

# **New Bayesian Framework with Mass-Radius-Space Priors to Constrain the Neutron Star EOS**

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**In collaboration with**  
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**James M. Lattimer**

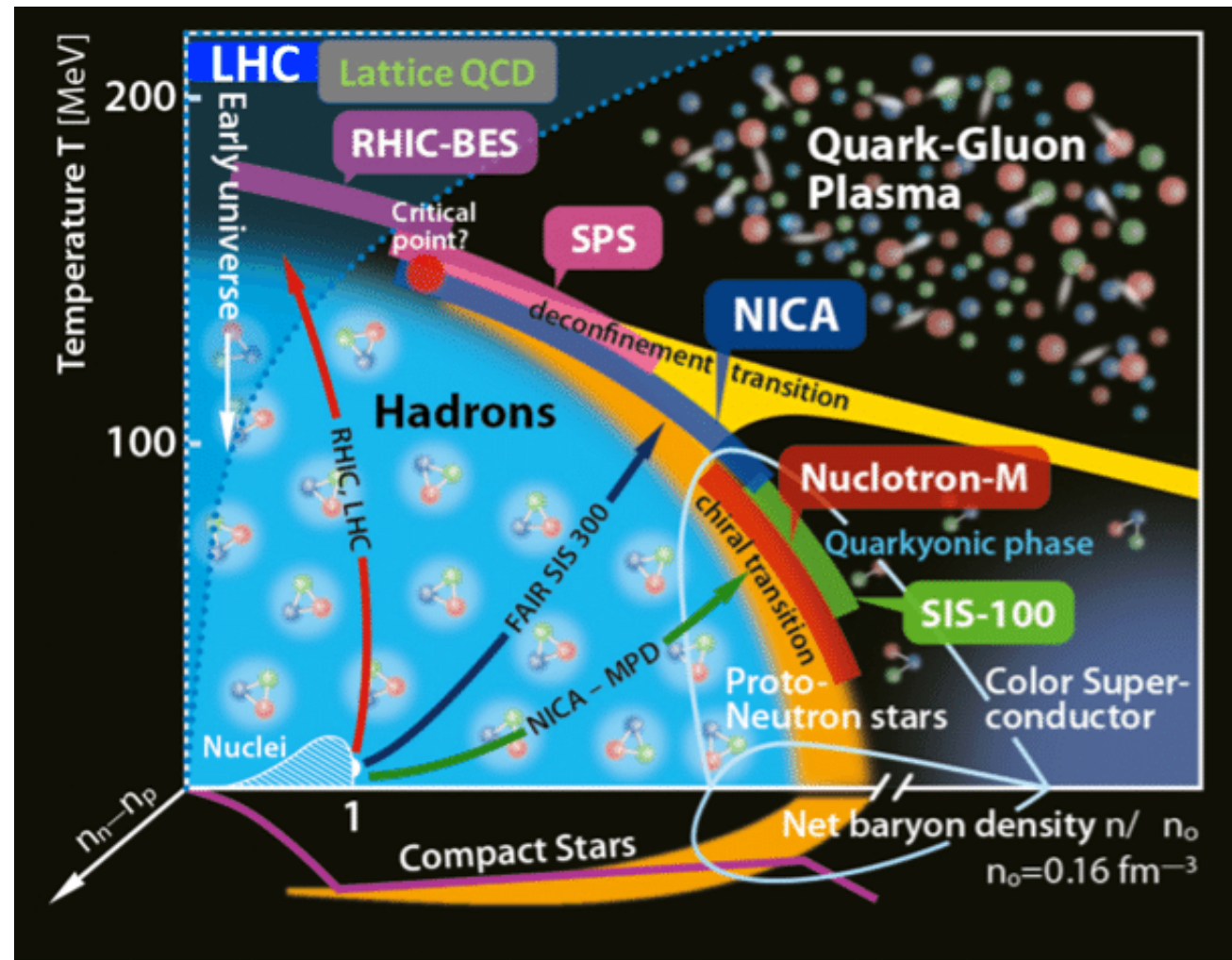
## Background

We aim to understand the EOS of cold ultra-dense matter (degenerate neutron matter)

However,

- It's impossible to access in terrestrial experiments currently (or near future)
- It's a non-perturbative QCD problem

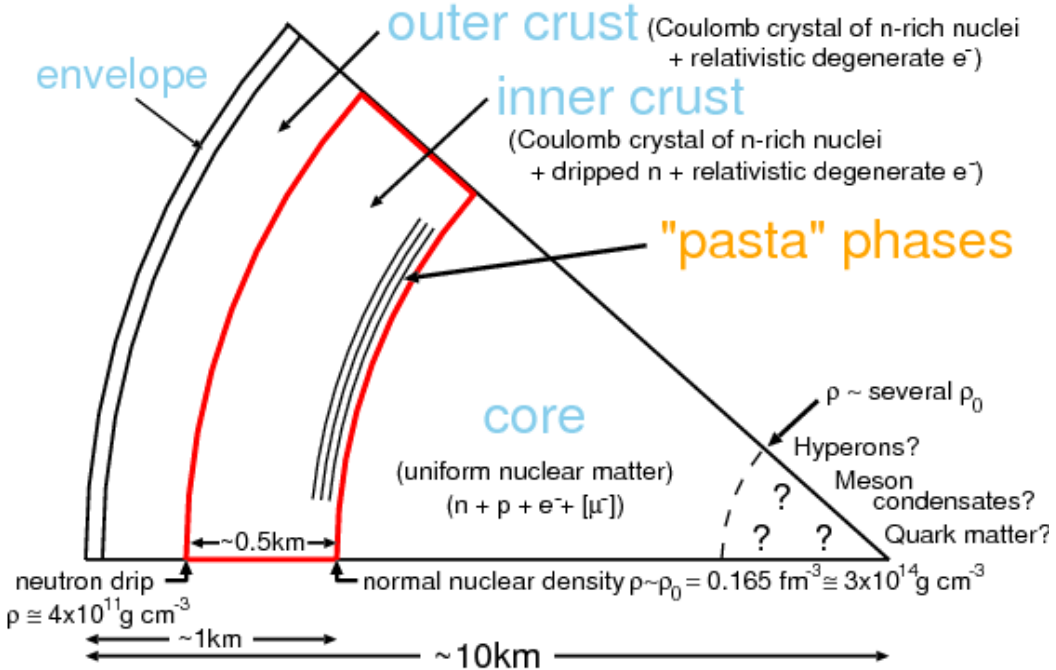
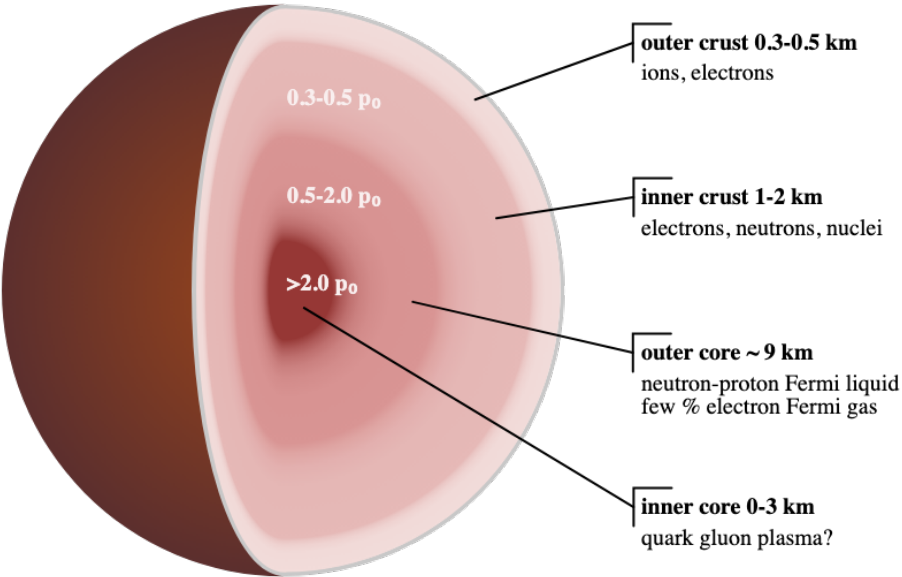
**So, what to do?**



<https://doi.org/10.48550/arXiv.2201.00202>

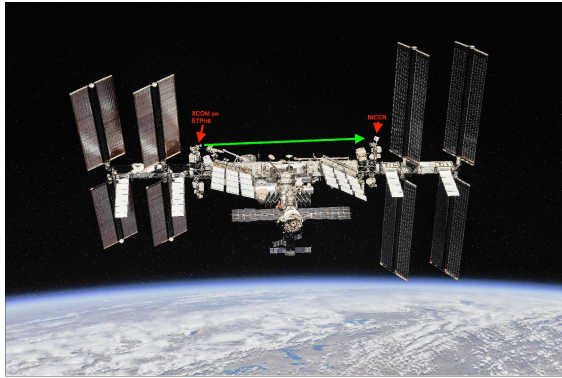
# Background

Neutron stars are natural labs to probe (cold) ultra-dense matter



## Background

We now have multi-messenger observations of neutron stars



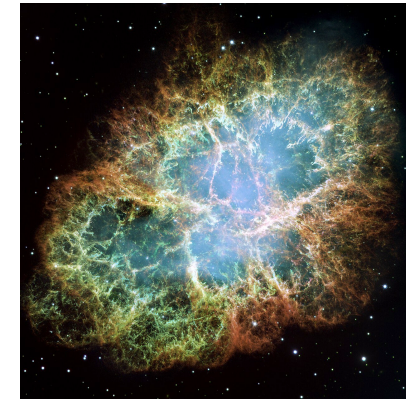
**X-ray Pulsar Timing: Mass and Radius**



