INSTITUTE FOR NUCLEAR THEORY

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Virial theorem and nucleon mass structure

Based on [C.L., Metz, Pasquini, Rodini, JHEP11 (2021) 121]

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June 14, 2022, INT, Seattle, USA



- What is the virial theorem ?
- What is its physical meaning?
- What is its relation to mass?



[Clausius, PM40 (1870) 122] [Goldstein, *Classical Mechanics* (1980)]



 $\vec{P} = \sum_k \vec{p_k}$

 $G = \sum_{k} \vec{p_k} \cdot \vec{r_k}$

[Clausius, PM40 (1870) 122] [Goldstein, *Classical Mechanics* (1980)]



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Time average $\llbracket O \rrbracket \equiv \lim_{\tau \to \infty} \frac{1}{\tau} \int_0^\tau dt \, O(t)$



[Clausius, PM40 (1870) 122] [Goldstein, *Classical Mechanics* (1980)]







Vis (latin): force, energy, power

[Clausius, PM40 (1870) 122] [Goldstein, *Classical Mechanics* (1980)]





 $\mathcal{T} = \frac{1}{2} \sum_{k} m_{k} \vec{v}_{k}^{2}$ $\mathbf{\mathcal{T}} = -\frac{1}{2} \sum_{k} \left[\vec{F}_{k} \cdot \vec{r}_{k} \right]$ $= \frac{n}{2} \left[\mathcal{V} \right]$ $\vec{F}_{k} = -\frac{\partial \mathcal{V}}{\partial \vec{r}_{k}}, \quad \mathcal{V} \propto |\vec{r}_{i} - \vec{r}_{j}|^{n}$ \mathbf{Virial}

Vis (latin): force, energy, power



Ideal gas

 $-\frac{1}{2}\sum_k \left[\!\!\left[\vec{F}_k\cdot\vec{r}_k\right]\!\!\right] = \frac{1}{2}\int p\,\mathrm{d}\vec{S}\cdot\vec{r}$ Container

[Schectman, Good, AJP25 (1957) 219]

[Schectman, Good, AJP25 (1957) 219] ideal gas $-\frac{1}{2} \sum_{k} [[\vec{F}_{k} \cdot \vec{r}_{k}]] = \frac{1}{2} \int p \, d\vec{S} \cdot \vec{r}$ $= \frac{1}{2} p \int d^{3}r \, \vec{\nabla} \cdot \vec{r}$



[Schectman, Good, AJP25 (1957) 219]



Virial theorem
$$\llbracket \mathcal{T} \rrbracket = \frac{3}{2} pV$$

Equipartition
$$\llbracket \mathcal{T} \rrbracket = \frac{3}{2} N k_B T$$



Virial theorem
$$\llbracket \mathcal{T} \rrbracket = \frac{3}{2} pV$$
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theorem $\llbracket \mathcal{T} \rrbracket = \frac{3}{2} Nk_BT$

[Born, Heisenberg, Jordan, ZP35 (1926) 557] [Killingbeck, AJP38 (1970) 590]



Erhenfest theorem

$$\vec{P} = \sum_{k} \vec{p_k}$$
 $G = \sum_{k} \vec{p_k} \cdot \vec{r_k}$

$$rac{\mathrm{d}}{\mathrm{d}t}\langle G
angle = rac{1}{i}\langle [G,H]
angle \qquad H = \sum_k rac{ec{p}_k^2}{2m_k} + \mathcal{V}(\{ec{r}_k\})$$

 $\overline{}$

[Born, Heisenberg, Jordan, ZP35 (1926) 557] [Killingbeck, AJP38 (1970) 590]



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 $\vec{P} = \sum_{k} \vec{p_k} \qquad \qquad G = \sum_{k} \vec{p_k} \cdot \vec{r_k}$

$$= 2\langle \mathcal{T} \rangle - \sum_{k} \langle \vec{r}_k \cdot \frac{\partial}{\partial \vec{r}_k} \mathcal{V} \rangle$$

[Born, Heisenberg, Jordan, ZP35 (1926) 557] [Killingbeck, AJP38 (1970) 590]



$$\vec{P} = \sum_{k} \vec{p}_{k} \qquad G = \sum_{k} \vec{p}_{k} \cdot \vec{r}_{k}$$
nfest
$$\frac{d}{dt} \langle G \rangle = \frac{1}{i} \langle [G, H] \rangle \qquad H = \sum_{k} \frac{\vec{p}_{k}^{2}}{2m_{k}} + \mathcal{V}(\{\vec{r}_{k}\})$$

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Normalizable stationary state

$$H|\Psi\rangle = E|\Psi\rangle \quad \Rightarrow \quad \frac{\mathrm{d}}{\mathrm{d}t}\langle C$$

$$\frac{\mathrm{d}}{\mathrm{d}t}\langle G\rangle = 0$$

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angle \qquad = rac{n}{2} \langle \mathcal{V}
angle \qquad \mathcal{V} \propto |ec{r_i} - ec{r_j}|^r$$

[Born, Heisenberg, Jordan, ZP35 (1926) 557] [Killingbeck, AJP38 (1970) 590]



$$=\sum_{k}\vec{p_{k}} \qquad \qquad G=\sum_{k}\vec{p_{k}}\cdot\vec{r_{k}}$$

Erhenfest theorem

 \vec{P}

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$$\blacktriangleright \qquad \langle \mathcal{T} \rangle = \frac{1}{2} \sum_{k} \langle \vec{r_k} \cdot \frac{\partial}{\partial \vec{r_k}} \mathcal{V} \rangle \qquad = \frac{n}{2} \langle \mathcal{V} \rangle \qquad \qquad \mathcal{V} \propto |\vec{r_i} - \vec{r_j}|^n$$

