \text{Forcing}$ $S_3(\boldsymbol{r}) = \left\langle \left(\delta u_{\parallel}(\boldsymbol{r}) \right)^3 \right\rangle = -\frac{4}{5} \varepsilon \boldsymbol{r} \quad \text{Assuming self-similarity, no intermittent} \quad \text{event!}$

$$S_p(r) = \left\langle \left(\delta u_{\parallel}(r) \right)^p \right\rangle = C_p(\varepsilon r)^{p/3}$$

For r in the inertial range:

$$\partial_t \langle \boldsymbol{u}(x) \cdot \boldsymbol{u}(x+r) \rangle = \frac{1}{4} \nabla_r \cdot \langle |\delta \boldsymbol{u}(r)|^2 \delta \boldsymbol{u}(r) \rangle$$
 –Dissipation + Forcing

$$S_3(r) = \left\langle \left(\delta u_{\parallel}(r) \right)^3 \right\rangle = -\frac{4}{5} \varepsilon r$$

 Assuming self-similarity, no intermittent event!

$$S_p(r) = \left\langle \left(\delta u_{\parallel}(r) \right)^p \right\rangle = C_p(\varepsilon r)^{p/3}$$
 Works fine for $p = 3 \pm 1!$

$$S_2(r) = \left\langle \left(\delta u_{\parallel}(r) \right)^2 \right\rangle \sim r^{2/3} \qquad \longleftrightarrow \qquad E(k) \sim k^{-5/3}$$

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 Inertial Range: Assuming self-similarity (scale-invariance), and scale-locality [Kolmogorov (1941, 1946), Onsager (1945)]

We have a relatively clear picture of the dynamics in **incompressible** turbulent systems.





L. Richardson (1922)



A. Kolmogorov

(1941)

L. Onsager (1945)



Decaying, isotropic, homogeneous turbulent system (Saadat, et al., 2021)

- Forcing and Boundary Conditions at integral scales.
- Viscous Dissipation at smallest scales.
- Inertial range

We have a relatively clear picture of the dynamics in **incompressible** turbulent systems.



Scale-locality:

- Different modes exchange energy with neighbors mostly.
- Justifies expectation of universal statistics.
- Implicit assumption in LES Modeling.



L. Richardson (1922)



A. Kolmogorov (1941)



L. Onsager

(1945)

R. Kraichnan (1959)



G. Eyink (1994, 2005)



Method: Coarse-graining Approach



$G_{\ell}(\boldsymbol{r})$ should be:

- Homogeneous,
- Normalized,
- Spatially localized.



Method: Coarse-graining Approach





Coarse Cons. of Momentum:

 $\partial_t \bar{u} + \bar{u} \cdot \nabla \bar{u} = -\nabla \bar{p} - \nabla \cdot \tau_\ell + \mu \nabla^2 \bar{u} \qquad \nabla \cdot \bar{u} = 0$

Sub-scale Stress: $\tau_{\ell} = (\overline{u}\overline{u}_{\ell} - \overline{u}_{\ell}\overline{u}_{\ell})$



...

A. Leonard (1974)



M. Germano (1992)



G. Eyink

(1994)

C. Meneveau (1994)



H. Aluie (2011)

With the incompressible Turbulence Theory, we can explain:

Ocean Dynamics



Terrestrial Flows



Atmospheric Dynamics



But compressible turbulence theory is essential to understand:



Crab Nebula, NASA

Supernovae Explosions



NASA

Supersonic Flight



NIF, Lawrence Livermore National Laboratory Inertial Confinement Fusion

Energy Transfer Across Scales: Compressible

Mass Cons.