**GW detections: Tidal deformability**



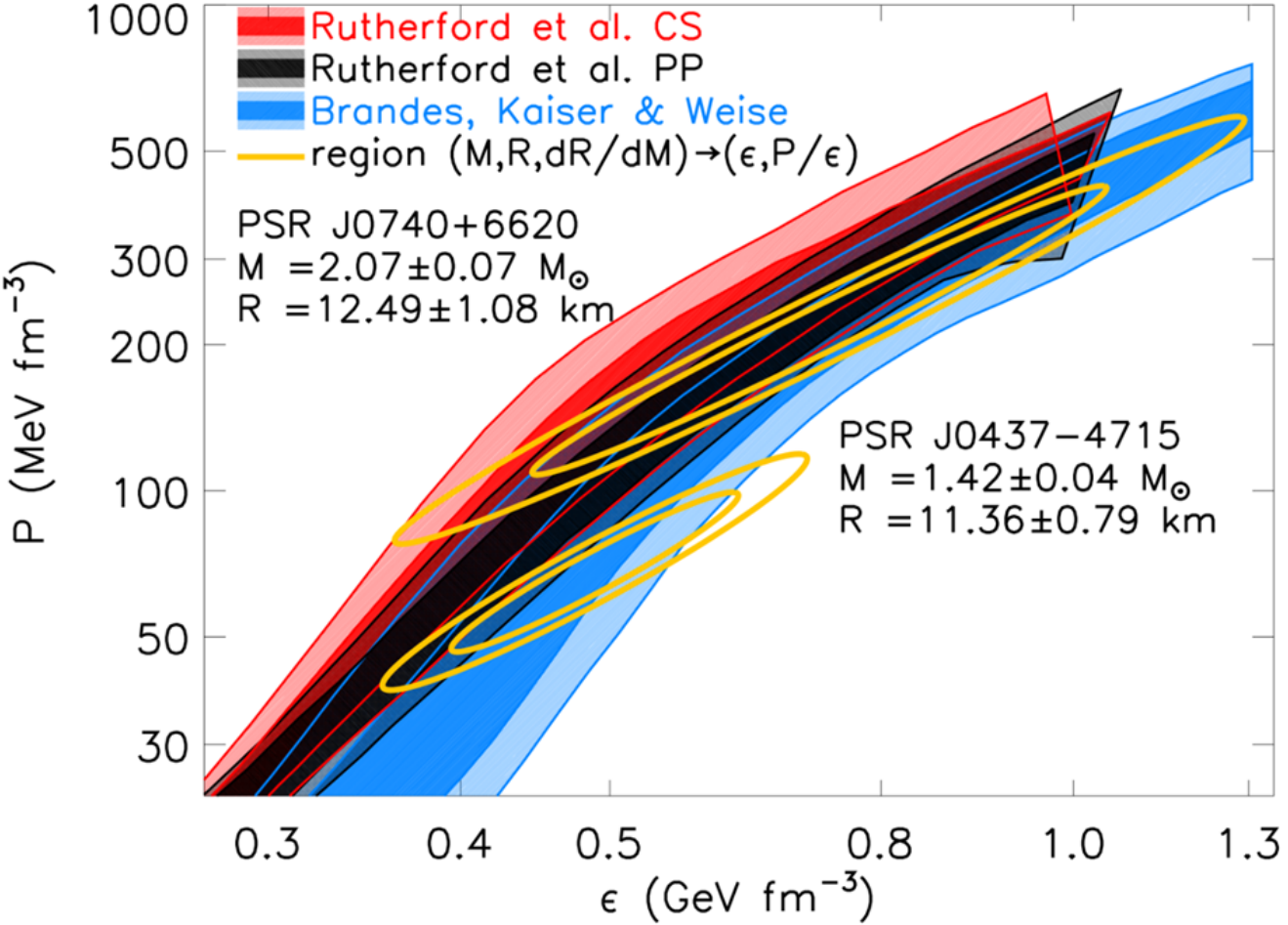
**Radio Pulsar Timing: Moment of Inertia**



**Supernova explosion: Binding energy**

# Background

## From observations to EOS: Bayesian approach



Bayes' Theorem:

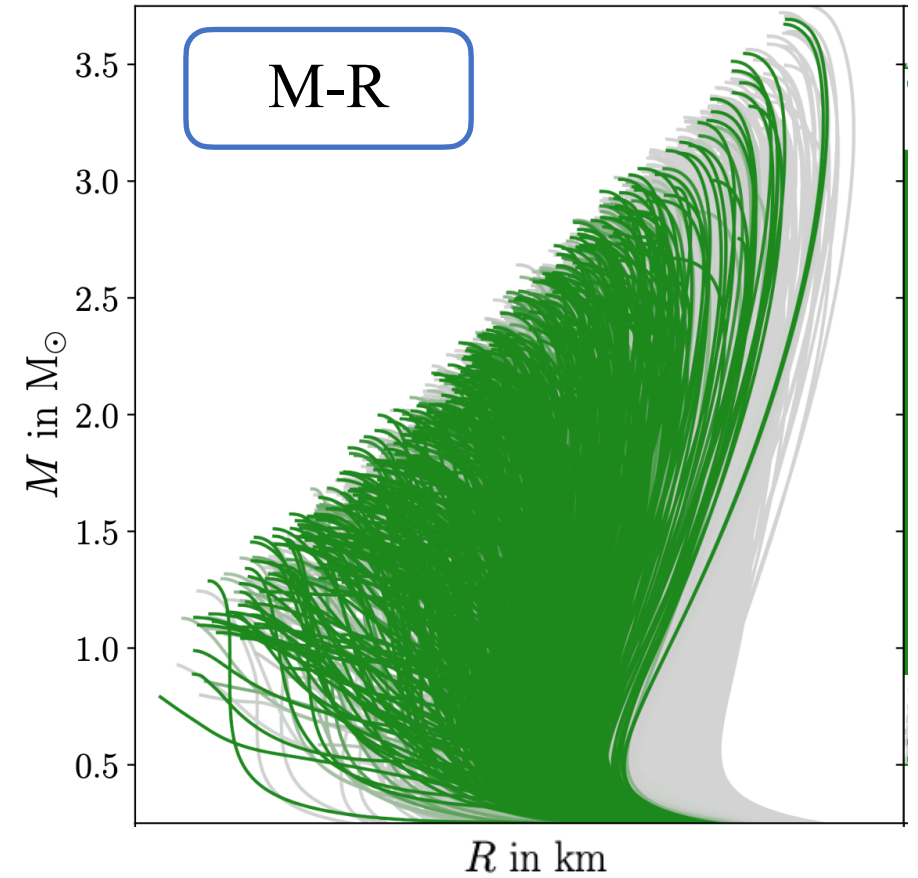
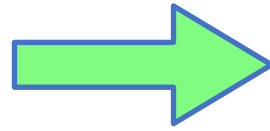
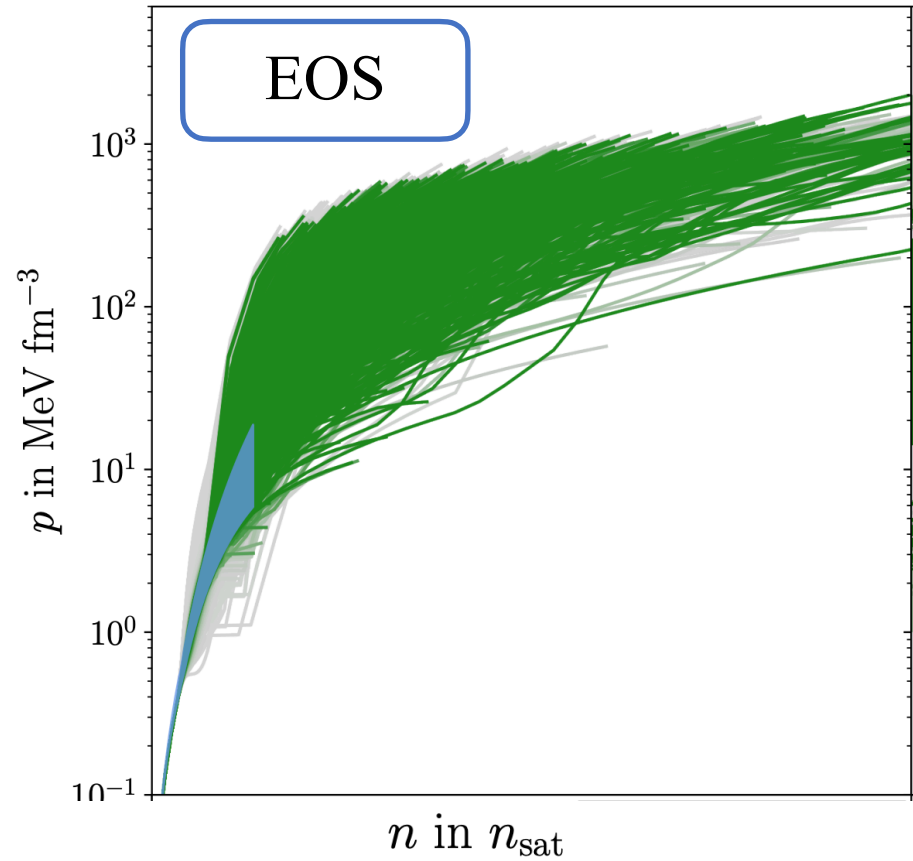
$$\mathcal{P}(\mathcal{M}(\theta, \mathcal{E}) | \mathcal{D}) = \frac{\mathcal{P}(\mathcal{D} | \mathcal{M}(M, R)) \mathcal{P}(\mathcal{M}(\theta, \mathcal{E}))}{\sum \mathcal{P}(\mathcal{D} | \mathcal{M}(M, R)) \mathcal{P}(\mathcal{M}(\theta, \mathcal{E}))}$$