<u>NB:</u> • For a superposition of stationary states, one also averages over time $\left\|\frac{\mathrm{d}\langle G\rangle}{\mathrm{d}t}\right\| = 0$ • The system is *at rest* since $\frac{\mathrm{d}}{\mathrm{d}t}\langle \vec{R}_{\mathrm{CM}}\rangle = \vec{0}$

[Fock, ZP63 (1930) 855] [Lucha, Schöberl, PRL64 (1990) 2733]



$$G = \sum_k \vec{p_k} \cdot \vec{r_k}$$
 generates spatial dilatations

$$U_D^{-1}\vec{r}_k U_D = \lambda \vec{r}_k, \qquad U_D^{-1}\vec{p}_k U_D = \lambda^{-1}\vec{p}_k \qquad U_D = e^{-i\kappa G}$$

$$\lambda = e^{\kappa}$$

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Variational approach $E(\kappa) \equiv \langle \Psi_{\kappa} | H | \Psi_{\kappa} \rangle = \langle \Psi | U_D^{-1} H U_D | \Psi \rangle$ $| \Psi_{\kappa} \rangle = U_D | \Psi \rangle$

 $|\Psi\rangle$ is a stationary state with eigenvalue E=E(0) if

$$\frac{\partial E}{\partial \kappa}(0) = \langle \Psi | \frac{\partial (U_D^{-1} H U_D)}{\partial \kappa} \bigg|_{\kappa=0} |\Psi\rangle = 0$$

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$$= i[G, H] = -\frac{\mathrm{d}G}{\mathrm{d}t}$$

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NB: Bag-like models use this variational approach to determine the mass of the system

[Landau, Lifshitz, *The Classical Theory of Fields* (1951)] [Deser, PLB64 (1976) 463] [Dudas, Pirjol, PLB260 (1991) 186] [C.L., Metz, Pasquini, Rodini, JHEP11 (2021) 121]



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$$G = \sum_{k} \vec{p}_{k} \cdot \vec{r}_{k} \quad \Longrightarrow \quad \int \mathrm{d}^{3}x \, T^{0i} x^{i}$$

$$\frac{\mathrm{d}G}{\mathrm{d}t} = \int \mathrm{d}^3 x \,\partial_0 T^{0i} x^i$$

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$$\frac{\mathrm{d}G}{\mathrm{d}t} = \int \mathrm{d}^3 x \,\partial_0 T^{0i} x^i$$
$$= \int \mathrm{d}^3 x \,(\partial_\mu T^{\mu i}) x^i - \int \mathrm{d}^3 x \,(\partial_k T^{ki}) x^i$$

[Landau, Lifshitz, *The Classical Theory of Fields* (1951)] [Deser, PLB64 (1976) 463] [Dudas, Pirjol, PLB260 (1991) 186] [C.L., Metz, Pasquini, Rodini, JHEP11 (2021) 121]

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$$\begin{aligned} \frac{\mathrm{d}G}{\mathrm{d}t} &= \int \mathrm{d}^3 x \,\partial_0 T^{0i} x^i \\ &= \int \mathrm{d}^3 x \,(\partial_\mu T^{\mu i}) x^i - \int \mathrm{d}^3 x \,(\partial_k T^{ki}) x^i \\ &= \int \mathrm{d}^3 x \,\vec{\mathcal{F}} \cdot \vec{x} + \sum_i \int \mathrm{d}^3 x \,T^{ii} \end{aligned}$$

Four-force density $\mathcal{F}^{\nu} \equiv \partial_{\mu} T^{\mu\nu}$

[Landau, Lifshitz, *The Classical Theory of Fields* (1951)] [Deser, PLB64 (1976) 463] [Dudas, Pirjol, PLB260 (1991) 186] [C.L., Metz, Pasquini, Rodini, JHEP11 (2021) 121]

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Four-force density $\mathcal{F}^{\nu} \equiv \partial_{\mu}T^{\mu\nu}$

Classical

$$\left[\!\left[\sum_{i} \int \mathrm{d}^{3}x \, T^{ii} \,\right]\!\right] = -\left[\!\left[\int \mathrm{d}^{3}x \, \vec{\mathcal{F}} \cdot \vec{x} \,\right]\!\right]$$

Quantum (stationary state)

$$\left\langle \sum_{i} \int \mathrm{d}^{3}x \, T^{ii} \right\rangle = -\left\langle \int \mathrm{d}^{3}x \, \vec{\mathcal{F}} \cdot \vec{x} \right\rangle$$

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$$\begin{split} \frac{\mathrm{d}G}{\mathrm{d}t} &= \int \mathrm{d}^3 x \, \partial_0 T^{0i} x^i \\ &= \int \mathrm{d}^3 x \, (\partial_\mu T^{\mu i}) x^i - \int \mathrm{d}^3 x \, (\partial_k T^{ki}) x^i \\ &= \int \mathrm{d}^3 x \, \vec{\mathcal{F}} \cdot \vec{x} + \sum_i \int \mathrm{d}^3 x \, T^{ii} \end{split} \quad \qquad \text{Foundation}$$

our-force
$${\cal F}^
u\equiv \partial_\mu T^{\mu
u}$$

Classical

$$\left[\left[\sum_{i} \int \mathrm{d}^{3}x \, T^{ii}\right]\right] = -\left[\left[\int \mathrm{d}^{3}x \, \vec{\mathcal{F}} \cdot \vec{x}\right]\right] \qquad = 0$$

Isolated system (von Laue condition)

Quantum (stationary state)

$$\left\langle \sum_{i} \int \mathrm{d}^{3}x \, T^{ii} \right\rangle = -\left\langle \int \mathrm{d}^{3}x \, \vec{\mathcal{F}} \cdot \vec{x} \right\rangle \qquad = 0$$