 $\partial_t \rho + \nabla \cdot (\rho \boldsymbol{u}) = 0$

Momentum Cons.

$$\partial_t(\rho \boldsymbol{u}) + \boldsymbol{\nabla} \cdot (\rho \boldsymbol{u} \boldsymbol{u}) = \boldsymbol{\nabla} P + \boldsymbol{\nabla} \cdot (2\eta \boldsymbol{S} \cdot \boldsymbol{u} + \zeta \theta \boldsymbol{u})$$

Equation of State

+

Total Energy Cons.

$$\partial_t \left(\frac{1}{2} \rho u^2 + e \right) + \nabla \cdot \left[\left(e + P + \frac{1}{2} \rho u^2 \right) \boldsymbol{u} - \kappa \nabla T - 2\eta \boldsymbol{S} \cdot \boldsymbol{u} - \zeta \theta \boldsymbol{u} \right] = 0$$

Energy Transfer Across Scales: Compressible

Mass Cons. $\partial_t \rho + \nabla \cdot (\rho u) = 0$

Momentum Cons. ∂_t

$$\partial_t(\rho u) + \nabla \cdot (\rho u u) = \nabla P + \nabla \cdot (2\eta S \cdot u + \zeta \theta u) + Equation of State$$

Total Energy Cons.

$$\partial_t \left(\frac{1}{2} \rho u^2 + e \right) + \nabla \cdot \left[\left(e + P + \frac{1}{2} \rho u^2 \right) \boldsymbol{u} - \kappa \nabla T - 2\eta \boldsymbol{S} \cdot \boldsymbol{u} - \zeta \theta \boldsymbol{u} \right] = 0$$

Kinetic Energy
Budget
$$\partial_t \left(\frac{1}{2}\rho u^2\right) + \nabla \cdot J_{KE} = p(\nabla \cdot u) - 2\eta |S|^2 - \zeta \theta^2$$
Internal Energy
Budget $\partial_t (e) + \nabla \cdot J_{IE} = -p(\nabla \cdot u) + 2\eta |S|^2 + \zeta \theta^2$ Pressure-DilatationViscous DissipationViscous DissipationViscous Dissipation

Modify the Coarse-graining Method

Favre Averaging (Favre, 1965) $\overline{u}_{\ell}(\mathbf{x}) = \int d\mathbf{r} \, u(\mathbf{r}) G_{\ell}(\mathbf{x} + \mathbf{r})$ $\widetilde{\boldsymbol{u}}_{\ell}(\boldsymbol{x}) \equiv \frac{\overline{\rho \boldsymbol{u}_{\ell}}}{\overline{\rho_{\ell}}}$

Why Favre Averaging? The Scale-decomposition must satisfy the Inviscid Criterion [Aluie Physica D (2013)].

Coarse Cons. of Momentum:



1.2

Zhao, Aluie, 2019, PRF

 $\partial_t (\bar{\rho}_\ell \tilde{\boldsymbol{u}}_\ell) + \nabla \cdot (\bar{\rho}_\ell \tilde{\boldsymbol{u}}_\ell \tilde{\boldsymbol{u}}_\ell) = -\nabla \bar{P}_\ell - \nabla \cdot (\bar{\rho} \tilde{\tau}_\ell) + \mu \nabla \cdot \bar{\sigma}_\ell + \bar{\rho}_\ell \tilde{\boldsymbol{F}} \qquad \bar{\rho} \tilde{\tau}_\ell = \bar{\rho}_\ell (\tilde{\boldsymbol{u}} \tilde{\boldsymbol{u}}_\ell - \tilde{\boldsymbol{u}}_\ell \tilde{\boldsymbol{u}}_\ell)$



...

A. Leonard (1974)



M. Germano (1992)



G. Eyink

(1994)

C. Meneveau (1994)



H. Aluie (2011)



 $\langle \Sigma^{F, \, \text{diss}} \rangle$

 $\left< \Sigma_{\ell}^{C, \text{diss}} \right>$

 $\left\langle \Sigma_{\ell}^{K,\,\mathrm{diss}} \right\rangle$

$$\bar{f}_{\ell}(\boldsymbol{x}) = \int d\boldsymbol{r} \, G_{\ell}(\boldsymbol{r}) \boldsymbol{f}(\boldsymbol{x} + \boldsymbol{r})$$
$$\tilde{f}_{\ell}(\boldsymbol{x}) \equiv \frac{\overline{\rho f_{\ell}}}{\overline{\rho_{\ell}}}$$



$$\partial_t \left(\bar{\rho}_\ell \frac{|\tilde{u}_\ell|^2}{2} \right) + \nabla \cdot \boldsymbol{J}_\ell = -\Pi_\ell - \Lambda_\ell - \overline{\tau}(p, \nabla \cdot \boldsymbol{u}) - (-\overline{P \nabla \cdot u}_\ell) - D_\ell$$

$$\bar{f}_{\ell}(\boldsymbol{x}) = \int d\boldsymbol{r} \, G_{\ell}(\boldsymbol{r}) \boldsymbol{f}(\boldsymbol{x} + \boldsymbol{r})$$
$$\tilde{f}_{\ell}(\boldsymbol{x}) \equiv \frac{\overline{\rho f_{\ell}}}{\overline{\rho_{\ell}}}$$