*B. Sun and J. M. Lattimer. Correlations between the Neutron Star Mass–Radius Relation and the Equation of State of Dense Matter. ApJ 984 30 (2025)*

Background

Bayes' Theorem:

$$\mathcal{P}(\mathcal{M}_i(\theta, \mathcal{E}) | \mathcal{D}) = \frac{\mathcal{P}(\mathcal{D} | \mathcal{M}_i(M, R)) \mathcal{P}(\mathcal{M}_i(\theta, \mathcal{E}))}{\sum_j \mathcal{P}(\mathcal{D} | \mathcal{M}_j(M, R)) \mathcal{P}(\mathcal{M}_j(\theta, \mathcal{E}))},$$



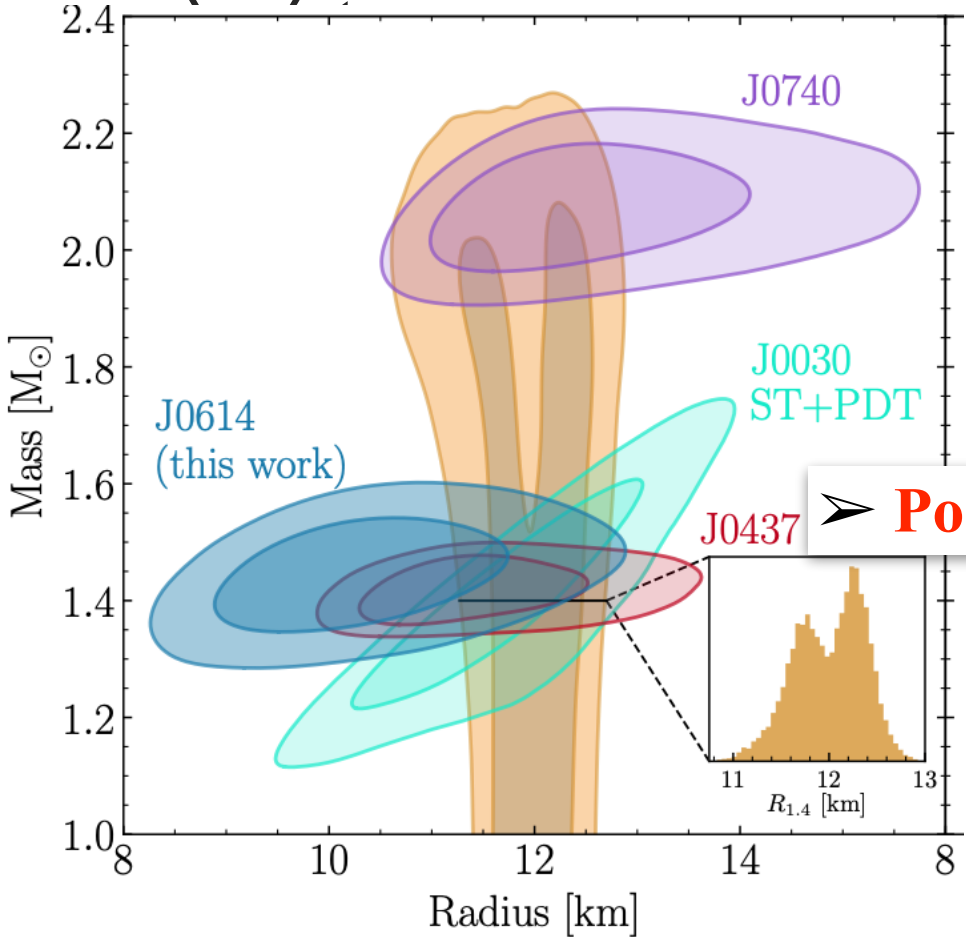
Koehn et al. *Phys. Rev. X* 15, 021014 (2025)

➤ **Prior distribution:  $\mathcal{P}(\mathcal{M}_i(\theta, \mathcal{E}))$ , where  $\mathcal{M}_i(\theta, \mathcal{E})$  refers to a certain model**

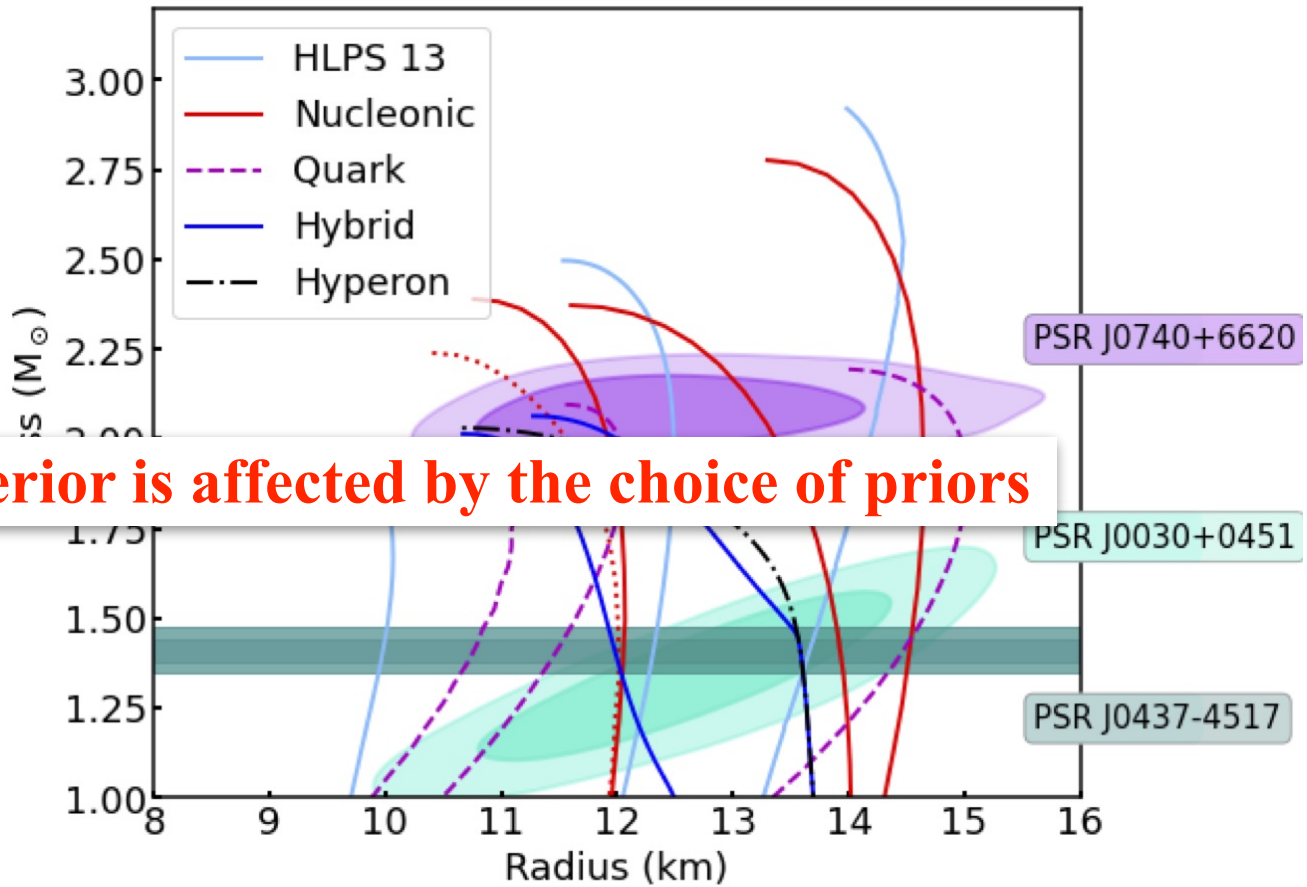
# Background

## Bayes' Theorem:

$$\mathcal{P}(\mathcal{M}_i(\theta, \mathcal{E}) | \mathcal{D}) = \frac{\mathcal{P}(\mathcal{D} | \mathcal{M}_i(M, R)) \mathcal{P}(\mathcal{M}_i(\theta, \mathcal{E}))}{\sum_j \mathcal{P}(\mathcal{D} | \mathcal{M}_j(M, R)) \mathcal{P}(\mathcal{M}_j(\theta, \mathcal{E}))}$$



Mauviard et al. ApJ 995 60 (2025)



➤ **Posterior is affected by the choice of priors**

<https://www.jinaweb.org/news/nicer-measures-radius-most-massive-neutron-star>

➤ **Observational distribution:**  $\mathcal{D}$

➤ **Likelihood:**  $\mathcal{P}(\mathcal{D} | \mathcal{M}_i(M, R))$

## Motivation

**How to define a good prior for Bayesian analysis?**

Let's take a look at **Alan's fish**:

**Two independent observations for the fish:  
8 AM: Alive    8 PM: Dead**

**Question: When did the fish die?**

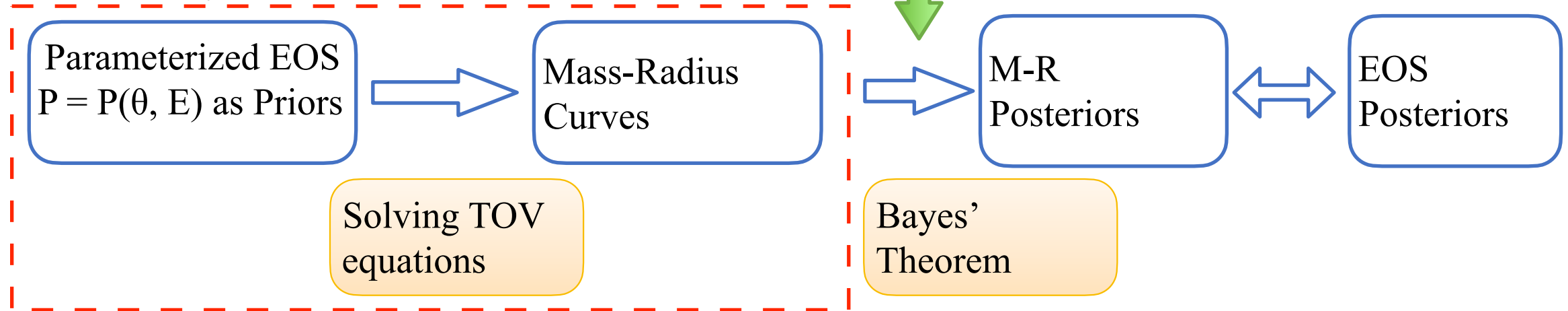
➤ **The ideal prior may uniformly cover time from 8 AM to 8 PM.**