Physical interpretation $\vec{x} \mapsto (1 + \delta \kappa) \vec{x}$



$$\delta H = \frac{1}{i} \left[H, G \right] \delta \kappa = -\frac{\mathrm{d}G}{\mathrm{d}t} \, \delta \kappa$$

 $\delta H = -\delta W$

Physical interpretation $\vec{x} \mapsto (1 + \delta \kappa) \vec{x}$



$$\delta H = -\delta W$$

$$\delta H = \frac{1}{i} [H, G] \,\delta \kappa = -\frac{\mathrm{d}G}{\mathrm{d}t} \,\delta \kappa$$

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Physical interpretation $\vec{x} \mapsto (1 + \delta \kappa) \vec{x}$ $\delta H = -\delta W$ $\delta H = \frac{1}{i} [H, G] \, \delta \kappa = -\frac{\mathrm{d}G}{\mathrm{d}t} \, \delta \kappa$ $\delta W = \frac{\mathrm{d}G}{\mathrm{d}t} \, \delta \kappa$

$$= \int \mathrm{d}^3 x \frac{\partial_0 T^{0i}}{\underset{\text{force}}{\overset{\text{Local}}{\overset{\text{force}}{\overset{force}{\overset{force}}{\overset{force}{\overset{force}}{\overset{force}{\overset{force}}{\overset{force}}{\overset{force}{\overset{force}}{\overset{force}{\overset{force}}{\overset{force}{\overset{force}{\overset{force}}{\overset{force}}{\overset{force}{\overset{force}}{\overset{force}{\overset{force}}{\overset{force}}{\overset{force}{\overset{force}}{\overset{force}{\overset{force}}{\overset{force}}{\overset{force}{\overset{force}}{\overset{force}{\overset{force}}{\overset{force}}{\overset{force}}{\overset{force}}{\overset{force}}{\overset{force}{\overset{force}}{\overset{force}}{\overset{force}}{\overset{force}}{\overset{force}{\overset{force}}{\overset{force}}{\overset{force}{\overset{force}}{\overset{force}}{\overset{force}}{\overset{force}}{\overset{force}}{\overset{force}{\overset{force}}{\overset{force}}{\overset{force}{\overset{force}}{\overset{force}{\overset{force}}{\overset{force}}{\overset{force}{\overset{force}}{\overset{force}}{\overset{force}}{\overset{force}}{\overset{force}{\overset{force}}{\overset{force}{\overset{force}}{\overset{force}}{\overset{force}}{\overset{force}}{\overset{force}}{\overset{force}{\overset{force}}{\overset{force}}{\overset{force}}{\overset{force}}{\overset{force}{\overset{force}}{\overset{for$$

$$\begin{split} \delta \vec{x} &= \delta \kappa \, \vec{x} \\ \delta (\mathrm{d}^3 x) &= 3 \delta \kappa \, \mathrm{d}^3 x \end{split}$$

Physical interpretation $\vec{x} \mapsto (1 + \delta \kappa) \vec{x}$ $\delta H = -\delta W$ $\delta H = \frac{1}{i} [H, G] \, \delta \kappa = -\frac{\mathrm{d}G}{\mathrm{d}t} \, \delta \kappa$ $= \int \mathrm{d}^3 x \, \partial_0 T^{0i} \delta x^i$ $\delta \vec{x} = \delta \kappa \vec{x}$ $\delta (\mathrm{d}^3 x) = 3\delta \kappa \, \mathrm{d}^3 x$

$$= \int \mathrm{d}^3 x \, \vec{\mathcal{F}} \cdot \delta \vec{x} + \int \delta (\mathrm{d}^3 x) \, \frac{1}{3} \sum_i T^{ii}$$

Work on the system

force





Generalization to spacetime dilatations $j_D^{\mu} = T^{\mu\nu} x_{\nu}$

$$D = \int \mathrm{d}^3 x \, j_D^0 = Ht - G$$

$$e^{i\kappa D}\phi(x)e^{-i\kappa D} = e^{\kappa d_{\phi}}\phi(e^{\kappa}x) \qquad \qquad H = \int d^3x \, T^{00}$$

$$\Leftrightarrow \quad \frac{1}{i} \left[\phi(x), D\right] = (x_{\mu}\partial^{\mu} + d_{\phi})\phi(x) \qquad \qquad G = \int d^3x \, T^{0i}x^i$$

Generalization to spacetime dilatations

 $j_D^\mu = T^{\mu\nu} x_\nu$

n

$$D = \int d^3x \, j_D^0 = Ht - G \qquad \qquad \begin{aligned} e^{i\kappa D}\phi(x)e^{-i\kappa D} &= e^{\kappa d_\phi}\phi(e^\kappa x) & H = \int d^3x \, T^{00} \\ \Leftrightarrow \quad \frac{1}{i}\left[\phi(x), D\right] &= (x_\mu\partial^\mu + d_\phi)\phi(x) & G = \int d^3x \, T^{0i}x^i \end{aligned}$$

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Generalization to spacetime dilatations

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 $\langle H \rangle = \left\langle \frac{\mathrm{d}D}{\mathrm{d}t} \right\rangle$

theorem $\frac{\mathrm{d}H}{\mathrm{d}t} = \frac{\partial H}{\partial t} = 0$

Virial

Temporal rescaling

$$= \langle H \rangle - \left\langle \frac{\mathrm{d}G}{\mathrm{d}t} \right\rangle$$

$$\frac{\mathrm{d}G}{\mathrm{d}t} = \sum_{i} \int \mathrm{d}^{3}x \, T^{ii} + \int \mathrm{d}^{3}x \, \vec{\mathcal{F}} \cdot \vec{x}$$

 $\frac{\mathrm{d}D}{\mathrm{d}t} = \int \mathrm{d}^3 x \, T^{\mu}_{\ \mu} + \int \mathrm{d}^3 x \, \mathcal{F}^{\mu} x_{\mu}$