Temporal Change of Coarse KE

$$\partial_t \left(\bar{\rho}_{\ell} \frac{|\tilde{u}_{\ell}|^2}{2} \right) + \nabla \cdot \boldsymbol{J}_{\ell} = -\Pi_{\ell} - \Lambda_{\ell} - \overline{\tau}(p, \nabla \cdot \boldsymbol{u}) - (-\overline{P\nabla \cdot u}_{\ell}) - D_{\ell}$$

$$\bar{f}_{\ell}(\boldsymbol{x}) = \int d\boldsymbol{r} \, G_{\ell}(\boldsymbol{r}) \boldsymbol{f}(\boldsymbol{x} + \boldsymbol{r})$$
$$\tilde{f}_{\ell}(\boldsymbol{x}) \equiv \frac{\overline{\rho f_{\ell}}}{\overline{\rho_{\ell}}}$$



$$\partial_t \left(\bar{\rho}_{\ell} \frac{|\tilde{u}_{\ell}|^2}{2} \right) + \nabla \cdot \boldsymbol{J}_{\ell} = -\Pi_{\ell} - \Lambda_{\ell} - \overline{\tau} (p, \nabla \cdot \boldsymbol{u}) - (-\overline{P \nabla \cdot \boldsymbol{u}}_{\ell}) - D_{\ell}$$

Spatial Transport

$$\bar{f}_{\ell}(\boldsymbol{x}) = \int d\boldsymbol{r} \, G_{\ell}(\boldsymbol{r}) \boldsymbol{f}(\boldsymbol{x} + \boldsymbol{r})$$
$$\tilde{f}_{\ell}(\boldsymbol{x}) \equiv \frac{\overline{\rho f_{\ell}}}{\overline{\rho_{\ell}}}$$



No transfer in scale. Zero on average for spatially homogeneous flows. $\partial_t \left(\bar{\rho}_\ell \frac{|\tilde{u}_\ell|^2}{2} \right) + \nabla \cdot \boldsymbol{J}_\ell = -\Pi_\ell - \Lambda_\ell - \overline{\tau}(p, \nabla \cdot \boldsymbol{u}) - (-\overline{P \nabla \cdot u}_\ell) - D_\ell$ Spatial Transport

$$\bar{f}_{\ell}(\boldsymbol{x}) = \int d\boldsymbol{r} \, G_{\ell}(\boldsymbol{r}) \boldsymbol{f}(\boldsymbol{x} + \boldsymbol{r})$$
$$\tilde{f}_{\ell}(\boldsymbol{x}) \equiv \frac{\overline{\rho f_{\ell}}}{\overline{\rho_{\ell}}}$$



Viscous Dissipation

Plays role at Smallest Scales¹

 $\bar{f}_{\ell}(\boldsymbol{x}) = \int d\boldsymbol{r} \, G_{\ell}(\boldsymbol{r}) \boldsymbol{f}(\boldsymbol{x} + \boldsymbol{r})$ $\tilde{f}_{\ell}(\boldsymbol{x}) \equiv \frac{\overline{\rho f_{\ell}}}{\overline{\rho_{\ell}}}$

 $1 \sim 12$

/



Acts as a large-scale forcing

$$\partial_t \left(\bar{\rho}_{\ell} \frac{|u_{\ell}|^2}{2} \right) + \nabla \cdot \boldsymbol{J}_{\ell} = -\Pi_{\ell} - \Lambda_{\ell} - \overline{\tau}(p, \nabla \cdot \boldsymbol{u}) - (-\overline{P} \nabla \cdot \boldsymbol{u}_{\ell}) - D_{\ell}$$
Pressure-Dilatation