# Motivation

NICER/LIGO constraints

Traditionally,



**Prior and observations are in two different spaces (EOS vs M-R)**

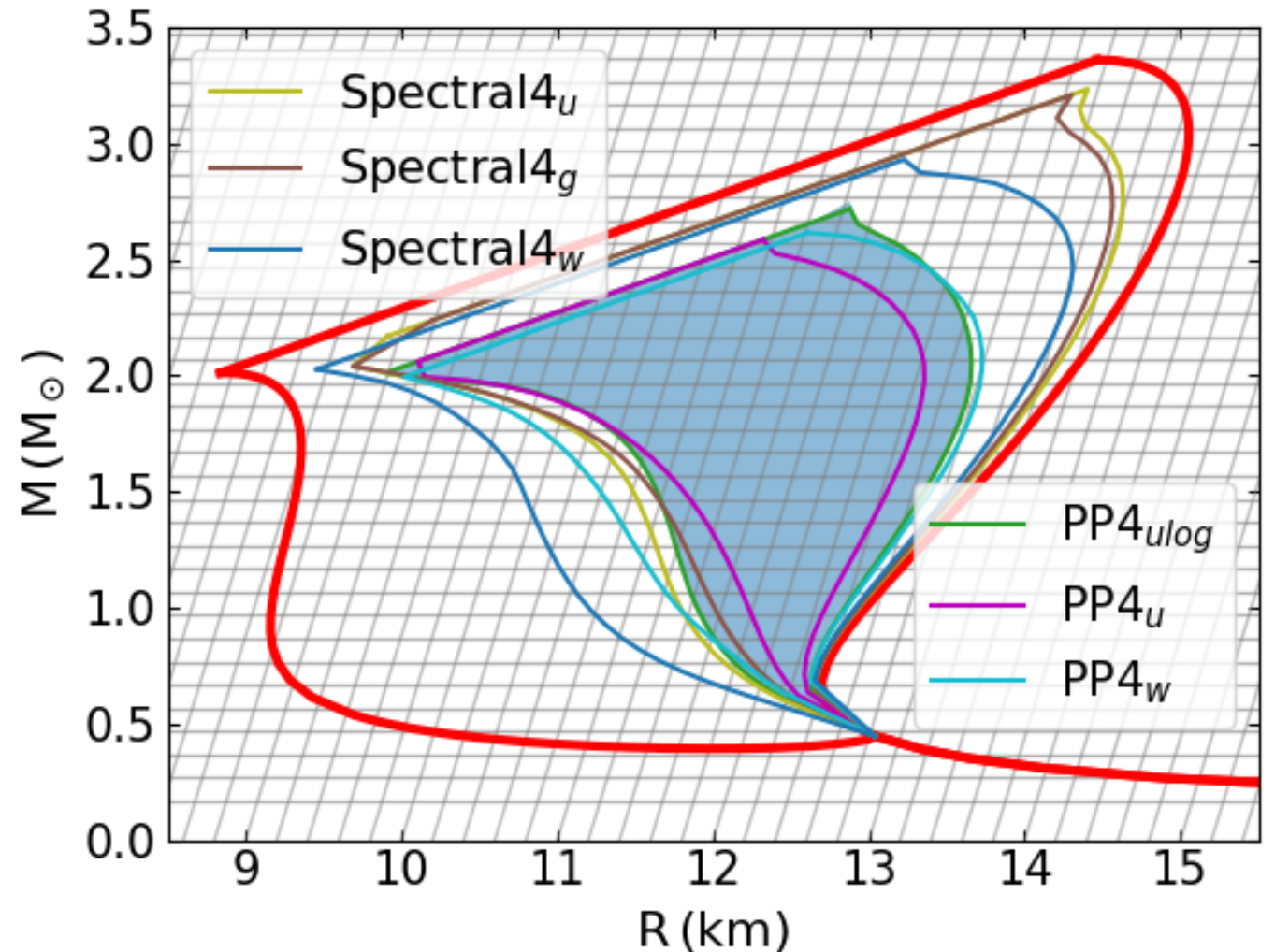
➤ **May have a concentration in M-R space; May be more sensitive to Prior choices...**

## Motivation

**Red boundary:** physically allowed boundary for neutron star M-R curves in terms of causality and thermodynamic stability

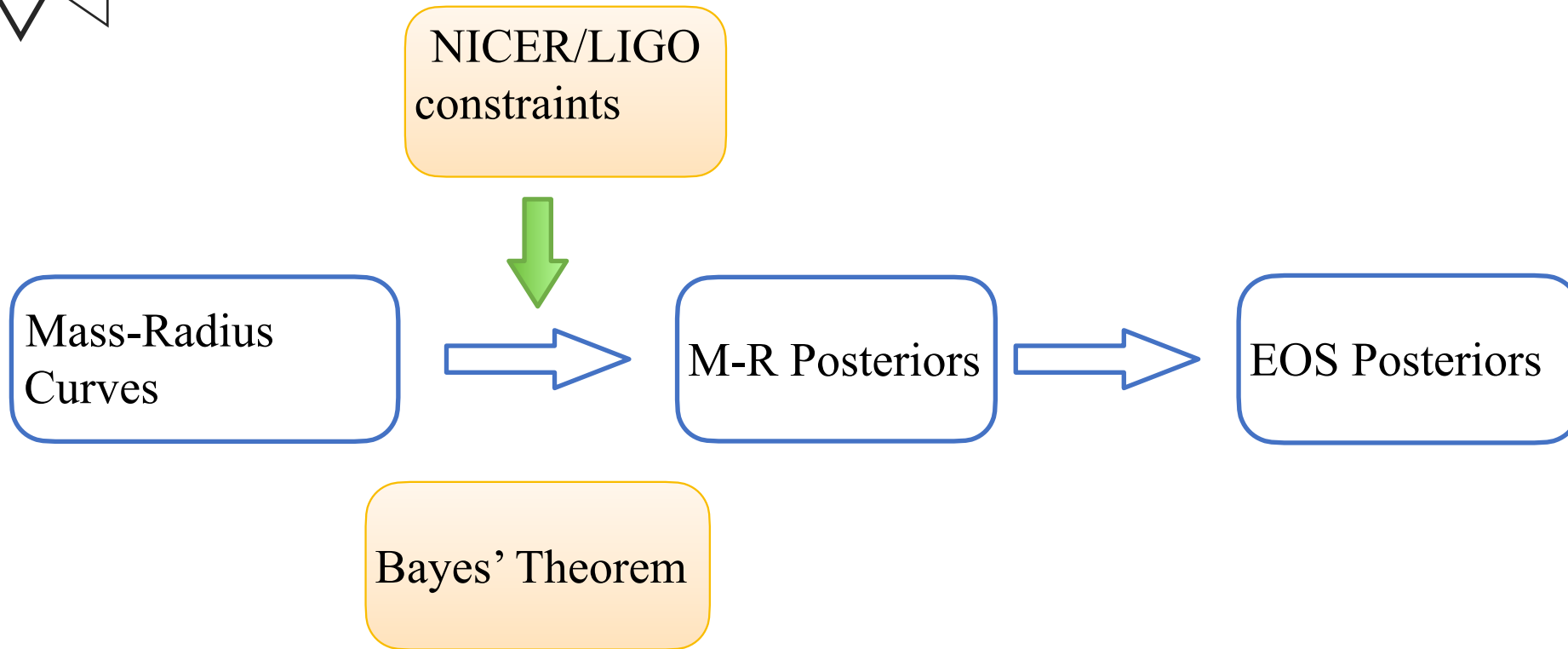
**Boundaries inside with various colors:** different traditional priors

➤ They tend to concentrate in **larger-radius** region



## Motivation

**A more Natural way?**



**Both priors and observations are in M-R space; No need to solve TOV equations**



## Motivation

To accomplish this scheme, two main issues should be solved:

1, How to parameterize M-R curves directly?

2, How to map (M, R) to its underlying (P, E)?