Virial

theorem

 $\frac{\mathrm{d}H}{\mathrm{d}t} = \frac{\partial H}{\partial t} = 0$

Generalization to spacetime dilatations

 $j^{\mu}_{D} = T^{\mu\nu} x_{\nu}$

$$D = \int d^3x \, j_D^0 = Ht - G \qquad \qquad \begin{array}{c} e^{i\kappa D}\phi(x)e^{-i\kappa D} = e^{\kappa d_{\phi}}\phi(e^{\kappa}x) \\ \Leftrightarrow \quad \frac{1}{i}\left[\phi(x), D\right] = (x_{\mu}\partial^{\mu} + d_{\phi})e^{i\kappa D} \\ \end{array}$$

 $\langle H \rangle = \left\langle \frac{\mathrm{d}D}{\mathrm{d}t} \right\rangle$

Temporal

rescaling

$$e^{i\kappa D}\phi(x)e^{-i\kappa D} = e^{\kappa d_{\phi}}\phi(e^{\kappa}x) \qquad \qquad H = \int d^3x T^{00}$$

$$\Rightarrow \quad \frac{1}{i} \left[\phi(x), D\right] = (x_{\mu}\partial^{\mu} + d_{\phi})\phi(x) \qquad \qquad G = \int d^3x T^{0i}x^i$$

$$\frac{\mathrm{d}D}{\mathrm{d}t} = \int \mathrm{d}^3 x \, T^{\mu}_{\ \mu} + \int \mathrm{d}^3 x \, \mathcal{F}^{\mu} x_{\mu}$$

$$\frac{\mathrm{d}G}{\mathrm{d}t} = \sum_{i} \int \mathrm{d}^{3}x \, T^{ii} + \int \mathrm{d}^{3}x \, \vec{\mathcal{F}} \cdot \vec{x}$$

Temporal dilatation breaking

 $=\langle H\rangle - \left\langle \frac{\mathrm{d}G}{\mathrm{d}t} \right\rangle$

Spatial dilatation breaking

No new information from temporal dilatations !

To sum up, the virial theorem

- I. is a statement about mechanical equilibrium of stationary states under dilatations
- 2. provides an equality between average values of different quantities at rest
- 3. does not require isolation of the system

To sum up, the virial theorem

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- 3. does not require isolation of the system

Generalization to arbitrary spatial deformations

[Parker, PR96 (1954) 1686]

$$G^{ij} = \int \mathrm{d}^3 x \, T^{0i} x^j \quad \Longrightarrow \quad \left\langle \int \mathrm{d}^3 x \, T^{ij} \,\right\rangle = -\left\langle \int \mathrm{d}^3 x \, \mathcal{F}^i x^j \,\right\rangle$$

Tensor virial theorem

Not additive and hence not suited for a mass decomposition

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Expectation value

$$M = \frac{\langle p | P^{\mu} P_{\mu} | p \rangle}{\langle p | p \rangle} \frac{1}{M}$$

Not additive and hence not suited for a mass decomposition

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$$M = \frac{\langle p | P^{\mu} P_{\mu} | p \rangle}{\langle p | p \rangle} \; \frac{1}{M}$$

$$= \frac{\langle p|P^{\mu}|p\rangle}{\langle p|p\rangle} \frac{p_{\mu}}{M}$$

CM fourvelocity

Not additive and hence not suited for a mass decomposition

Expectation value

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$$= \frac{\langle p|P^{\mu}|p\rangle}{\langle p|p\rangle} \frac{p_{\mu}}{M}$$

CM fourvelocity

$$=\frac{\langle p_{\rm rest}|H|p_{\rm rest}\rangle}{\langle p_{\rm rest}|p_{\rm rest}\rangle}$$

Proper inertia (i.e. rest-frame energy) of the system

Not additive and hence not suited for a mass decomposition

Expectation value

$$M = \frac{\langle p | P^{\mu} P_{\mu} | p \rangle}{\langle p | p \rangle} \frac{1}{M}$$

Proper inertia (i.e. rest-frame energy) of the system

A mass decomposition is fundamentally an energy decomposition

$$H = \sum_{a} H_{a}$$

$$= \frac{\langle p | P^{\mu} | p \rangle}{\langle p | p \rangle} \frac{p_{\mu}}{M}$$

CM fourvelocity

$$=\frac{\langle p_{\rm rest}|H|p_{\rm rest}\rangle}{\langle p_{\rm rest}|p_{\rm rest}\rangle}$$

Example: Dirac theory with external potential

 $E = \int \mathrm{d}^3 r \,\psi^{\dagger} \vec{\alpha} \cdot \vec{p} \,\psi + m \int \mathrm{d}^3 r \,\psi^{\dagger} \beta \psi + \int \mathrm{d}^3 r \,\psi^{\dagger} \mathcal{V}(\vec{r}) \psi$

Kinetic energy

Rest mass energy

Potential energy

Example: Dirac theory with external potential

$$E = \int \mathrm{d}^3 r \,\psi^{\dagger} \vec{\alpha} \cdot \vec{p} \,\psi + m \int \mathrm{d}^3 r \,\psi^{\dagger} \beta \psi + \int \mathrm{d}^3 r \,\psi^{\dagger} \mathcal{V}(\vec{r}) \psi$$

Kinetic energy

Rest mass energy

Potential energy

 $\int \mathrm{d}^3 r \,\psi^{\dagger} \vec{\alpha} \cdot \vec{p} \,\psi = n \int \mathrm{d}^3 r \,\psi^{\dagger} \mathcal{V}(\vec{r}) \psi$ Virial theorem $\mathcal{V}(\vec{r}) \propto r^n$