Coarse-grained KE Budget

$$\bar{f}_{\ell}(\mathbf{x}) = \int d\mathbf{r} \ G_{\ell}(\mathbf{r}) f(\mathbf{x} + \mathbf{r}) \\
\bar{f}_{\ell}(\mathbf{x}) = \frac{\overline{\rho} \overline{f_{\ell}}}{\overline{\rho_{\ell}}} \\
\Lambda_{\ell}(\mathbf{x}) = \frac{1}{\overline{\rho_{\ell}}} \partial_{\mathbf{x}} \bar{p}_{\ell} [(\rho u)_{\ell} - \bar{\rho}_{\ell} \bar{u}_{\ell}] \\
Baropycnal Work \\
\partial_{t} \left(\overline{\rho_{\ell}} \frac{|\tilde{u}_{\ell}|^{2}}{2} \right) + \nabla \cdot J_{\ell} = -\Pi_{\ell} - \Lambda_{\ell} - \overline{\tau} (p, \nabla \cdot u) - (-\overline{P} \nabla \cdot u_{\ell}) - D_{\ell} \\
\Pi_{\ell}(\mathbf{x}) = -\partial_{\mathbf{x}} \overline{u}_{\ell} [(u^{2})_{\ell} - \overline{u}_{\ell}^{2}] \\
Deformation Work \\
Filtering Scale: \ell \\
\ell_{\ell}(\mathbf{x}) = \frac{1}{\rho_{\ell}} \partial_{\mathbf{x}} \bar{p}_{\ell} \left(-\overline{\rho} \nabla \cdot u_{\ell} \right) - D_{\ell} \\
\overline{\tau}_{\ell}(\mathbf{x}) = (\overline{p} \nabla \cdot u)_{\ell} - \overline{p}_{\ell} \nabla \cdot u_{\ell} \\
Pressure-Dilatation Defect$$

Filtering Scale:
$$\ell$$

 $\bar{f}_{\ell}(\mathbf{x}) = \int d\mathbf{r} \ G_{\ell}(\mathbf{r}) f(\mathbf{x} + \mathbf{r})$
 $\tilde{f}_{\ell}(\mathbf{x}) \equiv \frac{\overline{\rho}f_{\ell}}{\overline{\rho}_{\ell}}$
 $\tilde{f}_{\ell}(\mathbf{x}) \equiv \frac{|\tilde{u}_{\ell}|^2}{\overline{\rho}_{\ell}}$
 $\tilde{f}_{\ell}(\mathbf{x}) \equiv \frac{|\tilde{u}_{\ell}|^2}{\overline{\rho$

Sub-scale Flux Mechanisms

There is an unrefined intuition about shocks ...



Messier 42: Orion Nebula [Source: NASA]

McKee & Ostriker, 2007, Ann. Rev. Fluid. Mech.
 Ferrand et al., 2020, ApJ.

... some portion of the energy at a given scale must be directly dissipated via shocks, rather than cascading conservatively through intermediate scales until dissipation scales is reached. [McKee & Ostriker (2007)]



Bow shock near young star, LL Ori [Source: NASA]

Not just in the astrophysics community, ...



Lake Superior, US [Source: UCAR]

... spectrally nonlocal pathway for downscale energy transfer that is phenomenologically distinct from traditional concepts of turbulent cascades and can contribute substantially to total kinetic energy dissipation. [Samelson & Skyllingstad (2016)]

Kraichnan and Locality

Kraichnan (1974):

A generally unappreciated point is that the <u>inertial-range</u> <u>energy cascade is local in wavenumber</u>, even when the inertial-range spectrum is the spectral tail of coherent discontinuous structures,....










Even in 1D, shock is a multiscale structure!



Even in 1D, shock is a multiscale structure!

 $\partial_t u + u \partial_x u = \nu \partial_{xx},$

$$\partial_t \frac{|\overline{u}_\ell|^2}{2} = -\Pi_\ell - D_\ell,$$

$$\Pi_{\ell}(\mathbf{x}) = -\partial_{x}\overline{u}_{\ell}\left[\overline{(u^{2})}_{\ell} - \overline{u}_{\ell}^{2}\right]$$

The mechanism that represents vortex stretching or energy cascade.