We have developed the direct, highly-accurate inversion formula



## Motivation

**We developed a method fitting with maximum mass and two radii at certain fractional mass points:**

$$G_f = a_{Gf} \left( \frac{M_{max}}{M_{\odot}} \right)^{b_{Gf}} \left( \frac{R_g}{10 \text{ km}} \right)^{c_{Gf}} \left( \frac{R_h}{10 \text{ km}} \right)^{d_{Gf}}$$

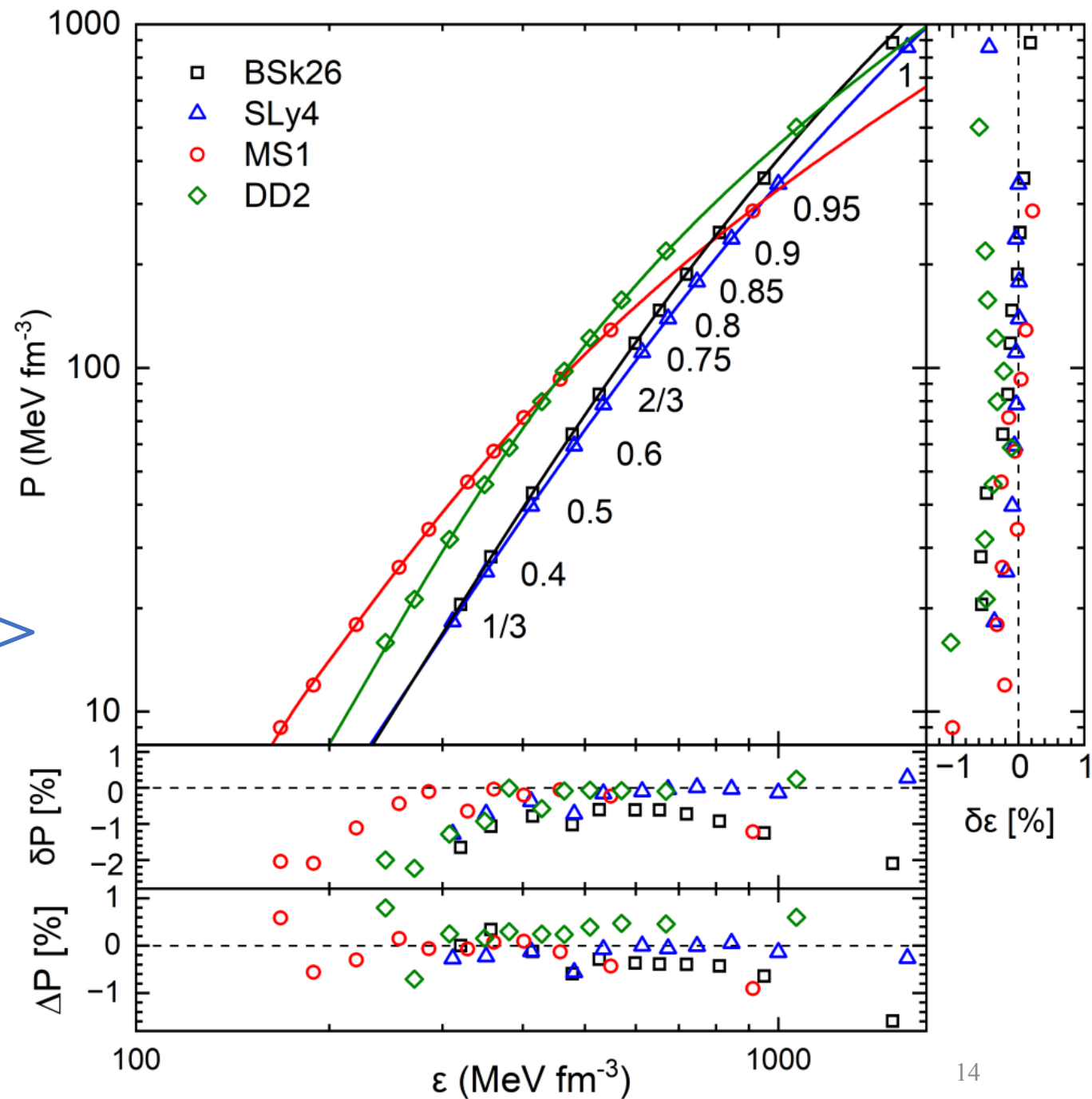
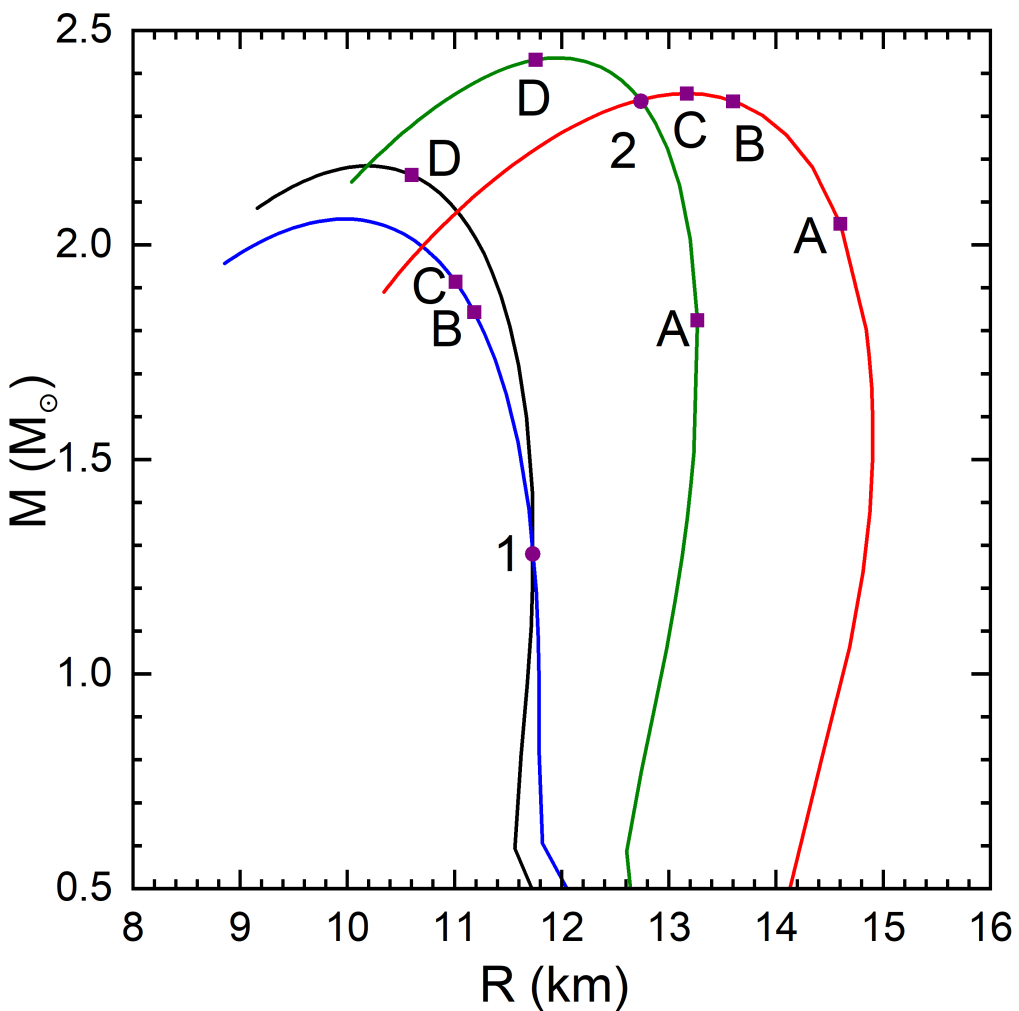
where  $G \in [\mathcal{E}, \text{P}, c_s/c, \mu, n]$

$f \in [1, 0.95, 0.9, 0.85, 0.8, 0.75, 2/3, 3/5, 1/2, 2/5, 1/3]$  is the grid we chose,  
[a, b, c, d, g, h] are fitting parameters (g and h tell which radii to use)

So, matrix of a total of  $6 \cdot 11 = 66$  parameters

**The fitting accuracy (RMS error) is about **0.5%** for both  $\mathcal{E}$  and  $\text{P}$**

# Motivation





## Motivation

Moreover, **the fitting error** should be taken into consideration:

We assumed a **Gaussian-like error**, the **probability density** distribution for EOS is

$$f(\mathcal{E}, P) = \sum_i \frac{\mathcal{P}_i}{2\pi\sigma_{P_i}\sigma_{\mathcal{E}_i}} \exp \left[ -\frac{(\mathcal{E} - \mu_{\mathcal{E}_i})^2}{2\sigma_{\mathcal{E}_i}^2} - \frac{(P - \mu_{P_i})^2}{2\sigma_{P_i}^2} \right],$$

where  $i$  refers to the grid point in one curve.

The total density distribution is the sum of all curves

## PMR method

Now it comes to the main question:

How to parametrize the mass-radius space directly?

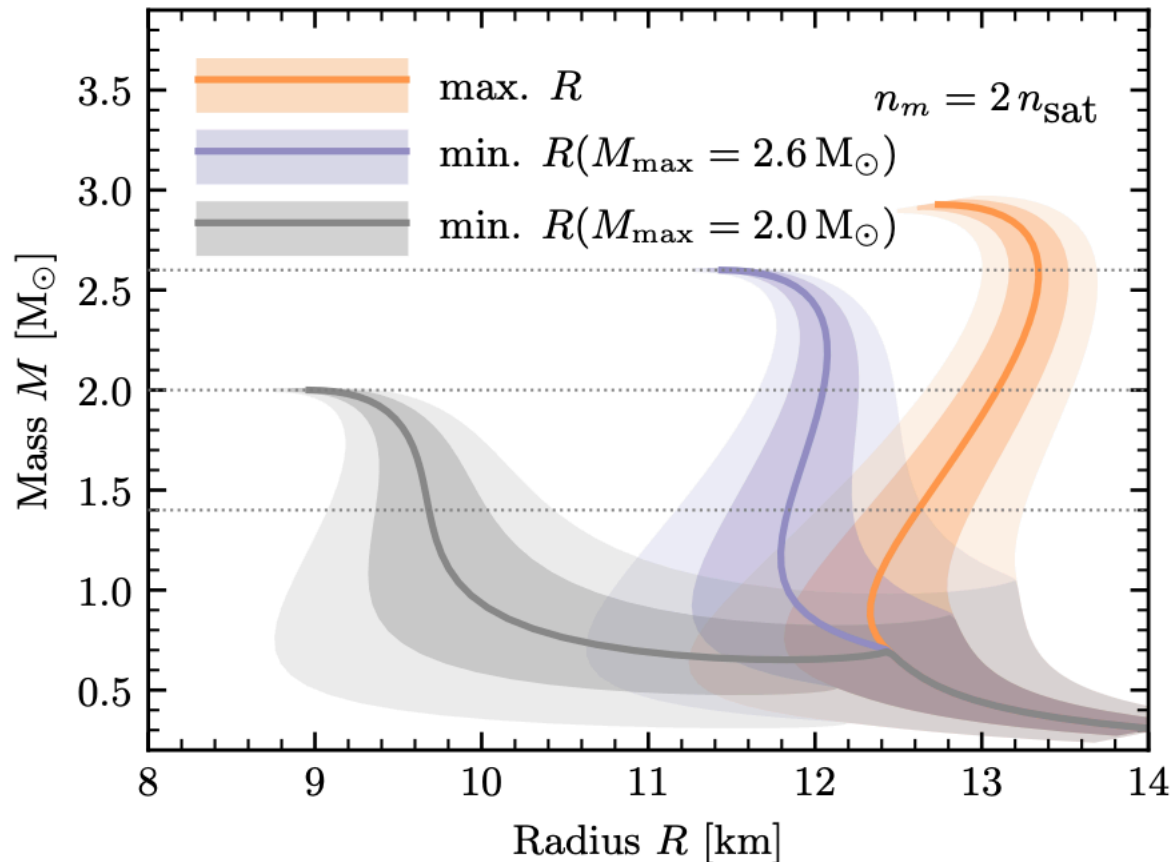


- We propose a simple but effective approach, namely **PMR method (Parameterized Mass-Radius method)**