Numerical equality between different physical quantities

Example: Dirac theory with external potential

$$E = \int \mathrm{d}^3 r \,\psi^{\dagger} \vec{\alpha} \cdot \vec{p} \,\psi + m \int \mathrm{d}^3 r \,\psi^{\dagger} \beta \psi + \int \mathrm{d}^3 r \,\psi^{\dagger} \mathcal{V}(\vec{r}) \psi$$

Kinetic energy

Rest mass energy

Potential energy

Virial theorem
$$\int d^3r \, \psi^{\dagger} \vec{\alpha} \cdot \vec{p} \, \psi = n \int d^3r \, \psi^{\dagger} \mathcal{V}(\vec{r}) \psi$$
$$\mathcal{V}(\vec{r}) \propto r^n$$

Numerical equality between different physical quantities

$$\implies E = m \int d^3 r \, \psi^{\dagger} \beta \psi + (n+1) \int d^3 r \, \psi^{\dagger} \mathcal{V}(\vec{r}) \psi$$

Rest mass energy

Potential energy

Example: Dirac theory with external potential

$$E = \int \mathrm{d}^3 r \,\psi^{\dagger} \vec{\alpha} \cdot \vec{p} \,\psi + m \int \mathrm{d}^3 r \,\psi^{\dagger} \beta \psi + \int \mathrm{d}^3 r \,\psi^{\dagger} \mathcal{V}(\vec{r}) \psi$$

Kinetic energy

Rest mass energy

Potential energy

Virial theorem $\mathcal{V}(\vec{r}) \propto r^n$

$$\int \mathrm{d}^3 r \, \psi^{\dagger} \vec{\alpha} \cdot \vec{p} \, \psi = n \int \mathrm{d}^3 r \, \psi^{\dagger} \mathcal{V}(\vec{r}) \psi$$

Numerical equality between different physical quantities

$$= \int d^3 r \, \psi^{\dagger} \beta \psi + (n+1) \int d^3 r \, \psi^{\dagger} \mathcal{V}(\vec{r}) \psi$$
Rest mass energy Potential energy

The virial theorem simplifies the calculations BUT spoils the physical picture !

[C.L., EPJC78 (2018) 120] [C.L., Metz, Pasquini, Rodini, JHEP11 (2021) 121]

For an isolated system in a stationary state (at rest)

 $\begin{array}{ll} \text{Definition} \\ \text{of mass} \end{array} \quad \langle H \rangle = M \end{array}$

Virial theorem

$$\langle H \rangle = \left\langle \frac{\mathrm{d}D}{\mathrm{d}t} \right\rangle = \left\langle \int \mathrm{d}^3 x \, T^{\mu}_{\ \mu} \right\rangle$$

[C.L., EPJC78 (2018) 120] [C.L., Metz, Pasquini, Rodini, JHEP11 (2021) 121]

For an isolated system in a stationary state (at rest)

Definition of mass

$$\langle H \rangle = M$$

Virial theorem

$$\langle H \rangle = \left\langle \frac{\mathrm{d}D}{\mathrm{d}t} \right\rangle = \left\langle \int \mathrm{d}^3 x \, T^{\mu}_{\ \mu} \right\rangle$$

$$\implies \langle \int \mathrm{d}^3 x \, T^{\mu}_{\ \mu} \rangle = M$$

Starting point of trace decomposition

Consequences of the virial theorem

[C.L., EPJC78 (2018) 120] [C.L., Metz, Pasquini, Rodini, JHEP11 (2021) 121]

For an isolated system in a stationary state (at rest)

 $\begin{array}{ll} \mbox{Definition} & \langle H \rangle = M \\ \mbox{Virial} & \langle H \rangle = \left\langle \frac{\mathrm{d}D}{\mathrm{d}t} \right\rangle = \langle \int \mathrm{d}^3 x \, T^{\mu}_{\ \mu} \rangle \\ \mbox{theorem} & \left\langle H \right\rangle = \left\langle \frac{\mathrm{d}D}{\mathrm{d}t} \right\rangle = \langle \int \mathrm{d}^3 x \, T^{\mu}_{\ \mu} \rangle \end{array} \end{array}$

Decomposition into irreducible representations of Poincaré group

$$T^{\mu\nu} = (T^{\mu\nu} - \frac{1}{4} g^{\mu\nu} T^{\alpha}_{\ \alpha}) + \frac{1}{4} g^{\mu\nu} T^{\alpha}_{\ \alpha}$$

Consequences of the virial theorem

[C.L., EPJC78 (2018) 120] [C.L., Metz, Pasquini, Rodini, JHEP11 (2021) 121]

For an isolated system in a stationary state (at rest)

$$\begin{array}{ll} \mbox{Definition} & \langle H \rangle = M \\ \mbox{Virial} & \langle H \rangle = \left\langle \frac{\mathrm{d}D}{\mathrm{d}t} \right\rangle = \langle \int \mathrm{d}^3 x \, T^{\mu}_{\ \mu} \rangle \\ \mbox{theorem} & \langle H \rangle = \left\langle \frac{\mathrm{d}D}{\mathrm{d}t} \right\rangle = \langle \int \mathrm{d}^3 x \, T^{\mu}_{\ \mu} \rangle \end{array} \end{array}$$

Decomposition into irreducible representations of Poincaré group

[C.L., EPJC78 (2018) 120] [C.L., Metz, Pasquini, Rodini, JHEP11 (2021) 121]

 $P^{\mu} = \int d^3x \, T^{0\mu}(x)$

For an isolated system in a stationary state (at rest)

$$\begin{array}{ll} \text{Definition} & \langle H \rangle = M \\ \text{of mass} & \langle H \rangle = M \\ \text{Virial} & \langle H \rangle = \left\langle \frac{\mathrm{d}D}{\mathrm{d}t} \right\rangle = \left\langle \int \mathrm{d}^3 x \, T^{\mu}_{\ \mu} \right\rangle \\ \text{theorem} & \left\langle H \right\rangle = \left\langle \frac{\mathrm{d}D}{\mathrm{d}t} \right\rangle = \left\langle \int \mathrm{d}^3 x \, T^{\mu}_{\ \mu} \right\rangle \\ \end{array}$$