0

 $\partial_t u + u \partial_x u = \nu \partial_{xx},$

$$\partial_t \frac{|\overline{u}_\ell|^2}{2} = -\Pi_\ell - D_\ell,$$

$$\Pi_{\ell}(\mathbf{x}) = -\partial_{x}\overline{u}_{\ell}\left[\overline{(u^{2})}_{\ell} - \overline{u}_{\ell}^{2}\right]$$

The mechanism that represents vortex stretching or energy cascade.



 $\partial_t u + u \partial_x u = \nu \partial_{xx},$

$$\partial_t \frac{|\overline{u}_\ell|^2}{2} = -\Pi_\ell - D_\ell,$$

 $\Pi_{\ell}(\mathbf{x}) = -\partial_{x}\overline{u}_{\ell}\left[\overline{(u^{2})}_{\ell} - \overline{u}_{\ell}^{2}\right]$

The mechanism that represents vortex stretching or energy cascade.



0

 $\partial_{t}u + u\partial_{x}u = v\partial_{xx},$ For $\ell = 0.15L \longrightarrow \bar{u}_{\ell}(x) = \int dr \, u(r)G_{\ell}(x+r)$ $u'_{\ell}(x) = u(x) - \bar{u}_{\ell}(x)$ $\partial_{t} \frac{|\bar{u}_{\ell}|^{2}}{2} = -\Pi_{\ell} - D_{\ell},$ $\Pi_{\ell}(x) = -\partial_{x}\bar{u}_{\ell}\left[(u^{2})_{\ell} - \bar{u}_{\ell}^{2}\right]$



 $\partial_{t} u + u \partial_{x} u = v \partial_{xx},$ For $\ell = 0.15L \longrightarrow \bar{u}_{\ell}(x) = \int dr \, u(r) G_{\ell}(x+r)$ $u'_{\ell}(x) = u(x) - \bar{u}_{\ell}(x)$ $\partial_{t} \frac{|\bar{u}_{\ell}|^{2}}{2} = -\Pi_{\ell} - D_{\ell},$ $\Pi_{\ell}(x) = -\partial_{x} \bar{u}_{\ell} \left[(u^{2})_{\ell} - \bar{u}_{\ell}^{2} \right]$



















 $u_{\ell}'(x) = u(x) - \bar{u}_{\ell}(x)$

For $\ell = 0.15L \longrightarrow \bar{u}_{\ell}(x) = \int dr \, u(r) G_{\ell}(x+r)$

 $\partial_t u + u \partial_x u = \nu \partial_{xx},$





Scale Locality of the cascade in Burgers Shock: $\Pi_{\ell}(x)$



Scale Locality of the cascade in Burgers Shock: $\Pi_{\ell}(x)$

$$\left\|\left\langle \Pi_{\ell_{K}}\left(\bar{u}_{\ell_{Q}}, u, u\right)\right\rangle / \left\langle \Pi_{\ell_{K}}(u, u, u)\right\rangle \right\| \to 0 \quad \text{As } Q \to 0$$

Deformation work is infrared local.



 $k_{\ell} = 10$

Scale Locality of the cascade in Burgers Shock: $\Pi_{\ell}(x)$

 $\left\|\left\langle \Pi_{\ell_{K}}(u,u',u)\right\rangle / \left\langle \Pi_{\ell_{K}}(u,u,u)\right\rangle \right\| \to 0 \qquad \text{As } Q \to \infty$



Coarse-grained KE Budget

$$\bar{f}_{\ell}(\boldsymbol{x}) = \int d\boldsymbol{r} \, G_{\ell}(\boldsymbol{r}) \boldsymbol{f}(\boldsymbol{x} + \boldsymbol{r})$$
$$\tilde{f}_{\ell}(\boldsymbol{x}) \equiv \frac{\overline{\rho f_{\ell}}}{\overline{\rho_{\ell}}}$$



$$\partial_t \left(\bar{\rho}_{\ell} \frac{|\tilde{u}_{\ell}|^2}{2} \right) + \nabla \cdot \boldsymbol{J}_{\ell} = -\Pi_{\ell} - \Lambda_{\ell} - \overline{\tau}(\boldsymbol{p}, \nabla \cdot \boldsymbol{u}) - (-\overline{P\nabla \cdot u}_{\ell}) - D_{\ell}$$