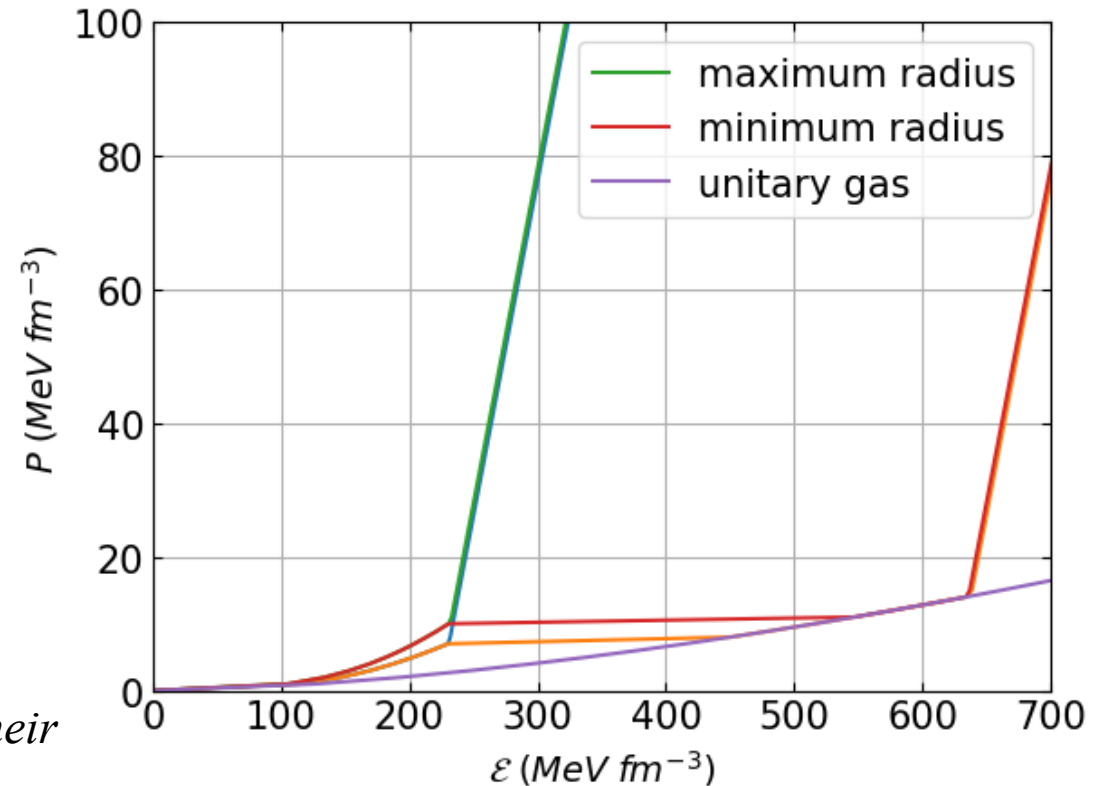
# PMR method

## Step 1: Establishing the M-R boundary

$\chi^{\text{EFT}}$  at  $N^3\text{LO}$  + causal EOS



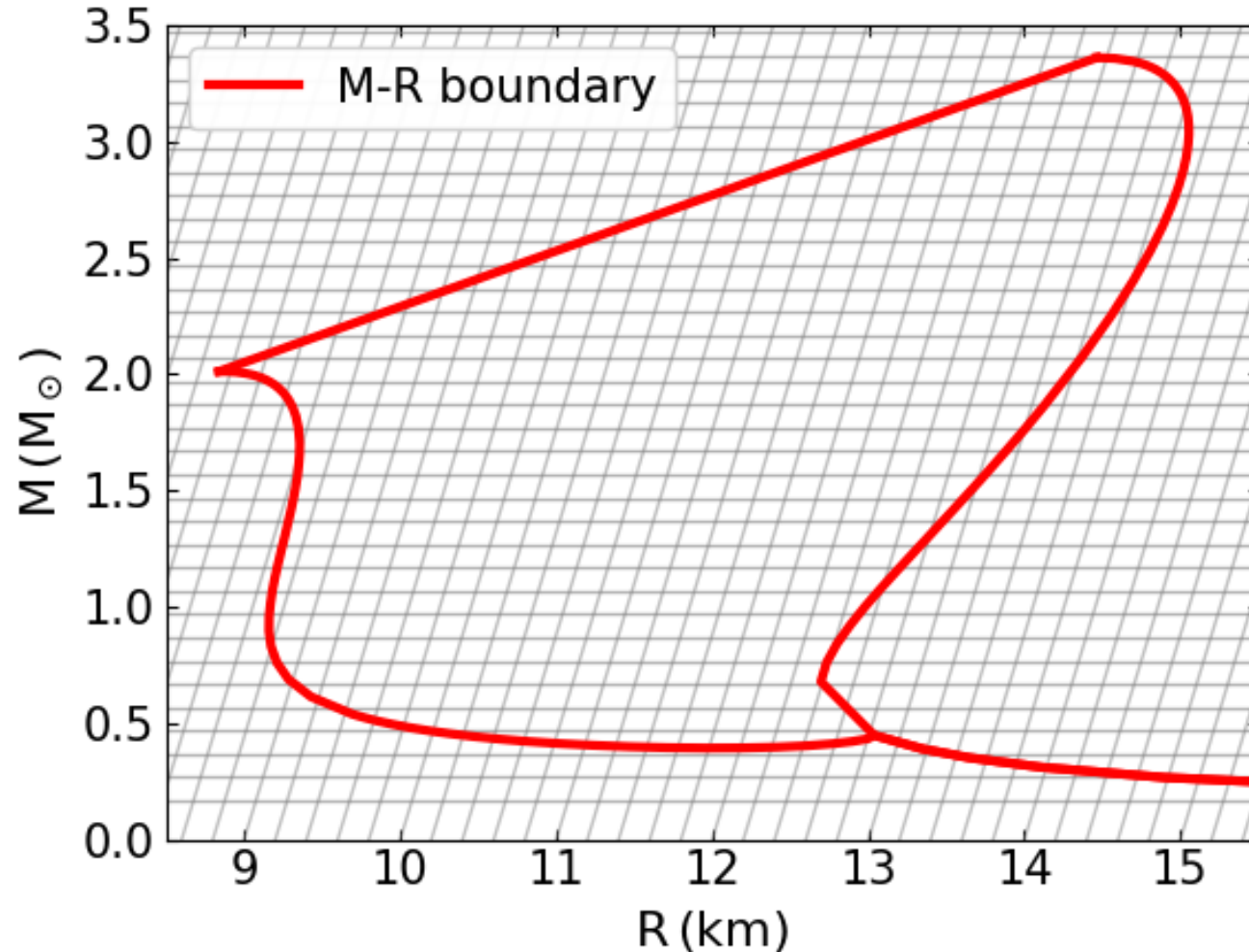
- Right boundary: constrained by causality
- Left boundary: A sharp 1st order phase transition followed by causality, achieving the assumed minimum  $M_{\text{max}}$



*C. Drischer. Limiting masses and radii of neutron stars and their implications, Phys. Rev. C 103, 045808 (2021)*