Decomposition into irreducible representations of Poincaré group

The virial theorem introduces the stress tensor T^{ij} in the mass decomposition even though it has nothing to do with the notion of mass

$$M = \underbrace{\langle \int \mathrm{d}^3 x \, \overline{\psi} m \psi \rangle}_{\sigma_q} + \underbrace{\langle \int \mathrm{d}^3 x \, (\frac{\beta(g)}{2g} \, G^2 + \gamma_m \overline{\psi} m \psi) \rangle}_{M - \sigma_q}$$

[Shifman, Vainshtein, Zakharov, PL78B (1978) 443] [Donoghue, Golowich, Holstein, *Dynamics of the Standard Model* (1992)] [Kharzeev, PISPF130 (1996) 105]

Requires 1 independent input

$$M = \underbrace{\langle \int \mathrm{d}^3 x \, \overline{\psi} m \psi \rangle}_{\sigma_q} + \underbrace{\langle \int \mathrm{d}^3 x \, (\frac{\beta(g)}{2g} \, G^2 + \gamma_m \overline{\psi} m \psi) \rangle}_{M - \sigma_q}$$

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Requires 1 independent input

Energy decomposition

[C.L., EPJC78 (2018) 120] [Metz, Pasquini, Rodini, PRD102 (2020) 114042]

$$M = \underbrace{\langle \int \mathrm{d}^3 x \left(T_q^{00} - \overline{\psi} m \psi \right) \rangle}_{\left[A_q(0) + \overline{C}_q(0)\right] M - \sigma_q} + \underbrace{\langle \int \mathrm{d}^3 x \, \overline{\psi} m \psi \rangle}_{\sigma_q} + \underbrace{\langle \int \mathrm{d}^3 x \, T_g^{00} \rangle}_{\left[A_g(0) + \overline{C}_g(0)\right] M}$$

Requires 2 independent inputs

 $A_q(0) + A_g(0) = 1$ $\bar{C}_q(0) + \bar{C}_g(0) = 0$

$$A_q(0) = \langle x \rangle_q$$
$$A_q(0) + 4\bar{C}_q(0) = c_1 + c_2 \frac{\sigma_q}{M}$$

Scheme and scale-dependent !

$$M = \underbrace{\langle \int d^3 x \,\overline{\psi} m \psi \rangle}_{\sigma_q} + \underbrace{\langle \int d^3 x \left(\frac{\beta(g)}{2g} \, G^2 + \gamma_m \overline{\psi} m \psi \right) \rangle}_{M - \sigma_q}$$

[Shifman, Vainshtein, Zakharov, PL78B (1978) 443] [Donoghue, Golowich, Holstein, Dynamics of the Standard Model (1992)] [Kharzeev, PISPF130 (1996) 105]

Requires 1 independent input

Energy decomposition

Ji's decomposition

[C.L., EPJC78 (2018) 120] [Metz, Pasquini, Rodini, PRD102 (2020) 114042]

$$M = \underbrace{\langle \int d^3x \left(T_q^{00} - \overline{\psi} m \psi \right) \rangle}_{\left[A_q(0) + \overline{C}_q(0)\right] M - \sigma_q} + \underbrace{\langle \int d^3x \, \overline{\psi} m \psi \rangle}_{\sigma_q} + \underbrace{\langle \int d^3x \, T_g^{00} \rangle}_{\left[A_g(0) + \overline{C}_g(0)\right] M}$$

Requires 2 independent inputs

$$A_q(0) + A_g(0) = 1$$

 $\bar{C}_q(0) + \bar{C}_g(0) = 0$

$$A_q(0) = \langle x \rangle_q$$
$$A_q(0) + 4\bar{C}_q(0) = c_1 + c_2 \frac{\sigma_q}{M}$$

Scheme and scale-dependent !

[Ji, PRL74 (1995) 1071] [Ji, PRD52 (1995) 271]

$$M = \underbrace{\langle \int \mathrm{d}^3 x \, (\bar{T}_q^{00} - \frac{3}{4} \, \overline{\psi} m \psi) \rangle}_{\frac{3}{4} [A_q(0) \, M - \sigma_q]} + \underbrace{\langle \int \mathrm{d}^3 x \, \overline{\psi} m \psi \rangle}_{\sigma_q} + \underbrace{\langle \int \mathrm{d}^3 x \, \overline{T}_g^{00} \rangle}_{\frac{3}{4} A_g(0) \, M} + \underbrace{\langle \int \mathrm{d}^3 x \, \frac{1}{4} (\frac{\beta(g)}{2g} \, G^2 + \gamma_m \overline{\psi} m \psi) \rangle}_{\frac{1}{4} (M - \sigma_q)}$$
Requires 2 independent inputs
$$\bar{T}^{\mu\nu} = T^{\mu\nu} - \frac{1}{4} \, g^{\mu\nu} T^{\alpha}_{\sigma}$$

Requires 2 independent inputs

Mass decompositions (in D2 scheme)

virial theorem

• What is the virial theorem ?

$$\succ \quad \langle \sum_{i} \int \mathrm{d}^{3}x \, T^{ii} \, \rangle = - \langle \int \mathrm{d}^{3}x \, \vec{\mathcal{F}} \cdot \vec{x} \, \rangle$$

- What is its physical meaning?
 - > Statement about mechanical equilibrium under spatial dilatations
- What is its relation to mass?
 - It has nothing to do with mass (i.e. rest-frame energy) but it can be used to create « new » sum rules