$$\int \text{Deformation Work is scale-local.}$$

Coarse-grained KE Budget

$$\bar{f}_{\ell}(\boldsymbol{x}) = \int d\boldsymbol{r} \, G_{\ell}(\boldsymbol{r}) \boldsymbol{f}(\boldsymbol{x} + \boldsymbol{r})$$
$$\tilde{f}_{\ell}(\boldsymbol{x}) \equiv \frac{\overline{\rho f_{\ell}}}{\overline{\rho_{\ell}}}$$



$$\partial_t \left(\bar{\rho}_\ell \frac{|\tilde{u}_\ell|^2}{2} \right) + \nabla \cdot \boldsymbol{J}_\ell = -\Pi_\ell - \Lambda_\ell - \overline{\tau}(\boldsymbol{p}, \nabla \cdot \boldsymbol{u}) - (-\overline{P\nabla \cdot u}_\ell) - D_\ell$$

Baropycnal Work

Normal Shock: A Real Compressible System



1. Johnson, 2014, J. Fluid. Mech.

Normal Shock: A Real Compressible System



1. Johnson, 2014, J. Fluid. Mech.

Normal Shock: A Real Compressible System



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$$\partial_t \left(\bar{\rho}_\ell \frac{|\tilde{u}_\ell|^2}{2} \right) + \nabla \cdot J_\ell = -\Pi_\ell - \Lambda_\ell - \overline{\tau} (p, \nabla \cdot \boldsymbol{u}) - (-\overline{P} \nabla \cdot \boldsymbol{u}_\ell) - D_\ell$$

$$A_\ell (\boldsymbol{w}) = \frac{1}{2} \partial_{\boldsymbol{v}} \overline{\boldsymbol{v}} \left[\overline{(\boldsymbol{w})} - \overline{\boldsymbol{v}} \right] = -\Pi_\ell - \Lambda_\ell - \overline{\tau} (p, \nabla \cdot \boldsymbol{u}) - (-\overline{P} \nabla \cdot \boldsymbol{u}_\ell) - D_\ell$$

$$\Lambda_{\ell}(\mathbf{x}) = \frac{1}{\bar{\rho}_{\ell}} \partial_{x} \bar{p}_{\ell} [(\rho u)_{\ell} - \bar{\rho}_{\ell} \bar{u}_{\ell}]$$



$$\Lambda_{\ell}(\mathbf{x}) = \frac{1}{\bar{\rho}_{\ell}} \partial_{x} \bar{p}_{\ell} \left[\overline{(\rho u)}_{\ell} - \bar{\rho}_{\ell} \bar{u}_{\ell} \right]$$





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$$\Lambda_{\ell}(\mathbf{x}) = \frac{1}{\bar{\rho}_{\ell}} \partial_{x} \bar{p}_{\ell} \left[\overline{(\rho u)}_{\ell} - \bar{\rho}_{\ell} \bar{u}_{\ell} \right]$$





$$\nabla \cdot \boldsymbol{J}_{\ell} = -\Pi_{\ell} - \Lambda_{\ell} - \overline{\tau}_{\ell} (\boldsymbol{p}, \nabla \cdot \boldsymbol{u}) - (-\overline{P \nabla \cdot \boldsymbol{u}}_{\ell}) - D_{\ell}$$

$$\boldsymbol{k}_{\ell} = 2 \qquad \boldsymbol{k}_{\ell} = 20$$



Scale Locality of the Sub-scale Flux: $\Lambda_{\ell}(x)$



Scale Locality of the Sub-scale Flux: $\Lambda_{\ell}(x)$



$$\nabla \cdot \boldsymbol{J}_{\ell} = -\Pi_{\ell} - \Lambda_{\ell} - \overline{\tau}_{\ell} (\boldsymbol{p}, \nabla \cdot \boldsymbol{u}) - (-\overline{P \nabla \cdot \boldsymbol{u}}_{\ell}) - D_{\ell}$$

$$\nabla \cdot J_{\ell} = \nabla \cdot (\overline{\rho} \, \frac{|\widetilde{u}|^2}{2} \widetilde{u} + \overline{p} \overline{u} + \widetilde{u} \overline{\rho} \widetilde{\tau}(u, u) - \widetilde{u} \overline{\sigma})$$