## PMR method

### Step 2: Constructing the M-R mesh



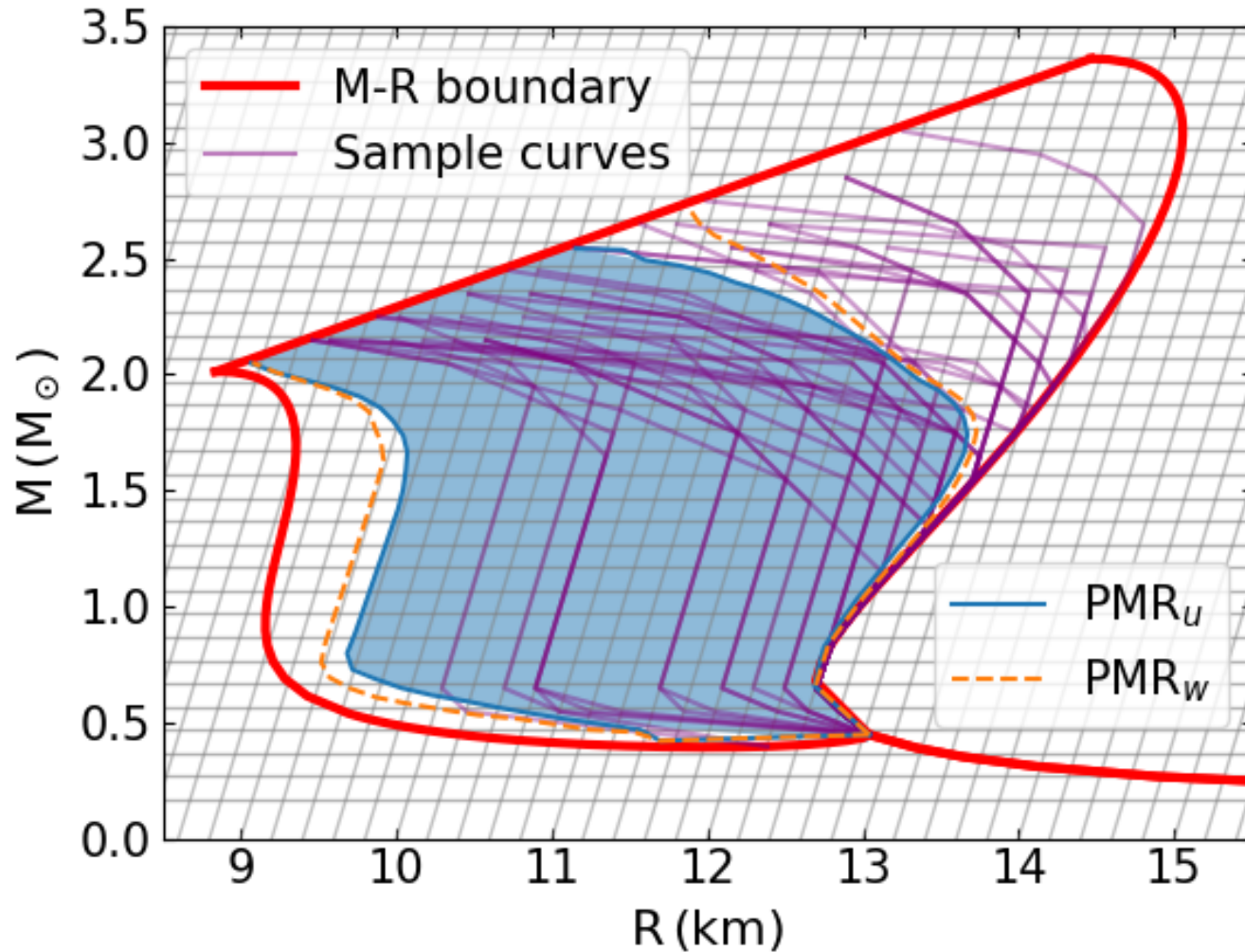
We used SLy4 crust EOS  
+ N3LO central value of 1  
sigma band up to  $1.5 n_s$

A uniform M-R mesh with  
sloped radius lines is  
adopted to improve  
computing efficiency

$$\Delta M = 0.1 M_{\odot},$$
$$\Delta R = 0.2 \text{ km}$$

## PMR method

### Step 3: Generating M-R curves



$\Delta M = +1$  unit;  
extend to the same or  
smaller radial grid lines

Satisfying:

$dR/dM$  non-increasing  
OR  
Along the boundaries

Transition  point

$dR/dM$  non-decreasing  
OR  
Terminate if  $M > 2M_{\odot}$



## PMR method

For comparison, different priors are chosen:

### PMR:

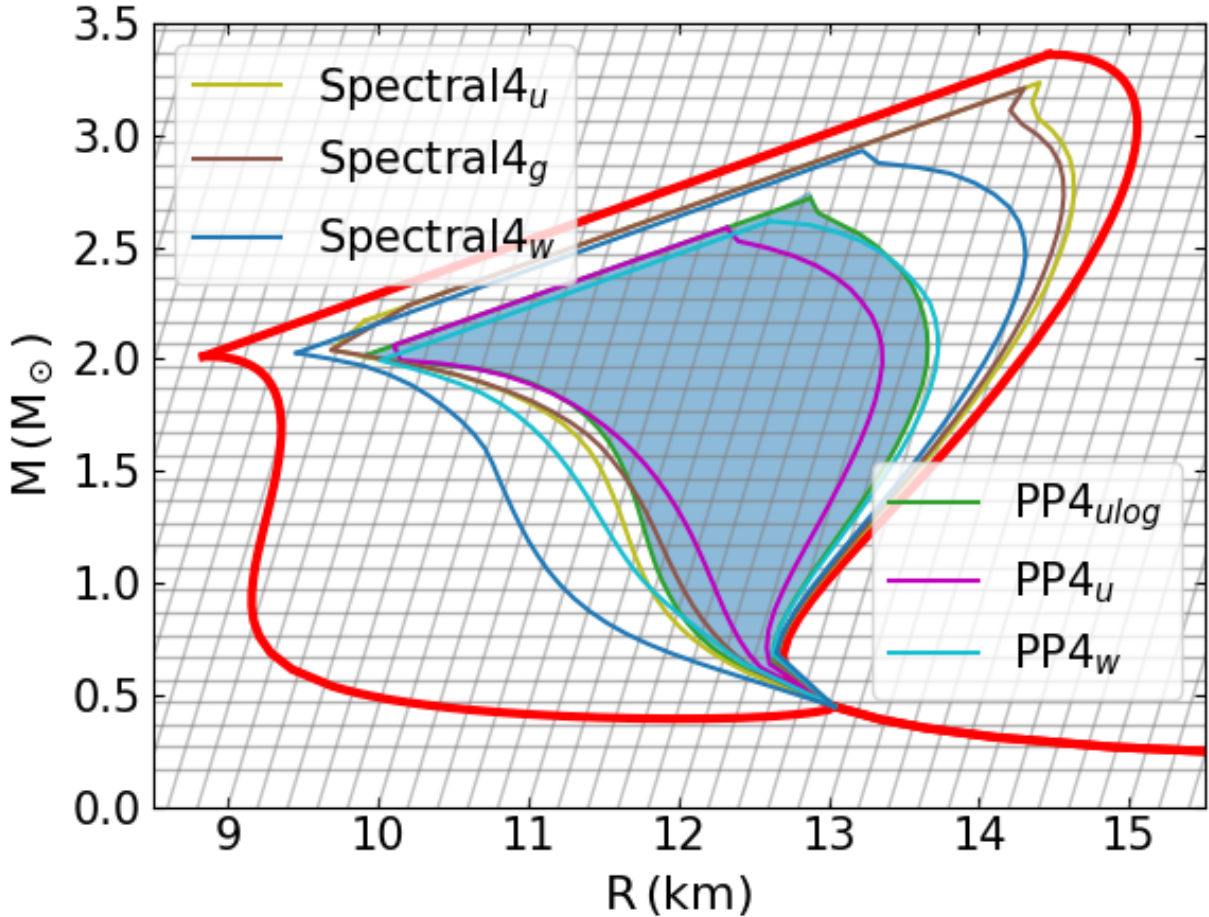
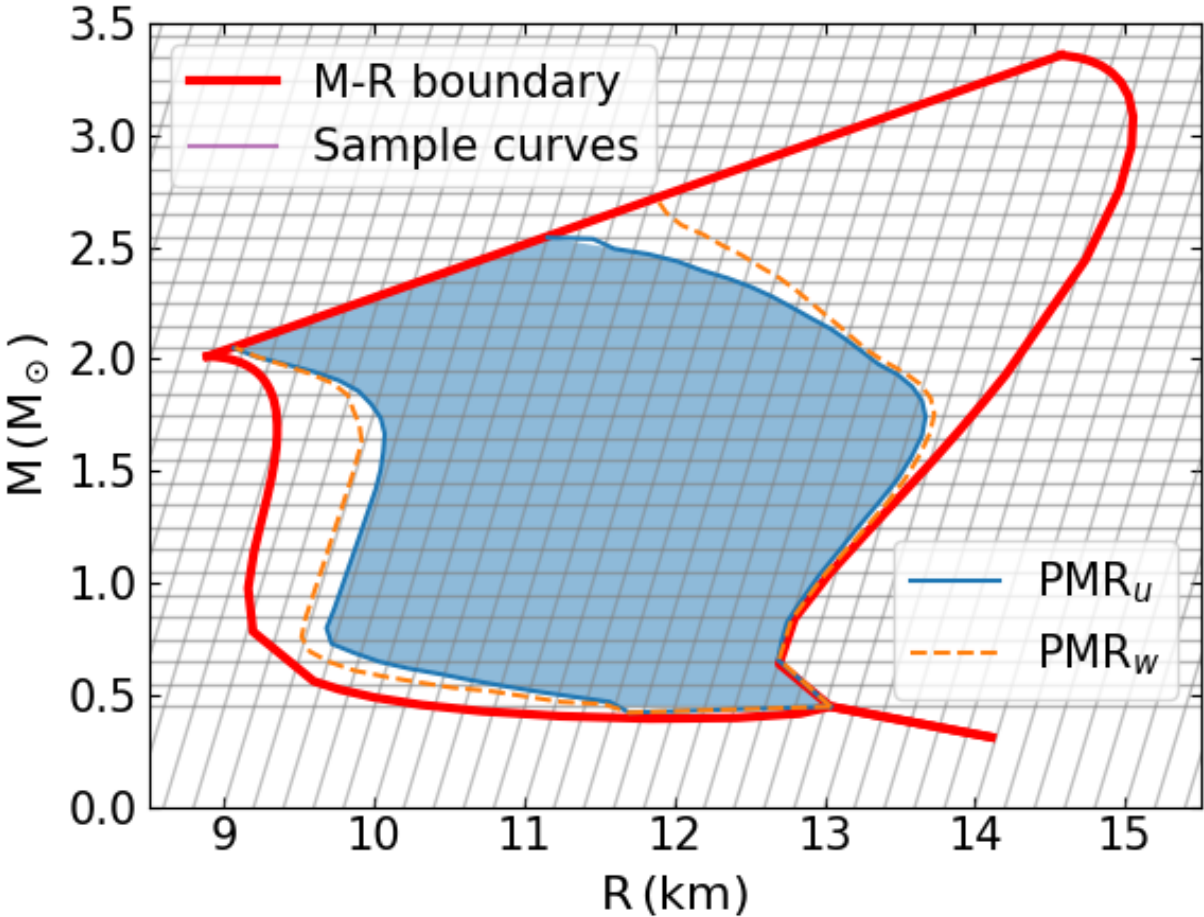
- Uniform sampling in  $M - R$  Space: Generate all curves and sampled randomly (PMR<sub>u</sub>)
- Uniform distribution of  $R_{1.4}$  values: Group curves by  $M_{max}$ , then make  $R_{1.4}$  uniform in each one (PMR<sub>w</sub>)
- Variation of the N3LO boundaries: Upper/center/lower bounds of  $1\sigma$  of N3LO (PMR<sub>p</sub> and PMR<sub>m</sub>)