Mass (energy) decomposition

$$M = \langle \int \mathrm{d}^3 x \, T^{00} \rangle = \sum_a \langle \int \mathrm{d}^3 x \, T^{00}_a \rangle$$

Virial theorem

$$0 = \langle \sum_{i} \int \mathrm{d}^{3}x \, T^{ii} \rangle = \sum_{a} \langle \sum_{i} \int \mathrm{d}^{3}x \, T^{ii}_{a} \rangle$$

$$M = \sum_{a} \langle \int d^{3}x \left[\alpha T_{a}^{00} + \beta \sum_{i} T_{a}^{ii} \right] \rangle$$
$$+ \sum_{a} \langle \int d^{3}x \left[(1 - \alpha) T_{a}^{00} + \gamma \sum_{i} T_{a}^{ii} \right] \rangle$$
$$Trace decomposition \qquad \alpha = 1, \quad \beta = -1, \quad \gamma = 0$$

Ji's decomposition $\alpha = \frac{3}{4}, \quad \beta = \frac{1}{4}, \quad \gamma = -\frac{1}{4}$

Backup slides

M The definition of the EMT is not unique

Canonical EMT (Noether's theorem)

$$T_{\rm can}^{\mu\nu} = \sum_{a} \frac{\partial \mathcal{L}}{\partial(\partial_{\mu}\phi_{a})} \,\partial^{\nu}\phi_{a} - g^{\mu\nu}\mathcal{L}$$

 $-G^{\mu\alpha\nu}$

Usually neither symmetric (for fields with non-zero spin) nor gauge invariant (when field gradients do not transform covariantly under gauge transformations)

However, P^{μ} is unique and gauge invariant !

« Improved » EMT (relocalization of energy and momentum)

$$T^{\mu\nu}_{\rm new} = T^{\mu\nu}_{\rm can} + \partial_{\alpha} G^{\alpha\mu\nu} \qquad G^{\alpha\mu\nu} =$$

$$\implies P^{\mu} = \int \mathrm{d}^3 x \, T_{\mathrm{new}}^{0\mu} = \int \mathrm{d}^3 x \, T_{\mathrm{can}}^{0\mu}$$

circulation

Intrinsic

Gauge invariance is a necessity

Symmetry under exchange of indices is only motivated by GR ...

<u>NB:</u> In GR one assumes the symmetry of the metric **or** the absence of torsion **or** the purely orbital form of AM

Kinetic EMT (most natural one in QFT)

$$J^{\mu\alpha\beta} = x^{\alpha}T^{\mu\beta} - x^{\beta}T^{\mu\alpha} + S^{\mu\alpha\beta}$$

$$\partial_{\mu}T^{\mu\nu} = 0$$

$$T^{\alpha\beta} - T^{\beta\alpha} = -\partial_{\mu}S^{\mu\alpha\beta}$$
Orbital
Intrinsic

Four-momentum conservation

Expectation value

$$\langle P_a^{\mu} \rangle = \frac{\langle p | P_a^{\mu} | p \rangle}{\langle p | p \rangle} = \underbrace{\frac{\int \mathrm{d}^3 r}{(2\pi)^3 \delta^{(3)}(\mathbf{0})}}_{= 1} \frac{\langle p | T_a^{0\mu}(\mathbf{0}) | p \rangle}{2p^0}$$

$$\langle p|T_a^{\mu\nu}(0)|p\rangle = 2p^{\mu}p^{\nu}A_a(0) + 2M^2g^{\mu\nu}\bar{C}_a(0)$$

$$\begin{array}{c} & & & & \\ & & & \\ & & \\ \hline \end{array} \begin{pmatrix} P_a^{\mu} \rangle = p^{\mu} A_a(0) + \frac{M^2}{p^0} \, g^{0\mu} \bar{C}_a(0) & & \\ & & \\ & & \\ & & \\ & & \\ \hline \end{array} \\ \begin{array}{c} \text{Not a four-vector !} \\ \text{(unless state is massless)} \\ & & \\ & & \\ \hline \end{array} \\ \begin{array}{c} \text{Light-front} \\ \text{version} \\ & & \\ & & \\ & & \\ p^{\pm} = (p^0 \pm p^3)/\sqrt{2} \end{array} \\ \begin{array}{c} \text{Not a four-vector !} \\ & & \\$$

Deep-inelastic scattering

Four-momentum sum rules

$$p^{\mu} = \sum_{a} \langle P_{a}^{\mu} \rangle \quad \Rightarrow \quad \begin{bmatrix} \sum_{a} A_{a}(0) = 1 \\ \sum_{a} \bar{C}_{a}(0) = 0 \end{bmatrix}$$

Why two sum rules ? What is the meaning of $\bar{C}_a(0)$?

Physical interpretation is simpler in target rest frame

$$\frac{\langle p_{\text{rest}} | \int d^3 x \, T_a^{\mu\nu}(x) | p_{\text{rest}} \rangle}{\langle p_{\text{rest}} | p_{\text{rest}} \rangle} = M \begin{pmatrix} A_a(0) + C_a(0) & 0 & 0 & 0 \\ 0 & -\bar{C}_a(0) & 0 & 0 \\ 0 & 0 & 0 & -\bar{C}_a(0) & 0 \\ 0 & 0 & 0 & -\bar{C}_a(0) \end{pmatrix}$$
$$\Leftrightarrow \quad \begin{pmatrix} \varepsilon_a & 0 & 0 & 0 \\ 0 & p_a & 0 & 0 \\ 0 & 0 & p_a & 0 \\ 0 & 0 & 0 & p_a \end{pmatrix} V$$

 \rightarrow $-\bar{C}_a(0)$ measures the average stress (or pressure) exerted by subsystem a

Mechanical equilibrium implies

$$\sum_{a} p_a = 0 \quad \Rightarrow \quad \sum_{a} \bar{C}_a(0) = 0$$

[Shifman, Vainshtein, Zakharov, PL78B (1978) 443] [Donoghue, Golowich, Holstein, *Dynamics of the Standard Model* (1992)] [Kharzeev, PISPF130 (1996) 105]

Poincaré symmetry tells us that

Trace decomposition

$$\langle p|T^{\mu\nu}(0)|p\rangle = 2p^{\mu}p^{\nu}$$
 $\langle p'|p\rangle = 2p^{0}(2\pi)^{3}\delta^{(3)}(\vec{p}'-\vec{p})$

Quark mass and quantum corrections break conformal symmetry

The physical interpretation of the « quark » and « gluon » contributions is however not so clear ...