$$\nabla \cdot \boldsymbol{J}_{\ell} = -\Pi_{\ell} - \Lambda_{\ell} - \overline{\tau}_{\ell} (\boldsymbol{p}, \nabla \cdot \boldsymbol{u}) - (-\overline{P \nabla \cdot \boldsymbol{u}}_{\ell}) - D_{\ell}$$

$$\nabla \cdot J_{\ell} = \nabla \cdot (\overline{\rho} \frac{|u|}{2} \widetilde{u} + \overline{p} \overline{u} + \widetilde{u} \overline{\rho} \widetilde{\tau}(u, u) - \widetilde{u} \overline{\sigma})$$



$$\nabla \cdot \boldsymbol{J}_{\ell} = -\Pi_{\ell} - \Lambda_{\ell} - \overline{\tau}_{\ell} (\boldsymbol{p}, \nabla \cdot \boldsymbol{u}) - (-\overline{\boldsymbol{P} \nabla \cdot \boldsymbol{u}}_{\ell}) - D_{\ell}$$



Baropycnal Work in Rayleigh-Taylor: $\Lambda_{\ell}(x)$

$$\partial_t \left(\bar{\rho}_\ell \frac{|\tilde{u}_\ell|^2}{2} \right) + \nabla \cdot J_\ell = -\Pi_\ell - \Lambda_\ell - \overline{\tau} (p, \nabla \cdot u) - (-\overline{P} \nabla \cdot u_\ell) - D_\ell$$
$$\Lambda_\ell (\mathbf{x}) = \frac{1}{\bar{\rho}_\ell} \partial_x \bar{p}_\ell [\overline{(\rho u)}_\ell - \bar{\rho}_\ell \overline{u}_\ell]$$

 ∇p



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Baropycnal Work in Rayleigh-Taylor: $\Lambda_{\ell}(x)$

$$\partial_t \left(\bar{\rho}_\ell \frac{|\tilde{u}_\ell|^2}{2} \right) + \nabla \cdot \boldsymbol{J}_\ell = -\Pi_\ell - \Lambda_\ell - \overline{\tau} (\boldsymbol{p}, \nabla \cdot \boldsymbol{u}) - (-\overline{P} \nabla \cdot \boldsymbol{u}_\ell) - D_\ell$$

$$\Lambda_{\ell}(\mathbf{x}) = \frac{1}{\bar{\rho}_{\ell}} \frac{\partial_{x} \bar{p}_{\ell}}{|(\rho u)_{\ell}|} - \bar{\rho}_{\ell} \bar{u}_{\ell}$$
+

abla p



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Baropycnal Work in Rayleigh-Taylor: $\Lambda_{\ell}(x)$

$$\partial_t \left(\bar{\rho}_\ell \frac{|\tilde{u}_\ell|^2}{2} \right) + \nabla \cdot \boldsymbol{J}_\ell = -\Pi_\ell - \Lambda_\ell - \overline{\tau} (p, \nabla \cdot \boldsymbol{u}) - (-\overline{P \nabla \cdot u}_\ell) - D_\ell$$

$$\Lambda_{\ell}(\mathbf{x}) = \frac{1}{\bar{\rho}_{\ell}} \partial_{x} \bar{p}_{\ell} \overline{[(\rho u)}_{\ell} - \bar{\rho}_{\ell} \bar{u}_{\ell} +$$

╈ p(x)u(x)Heavy $\rho(x)$ Light H +

 ∇p

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Baropycnal Work in Rayleigh-Taylor: $\Lambda_{\ell}(x)$

$$\partial_t \left(\bar{\rho}_\ell \frac{|\tilde{u}_\ell|^2}{2} \right) + \nabla \cdot \boldsymbol{J}_\ell = -\Pi_\ell - \Lambda_\ell - \overline{\tau} \left(p, \nabla \cdot \boldsymbol{u} \right) - \left(-\overline{P} \nabla \cdot \boldsymbol{u}_\ell \right) - D_\ell$$

$$\Lambda_{\ell}(\mathbf{x}) = \frac{1}{\bar{\rho}_{\ell}} \partial_{\mathbf{x}} p_{\ell} [(\rho u)_{\ell} - \rho_{\ell} u_{\ell}] +$$





 ∇p

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