### Traditional EOS parameterizations:

- 4-parameter Piecewise Polytropic (PP4), choosing parameters uniformly or log-uniformly, or weighted (PP4<sub>u</sub> / PP4<sub>u log</sub> / PP4<sub>w</sub>)
- 4-parameter Spectral representation, choosing parameters uniformly or in Gaussian, or weighed (Spectral4<sub>u</sub> / Spectral4<sub>g</sub> / Spectral4<sub>w</sub>)
- Variation of the N3LO boundaries

# Results

## Prior distributions: PMR vs Tradition methods





## Results

### All Bayesian methods are affected by the choice of priors

We want to examine:

(1). the **relative importance of prior modeling uncertainties** relative to the observational uncertainties ( $\sigma_{prior}/\sigma_{tot}$ )

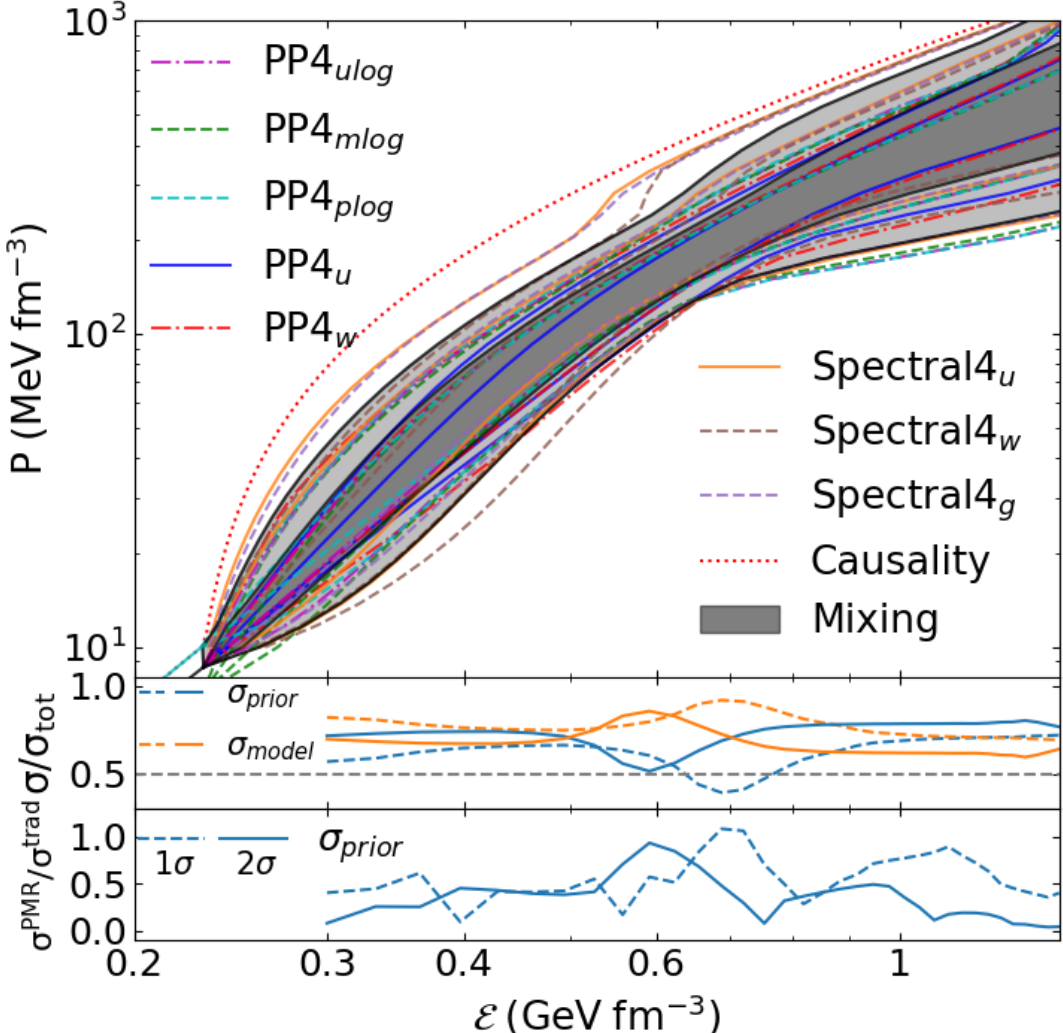
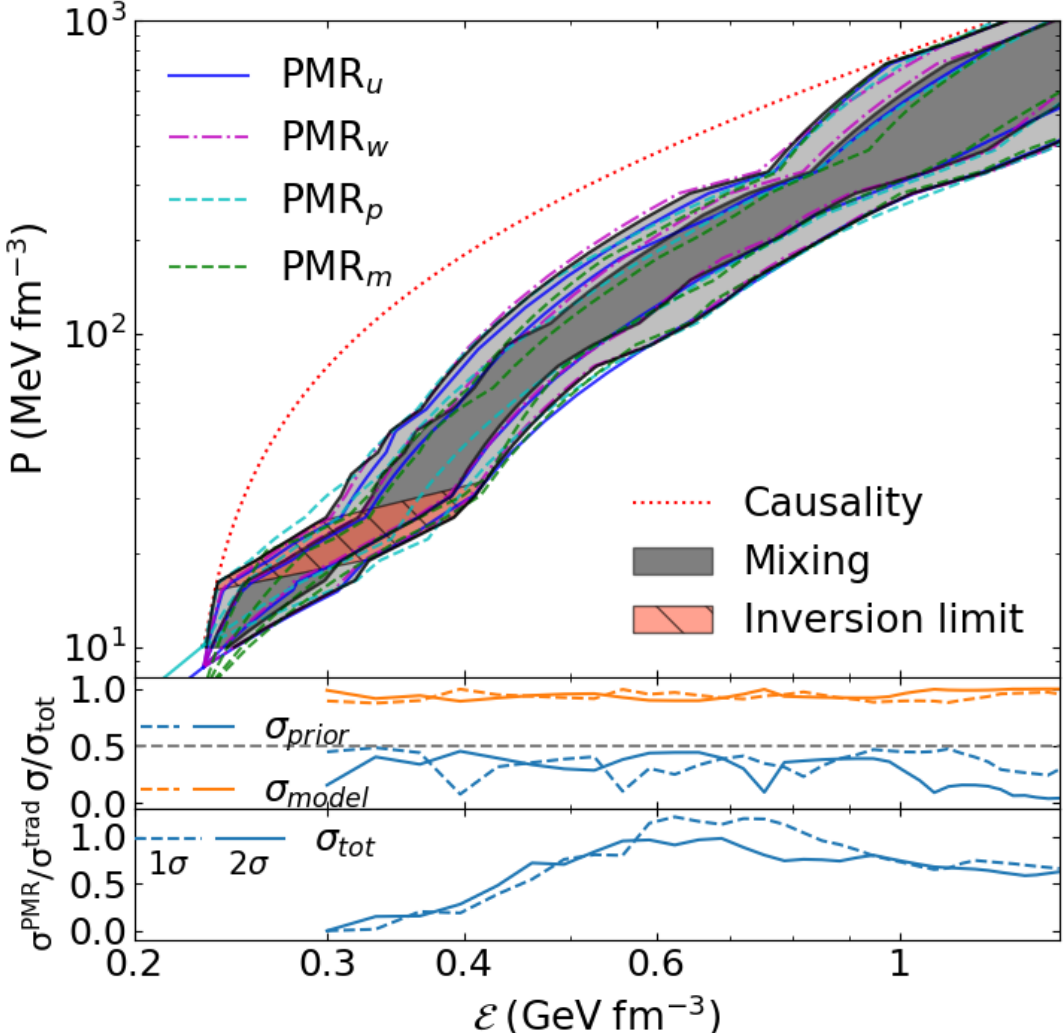
(2). the **relative accuracies** of the two approaches when confronted with the same astrophysical data (**PMR/traditional**)

We define the  $\sigma_{prior}$  by model mixing and

$$\sigma_{tot}^2(\mathcal{E}) = \sigma_{model}^2(\mathcal{E}) + \sigma_{prior}^2(\mathcal{E})$$

# Results

## Posterior distributions: PMR vs Tradition methods





## Conclusion

**We conclude the following potentials of PMR method:**

- 1, Providing a new framework that's **more direct and intuitive** in terms of observations
- 2, **Enhanced computing efficiency** with the current inversion formula
- 3, The **new prior has a lower concentration at large radius region**
- 4, Posteriors exhibit **lower sensitivity to prior assumptions**
- 5, Generally has a **smaller total uncertainty** when confronted with the same observational data



## Outlook

### **We are working on**

Using PMR method in the M-R space only to get posterior as updated M-R distribution

Then, combining with traditional Bayesian approaches to deal with the EOS inference

In short, this is basically a two-step Bayesian iteration process, and we want to see what will happen



## Outlook

**In a nutshell,**

**We proposed a new idea to do Bayesian analysis to infer neutron star EOS.**

**Hopefully there will be many more studies following this natural framework.**

<https://arxiv.org/abs/2601.04294>

THANK YOU