It is clearer to work in the rest frame

$$\begin{split} & \left\langle \int \mathrm{d}^3 x \, T^{\mu}_{\ \mu} \right\rangle = \left\langle \int \mathrm{d}^3 x \, T^{00} \right\rangle - \sum_i \left\langle \int \mathrm{d}^3 x \, T^{ii} \right\rangle \\ &= M &= 0 \\ & \mathbf{M} &= 0 \\ & \mathbf$$

The « gluon » contribution is enhanced because the gluon pressure-volume work is negative (attractive forces)

[C.L., EPJC78 (2018) 120] [Metz, Pasquini, Rodini, PRD102 (2020) 114042] [C.L., Metz, Pasquini, Rodini, JHEP11 (2021) 121]

Energy decomposition

Renormalized QCD operators

$$T^{\mu\nu} = T^{\mu\nu}_q + T^{\mu\nu}_g$$

$$\begin{split} T^{\mu\nu}_{q} &= \overline{\psi} \gamma^{\mu} \frac{i}{2} \overset{\leftrightarrow}{D}^{\nu} \psi \\ T^{\mu\nu}_{g} &= -G^{\mu\lambda} G^{\nu}{}_{\lambda} + \frac{1}{4} \, g^{\mu\nu} \, G^{2} \end{split}$$

Rest-frame energy

$$M = \langle H_q \rangle + \langle H_g \rangle$$

= $\langle \int d^3 x \, \overline{\psi} \gamma^0 i D^0 \psi \rangle + \langle \int d^3 x \, \frac{1}{2} (\vec{E}^2 + \vec{B}^2) \rangle$
[$A_q(0) + \bar{C}_q(0)$] M [$A_g(0) + \bar{C}_g(0)$] M

$$A_a(0) = \langle x \rangle_a$$

$$\bar{C}_a(0) = f_a(\langle x \rangle_q, \langle \overline{\psi} m \psi \rangle)$$

Refinement

$$M = \langle \int d^3x \,\overline{\psi} \vec{\gamma} \cdot i \vec{D} \psi \rangle + \langle \int d^3x \,\overline{\psi} m \psi \rangle + \langle \int d^3x \,\frac{1}{2} (\vec{E}^2 + \vec{B}^2) \rangle$$

$$\sim 21\% \,(\overline{\text{MS}}) \qquad \sim 8\% \,(\overline{\text{MS}}) \qquad \sim 71\% \,(\overline{\text{MS}}) \qquad \mu = 2 \,\text{GeV}$$

$$\sim 38\% \,(\text{D2}) \qquad \sim 8\% \,(\text{D2}) \qquad \qquad \nu = 2 \,\text{GeV}$$

[Ji, PRL74 (1995)] [Ji, PRD52 (1995)]

Ji's decomposition

It combines features from both trace and energy decompositions

Step I
$$T^{\mu\nu} = \bar{T}^{\mu\nu} + \hat{T}^{\mu\nu}$$
 $\bar{T}^{\mu\nu} = T^{\mu\nu} - \frac{1}{4} g^{\mu\nu} T^{\alpha}_{\ \alpha}$ Twist-2
 $\hat{T}^{\mu\nu} = \frac{1}{4} g^{\mu\nu} T^{\alpha}_{\ \alpha}$ Twist-4

Poincaré symmetry ensures that this separation is scheme and scale-independent !

Step 2

$$\begin{split} \bar{T}^{\mu\nu} &= \bar{T}^{\mu\nu}_{q} + \bar{T}^{\mu\nu}_{g} \\ \hat{T}^{\mu\nu} &= \hat{T}^{\mu\nu}_{m} + \hat{T}^{\mu\nu}_{a} \\ \hat{T}^{\mu\nu}_{a} &= \frac{1}{4} g^{\mu\nu} \overline{\psi} m \psi \\ \hat{T}^{\mu\nu}_{a} &= \frac{1}{4} g^{\mu\nu} \left[\frac{\beta(g)}{2g} G^{2} + \gamma_{m} \overline{\psi} m \psi \right] \end{split}$$

Rest-frame energy

Ji's decomposition

The physical interpretation of the « quark » and « gluon » contributions is however not so clear ...

$$T_{a}^{00} = \frac{\bar{T}_{a}^{00}}{= \frac{3}{4}T_{a}^{00} + \frac{1}{4}\sum_{i}T_{a}^{ii}} + \frac{\hat{T}_{a}^{00}}{= \frac{1}{4}T_{a}^{00} - \frac{1}{4}\sum_{i}T_{a}^{ii}} a = q, g$$

$$\sum_{i} \langle \int d^{3}x T_{a}^{ii} \rangle \neq 0$$
Partial pressure-
volume work

Also, it is tempting to write

$$\bar{T}_q^{00} - \frac{3}{4} \,\overline{\psi} m \psi \stackrel{?}{=} \overline{\psi} \vec{\gamma} \cdot i \vec{D} \psi$$
$$\bar{T}_g^{00} \stackrel{?}{=} \frac{1}{2} (\vec{E}^2 + \vec{B}^2)$$

... but there is no scheme where both are simultaneously justified !